Computational Logic 320441 CompLog Lecture Notes

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Preface

Introduction

The ability to *represent knowledge about the world* and to *draw logical inferences* is one of the central components of intelligent behavior. As a consequence, reasoning components of some form are at the heart of many artificial intelligence systems.

Logic: The field of *logic* studies representation and inference systems. It dates back and has its roots in Greek philosophy as presented in the works of Aristotle and others. Since then logic has grown in richness and diversity over the centuries to finally reach the modern methodological approach first expressed in the work of Frege. Logical calculi, which capture an important aspect of human thought, were now amenable to investigation with mathematical rigour and the beginning of this century saw the influence of these developments in the foundations of mathematics, in the work of Hilbert, Russell and Whitehead, in the foundations of syntax and semantics of language, and in philosophical foundations expressed most vividly by the logicians in the Vienna Circle.

Computational Logic: The field of *Computational Logic* looks at computational aspects of logic. It is essentially the computer-science perspective of logic. The idea is that logical statements can be executed on a machine. This has far-reaching consequences that ultimately lead to logic programming, deduction systems for mathematics and engineering, logical design and verification of computer software and hardware, deductive databases and software synthesis as well as logical techniques for analysis in the field of mechanical engineering.

Logic Engineering: As all of these applications require efficient implementations of the underlying inference systems, computational logic focuses on *proof theory* much more than on *model theory* (which is the focus of mathematical logic, a neighboring field). As the respective applications have different requirements on the expressivity and structure of the representation language and on the statements derived or the terms simplified, computational logic focuses on "logic engineering", i.e. the development of representation languages, inference systems, and module systems with specific properties.

Course Concept

Aims: The course 320441 "Computational Logic" (CompLog) is a specialization course offered to third-year undergraduate students and to first-year graduate students at Jacobs University Bremen. The course aims to give these students a solid (and somewhat theoretically oriented) foundation of computational logic and logic engineering techniques.

Prerequisites: The course makes very little assumptions about prior knowledge, but the learning curve is very steep for students who have no prior exposure to logic. As a consequence, the course has a prerequisite to the course 320211 *Formal Languages and Logic* which is a mandatory course in the Computer Science program at Jacobs University. This prerequisite can be waived by the instructor for other students.

Course Contents: We carefully recap the foundations of first-order logic and present the tableau calculus as a computationally inspired inference procedure. Free variable tableaux also introduce unification, and important computational tool in logics. Finally, we introduce the model existence method for proving completeness of calculi.

The next part of the course is about enhancing the expressivity of first-order logic to include functions, predicates, and sets. The intended application is a more adequate representation of mathematical concepts, where these objects are common. Here we introduce the simply typed λ calculus as the main representational vehicle, since it casts function comprehension into an equational theory which we show to be terminating, confluent, and complete. Thus we can build higher-order inference by extending unification and tableaux.

Finally, we explore the realm of decidable logics used for knowledge representation these days. These description logics specialize on representing concepts, and their relations and reasoning about them. Here the game is to add new operators to the language and extend the reasoning algorithms for them without losing decidability and tractability. We present the foundations of knowledge representation starting from semantic networks, over propositional logic with a setdescription semantics to ALC, which achieves feature-parity with semantic networks, but has a strong formal basis and well-understood, decision procedures. We conclude the course with a quick walk through the ALC extensions and relate this to the current Semantic Web standards.

This Document

This document contains the course notes for the course Computational Logic held at Jacobs University Bremen in the fall semesters 2004/07/09/11/13/14.

Contents: The document mixes the slides presented in class with comments of the instructor to give students a more complete background reference.

Caveat: This document is made available for the students of this course only. It is still an early draft, and will develop over the course of the course. It will be developed further in coming academic years.

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Knowledge Representation Experiment:

This document is also an experiment in knowledge representation. Under the hood, it uses the ST_EX package [Koh08, Koh15], a T_EX/IAT_EX extension for semantic markup, which allows to export the contents into the eLearning platform PantaRhei.

Comments and extensions are always welcome, please send them to the author.

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Acknowledgments

CompLog Students: The following students have submitted corrections and suggestions to this and earlier versions of the notes: Rares Ambrus, Florian Rabe, Deyan Ginev, Fulya Horozal.

Recorded Syllabus for Fall 2015

In this document, we record the progress of the course in Fall 2015 in the form of a "recorded syllabus", i.e. a syllabus that is created after the fact rather than before.

Recorded Syllabus Fall Semester 2014:

#	date	until	slide	page
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Here the syllabus of last year's course for reference, the one should be similar.

Recorded	Syllabus	Fall Semester	2013:
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#	date	until	
1	Sep 3.	admin/intro/history	
2	Sep 8.	more overview	
3	Sep 15.	First-Order Semantics	
4	Sep 17.	Capture-Avoiding substitution	
5	Sep 22.	First-Order ND Calculus	
7	Sep 29.	Model Existence	
8	Oct 1.	efficient unification	
9	Oct 6.	tableau soundness/completeness	
10	Oct 8.	Higher-Order predicate Logic	
11	Oct 13.	λ -calculus & Head Reduction	
12	Oct 15.	Termination of β -reduction	
13	Oct 22.	$\alpha\beta\eta$ -completeness, Simple Type Theory	
14	Oct 27	Logical Constants for Math	
15	Oct. 29	HOU & General Bindings	
16	Nov 3.	HOU completeness	
17	Nov 5.	Andrews' equality-based HOL	
18	Nov 10.	Higher-Order Tableaux	
19	Nov 12.	Recap FO Tableaux and Course Planning	
20	Nov 17.	Semantic Networks/Semantic Web	
20	Nov 19.	PL0 set description	
21	Nov 24.	ALC intro	
22	Nov 26.	ALC Inference	
23	Dec 1.	Semantic Web & number restrictions	
24	Dec 3.	More ALC extensions: Role Operations	

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Outline of the Course

In this course, we want to achieve three things: we want to

- 1) expose you to various logics from a computational perspective, in particular
- 2) teach you how to build up logics and and express domain theories modularly, and
- 3) apply that to the foundations of mathematics and of the Semantic Web.



320411/CompLog Administrativa

We will now go through the ground rules for the course. This is a kind of a social contract between the instructor and the students. Both have to keep their side of the deal to make learning as efficient and painless as possible.

Even though the lecture itself will be the main source of information in the course, there are various resources from which to study the material.



No Textbook: There is no single textbook that covers the course. Instead we have a comprehensive set of course notes (this document). They are provided in two forms: as a large PDF that is posted at the course web page and on the PantaRhei system. The latter is actually the preferred method of interaction with the course materials, since it allows to discuss the material in place, to play with notations, to give feedback, etc. The PDF file is for printing and as a fallback, if the PantaRhei system, which is still under development, develops problems.

But of course, there is a wealth of literature on the subject of computational logic, and the references at the end of the lecture notes can serve as a starting point for further reading. We will try to point out the relevant literature throughout the notes.

Now we come to a topic that is always interesting to the students: the grading scheme.

Prerequisites, Requirements, Grades

▷ Prerequisites: Mot	ivation, Interest, Curiosity, hard	work	(mainly,))	
 exposure to discrete Math, possibly category theory experience in (some) logics 					
You can do this cou	urse if you want! (even wi	thout th	nose, but they help))	
\triangleright Grades:	(plan your y	work inv	volvement carefully))	
In particular, no mic	Attendance and Wakefulness Homework Assignments Quizzes No Midterm Exam No Final Exam	10% 60% 30% - -	dance is mandatory (excuses possible)	!)	
\triangleright Note that for the grades, the percentages of achieved points are added with the weights above, and only then the resulting percentage is converted to a grade.					
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Our main motivation in this grading scheme is to entice you to study continuously. This means that you will have to stay involved, do all your homework assignments, and keep abreast with the course. This also means that your continued involvement may be higher than other (graduate) courses, but you are free to concentrate on these during exam week.



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Homework assignments are a central part of the course, they allow you to review the concepts covered in class, and practice using them. They are usually directly based on concepts covered in the lecture, so reviewing the course notes often helps getting started.

Homework Submissions, Grading, Tutorials
▷ Submissions: We use Heinrich Stamerjohanns' JGrader system
▷ submit all homework assignments electronically to https://jgrader.de.
▷ you can login with your Jacobs account and password. (should have one!)
▷ feedback/grades to your submissions
▷ get an overview over how you are doing! (do not leave to midterm)
▷ Tutorials: select a tutorial group and actually go to it regularly
▷ to discuss the course topics after class (lectures need pre/postparation)
▷ to discuss your homework after submission (to see what was the problem)
▷ to find a study group (probably the most determining factor of success)

The next topic is very important, you should take this very seriously, even if you think that this is just a self-serving regulation made by the faculty.

All societies have their rules, written and unwritten ones, which serve as a social contract among its members, protect their interestes, and optimize the functioning of the society as a whole. This is also true for the community of scientists worldwide. This society is special, since it balances intense cooperation on joint issues with fierce competition. Most of the rules are largely unwritten; you are expected to follow them anyway. The code of academic integrity at Jacobs is an attempt to put some of the aspects into writing.

It is an essential part of your academic education that you learn to behave like academics, i.e. to function as a member of the academic community. Even if you do not want to become a scientist in the end, you should be aware that many of the people you are dealing with have gone through an academic education and expect that you (as a graduate of Jacobs) will behave by these rules.

The Code of Academic Integrity	
▷ Jacobs has a "Code of Academic Integrity"	
▷ this is a document passed by the Jacobs community university)	(our law of the
▷ you have signed it during enrollment (we	e take this seriously)
It mandates good behaviors from both faculty and student ones:	<mark>ts</mark> and penalizes bad
▷ honest academic behavior (we	don't cheat/falsify)
 respect and protect the intellectual property of others treat all Jacobs members equally 	(no plagiarism) (no favoritism)



To understand the rules of academic societies it is central to realize that these communities are driven by economic considerations of their members. However, in academic societies, the primary good that is produced and consumed consists in ideas and knowledge, and the primary currency involved is academic reputation¹. Even though academic societies may seem as altruistic — scientists share their knowledge freely, even investing time to help their peers understand the concepts more deeply — it is useful to realize that this behavior is just one half of an economic transaction. By publishing their ideas and results, scientists sell their goods for reputation. Of course, this can only work if ideas and facts are attributed to their original creators (who gain reputation by being cited). You will see that scientists can become quite fierce and downright nasty when confronted with behavior that does not respect other's intellectual property.

Next we come to a special project that is going on in parallel to teaching the course. I am using the course materials as a research object as well. This gives you an additional resource, but may affect the shape of the course materials (which now server double purpose). Of course I can use all the help on the research project I can get, so please give me feedback, report errors and shortcomings, and suggest improvements.



¹Of course, this is a very simplistic attempt to explain academic societies, and there are many other factors at work there. For instance, it is possible to convert reputation into money: if you are a famous scientist, you may get a well-paying job at a good university,...

⊳ yo	u will help build better course materials	think of next-year's	students)
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What is (Computational) Logic

What is (Computational) Logic?			
The field of logic studies representation languages, inference systems, and their relation to the world.			
\triangleright It dates back and has its roots in Greek philosophy (Aristotle et al.)			
Logical calculi capture an important aspect of human thought, and make it amenable to investigation with mathematical rigour, e.g. in			
▷ foundation of mathematics (Hilbert, Russell and Whitehead)			
\triangleright foundations of syntax and semantics of language(Creswell, Montague,)			
ho Logics have many practical applications			
▷ logic/declarative programming (the third programming paradigm)			
▷ program verification: specify conditions in logic, prove program correctness			
program synthesis: prove existence of answers constructively, extract pro- gram from proof			
proof-carrying code: compiler proves safety conditions, user verifies before running.			
▷ deductive databases: facts + rules (get more out than you put in)			
▷ semantic web: the Web as a deductive database			
Computational Logic is the study of logic from a computational, proof-theoretic perspective. (model theory is mostly comprised under "mathematical logic".)			
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What is Logic?

 \vartriangleright formal languages, inference and their relation with the world

- \triangleright Formal language \mathcal{FL} : set of formulae
- ▷ Formula: sequence/tree of symbols (



So logic is the study of formal representations of objects in the real world, and the formal statements that are true about them. The insistence on a *formal language* for representation is actually something that simplifies life for us. Formal languages are something that is actually easier to understand than e.g. natural languages. For instance it is usually decidable, whether a string is a member of a formal language. For natural language this is much more difficult: there is still no program that can reliably say whether a sentence is a grammatical sentence of the English language.

We have already discussed the meaning mappings (under the monicker "semantics"). Meaning mappings can be used in two ways, they can be used to understand a formal language, when we use a mapping into "something we already understand", or they are the mapping that legitimize a representation in a formal language. We understand a formula (a member of a formal language) **A** to be a representation of an object \mathcal{O} , iff $[\mathbf{A}] = \mathcal{O}$.

However, the game of representation only becomes really interesting, if we can do something with the representations. For this, we give ourselves a set of syntactic rules of how to manipulate the formulae to reach new representations or facts about the world.

Consider, for instance, the case of calculating with numbers, a task that has changed from a difficult job for highly paid specialists in Roman times to a task that is now feasible for young children. What is the cause of this dramatic change? Of course the formalized reasoning procedures for arithmetic that we use nowadays. These *calculi* consist of a set of rules that can be followed purely syntactically, but nevertheless manipulate arithmetic expressions in a correct and fruitful way. An essential prerequisite for syntactic manipulation is that the objects are given in a formal language suitable for the problem. For example, the introduction of the decimal system has been instrumental to the simplification of arithmetic mentioned above. When the arithmetical calculi were sufficiently well-understood and in principle a mechanical procedure, and when the art of clock-making was mature enough to design and build mechanical devices of an appropriate kind, the invention of calculating machines for arithmetic by Wilhelm Schickard (1623), Blaise Pascal (1642), and Gottfried Wilhelm Leibniz (1671) was only a natural consequence.

We will see that it is not only possible to calculate with numbers, but also with representations of statements about the world (propositions). For this, we will use an extremely simple example; a fragment of propositional logic (we restrict ourselves to only one logical connective) and a small calculus that gives us a set of rules how to manipulate formulae.

3.1 A History of Ideas in Logic

Before starting with the discussion on particular logics and inference systems, we put things into perspective by previewing ideas in logic from a historical perspective. Even though the presentation (in particular syntax and semantics) may have changed over time, the underlying ideas are still pertinent in today's formal systems.

Many of the source texts of the ideas summarized in this Section can be found in [vH67].

History of Ideas (abbreviated): Propositional Logic				
⊳ General Logi	c	([ancient Greece, e.g. Aristotle])		
+ conceptual separation of syntax and semantics				
+ system o	f inference rules	("Syllogisms"	")	
– no formal language, no formal semantics				
$ ho$ Propositional Logic [Boole ~ 1850]				
+ functiona	I structure of formal language	(propositions + connective	s)	
+ mathema	+ mathematical semantics (~→ Boolean Algebra)			
- abstraction from internal structure of propositions				
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+ set-theoretic semantics		([Tarski 1936])	
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History of L	door (continued): Equadot	ions of Mathe	matica

History of Ideas	(continued): Foundation	ons of Mathematics	
⊳ Hilbert's Prograr	n: find logical system and calculu	us, ([Hilbert ~ 1930])	
▷ that formalize▷ that admits s▷ whose consist	es all of mathematics ound and complete calculi ence is provable in the system its	self	
\triangleright Hilbert's Program	n is impossible! system that formalizes arithmetics	([Gödel 1931])	
▷ then \mathcal{L} is incomplete ▷ then the consistence of \mathcal{L} cannot be proven in \mathcal{L} .			
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History of Ideas (continued): λ -calculus, set theory			
$ ho$ Simply typed λ -calculus	([Church 1940])		
+ simplifies Russel's types, λ -op	erator for functions		
+ comprehension as eta -equality	(can be mechanized)		
+ simple type-driven semantics	(standard semantics $ ightarrow$ incompleteness)		
\triangleright Axiomatic set theory			
+- type-less representation	(all objects are sets)	(all objects are sets)	
+ first-order logic with axioms			
+ restricted set comprehension	(no set of sets)	(no set of sets)	
– functions and relations are der	ived objects		
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Part I

Formal Systems

To prepare the ground for the particular developments coming up, let us spend some time on recapitulating the basic concerns of formal systems.

Logical Systems

The notion of a logical system is at the basis of the field of logic. In its most abstract form, a logical system consists of a formal language, a class of models, and a satisfaction relation between models and expressions of the formal lanugage. The satisfaction relation tells us when an expression is deemed true in this model.

Logical Systems

- \triangleright Definition 4.0.1 A logical system is a triple $\mathcal{S} := \langle \mathcal{L}, \mathcal{K}, \models \rangle$, where \mathcal{L} is a formal language, \mathcal{K} is a set and $\models \subseteq \mathcal{K} \times \mathcal{L}$. Members of \mathcal{L} are called formulae of S, members of \mathcal{K} models for S, and \models the satisfaction relation.
- \triangleright **Definition 4.0.2** Let $S := \langle \mathcal{L}, \mathcal{K}, \models \rangle$ be a logical system, $\mathcal{M} \in \mathcal{K}$ be a model and $\mathbf{A} \in \mathcal{L}$ a formula, then we call \mathbf{A}
 - \triangleright satisfied by \mathcal{M} , iff $\mathcal{M} \models \mathbf{A}$
 - \triangleright falsified by \mathcal{M} , iff $\mathcal{M} \not\models \mathbf{A}$
 - \triangleright satisfiable in \mathcal{K} , iff $\mathcal{M} \models \mathbf{A}$ for some model $\mathcal{M} \in \mathcal{K}$.
 - \triangleright valid in \mathcal{K} (write $\models \mathcal{M}$), iff $\mathcal{M} \models \mathbf{A}$ for all models $\mathcal{M} \in \mathcal{K}$
 - ▷ falsifiable in \mathcal{K} , iff $\mathcal{M} \not\models \mathbf{A}$ for some $\mathcal{M} \in \mathcal{K}$.
 - \triangleright unsatisfiable in \mathcal{K} , iff $\mathcal{M} \not\models \mathbf{A}$ for all $\mathcal{M} \in \mathcal{K}$.
- \triangleright **Definition 4.0.3** Let $S := \langle \mathcal{L}, \mathcal{K}, \models \rangle$ be a logical system, then we define the entailment relation $\models \subseteq \mathcal{L} \times \mathcal{L}$. We say that A entails B (written A \models B), iff we have $\mathcal{M} \models \mathbf{B}$ for all models $\mathcal{M} \in \mathcal{K}$ with $\mathcal{M} \models \mathbf{A}$.

 \triangleright Observation 4.0.4 $\mathbf{A} \models \mathbf{B}$ and $\mathcal{M} \models \mathbf{A}$ imply $\mathcal{M} \models \mathbf{B}$.

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Example 4.0.5 (First-Order Logic as a Logical System) Let $\mathcal{L} := wff_o(\Sigma), \mathcal{K}$ be the class of first-order models, and $\mathcal{M} \models \mathbf{A} : \Leftrightarrow \mathcal{I}_{\varphi}(\mathbf{A}) = \mathsf{T}$, then $\langle \mathcal{L}, \mathcal{K}, \models \rangle$ is a logical system in the sense of Definition 4.0.1.

Note that central notions like the entailment relation (which is central for understanding reasoning processes) can be defined independently of the concrete compositional setup we have used for firstorder logic, and only need the general assumptions about logical systems.

Let us now turn to the syntactical counterpart of the entailment relation: derivability in a calculus. Again, we take care to define the concepts at the general level of logical systems.

Calculi, Derivations, and Proofs

The intuition of a calculus is that it provides a set of syntactic rules that allow to reason by considering the form of propositions alone. Such rules are called inference rules, and they can be strung together to derivations — which can alternatively be viewed either as sequences of formulae where all formulae are justified by prior formulae or as trees of inference rule applications. But we can also define a calculus in the more general setting of logical systems as an arbitrary relation on formulae with some general properties. That allows us to abstract away from the homomorphic setup of logics and calculi and concentrate on the basics.

Derivation Systems and Inference Rules \triangleright Definition 5.0.1 Let $\mathcal{S} := \langle \mathcal{L}, \mathcal{K}, \models \rangle$ be a logical system, then we call a relation $\vdash \subseteq \mathcal{P}(\mathcal{L}) \times \mathcal{L}$ a derivation relation for \mathcal{S} , if it \triangleright is proof-reflexive, i.e. $\mathcal{H} \vdash \mathbf{A}$, if $\mathbf{A} \in \mathcal{H}$; \triangleright is proof-transitive, i.e. if $\mathcal{H} \vdash \mathbf{A}$ and $\mathcal{H}' \cup \{\mathbf{A}\} \vdash \mathbf{B}$, then $\mathcal{H} \cup \mathcal{H}' \vdash \mathbf{B}$; \triangleright admits weakening, i.e. $\mathcal{H} \vdash \mathbf{A}$ and $\mathcal{H} \subseteq \mathcal{H}'$ imply $\mathcal{H}' \vdash \mathbf{A}$. \triangleright Definition 5.0.2 We call $\langle \mathcal{L}, \mathcal{K}, \models, \vdash \rangle$ a formal system, iff $\mathcal{S} := \langle \mathcal{L}, \mathcal{K}, \models \rangle$ is a logical system, and \vdash a derivation relation for S. \triangleright Definition 5.0.3 Let \mathcal{L} be a formal language, then an inference rule over \mathcal{L} $\frac{\mathbf{A}_1 \ \cdots \ \mathbf{A}_n}{\mathbf{C}} \mathcal{N}$ where A_1, \ldots, A_n and C are formula schemata for \mathcal{L} and \mathcal{N} is a name. The A_i are called assumptions, and C is called conclusion. ▷ Definition 5.0.4 An inference rule without assumptions is called an axiom (schema). \triangleright Definition 5.0.5 Let $S := \langle \mathcal{L}, \mathcal{K}, \models \rangle$ be a logical system, then we call a set C of inference rules over \mathcal{L} a calculus for \mathcal{S} . V JACOBS **©**

With formula schemata we mean representations of sets of formulae, we use boldface uppercase letters as (meta)-variables for formulae, for instance the formula schema $\mathbf{A} \Rightarrow \mathbf{B}$ represents the set of formulae whose head is \Rightarrow .

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Derivations and Proofs

 $\triangleright \ \, {\bf Definition} \ \, {\bf 5.0.6} \ \, {\rm Let} \ \, {\cal S} := \langle {\cal L}, {\cal K}, \models \rangle \ \, {\rm be} \ \, {\rm a} \ \, {\rm logical} \ \, {\rm system} \ \, {\rm and} \ \, {\cal C} \ \, {\rm a} \ \, {\rm calculus} \ \, {\rm for} \ \, {\cal S}, \ \, {\rm then} \ \, {\rm a} \ \, {\cal C} - {\rm derivation} \ \, {\rm of} \ \, {\rm a} \ \, {\rm formula} \ \, {\bf C} \in {\cal L} \ \, {\rm from} \ \, {\rm a} \ \, {\rm set} \ \, {\cal H} \subseteq {\cal L} \ \, {\rm of} \ \, {\rm hypotheses} \ \, {\rm (write} \ \, {\cal H} \vdash_{\cal C} \ \, {\bf C}) \ \, {\rm is} \ \, {\rm a} \ \, {\rm sequence} \ \, {\bf A}_1, \ldots, \ \, {\bf A}_m \ \, {\rm of} \ \, {\cal L} \ \, {\rm formulae}, \ \, {\rm such} \ \, {\rm that} \ \, {\rm that}$

 $\triangleright \mathbf{A}_m = \mathbf{C},$ (derivation culminates in C) \triangleright for all $1 \leq i \leq m$, either $\mathbf{A}_i \in \mathcal{H}$, or (hypothesis) \triangleright there is an inference rule $\frac{\mathbf{A}_{l_1} \cdots \mathbf{A}_{l_k}}{\mathbf{A}_i}$ in \mathcal{C} with $l_j < i$ for all $j \leq k$. (rule application) Observation: We can also see a derivation as a tree, where the A_{l_i} are the children of the node A_k . Example 5.0.7 In the propositional Hilbert $\frac{\overline{P \Rightarrow Q \Rightarrow P} K}{Q \Rightarrow P} MP$ calculus \mathcal{H}^0 we have the derivation $P \vdash_{\mathcal{H}^0} Q \Rightarrow P$: the sequence is $P \Rightarrow Q \Rightarrow P, P, Q \Rightarrow P$ and the corresponding tree on the right. ୲⊳ $\triangleright \ \mathbf{Observation} \ \mathbf{5.0.8} \ \textit{Let} \ \mathcal{S} := \langle \mathcal{L}, \mathcal{K}, \models \rangle \ \textit{be a logical system and} \ \mathcal{C} \ \textit{a calcu-}$ lus for S, then the C-derivation relation $\vdash_{\mathcal{D}}$ defined in Definition 5.0.6 is a derivation relation in the sense of Definition 5.0.1.¹ \triangleright Definition 5.0.9 We call $\langle \mathcal{L}, \mathcal{K}, \models, \mathcal{C} \rangle$ a formal system, iff $\mathcal{S} := \langle \mathcal{L}, \mathcal{K}, \models \rangle$ is a logical system, and C a calculus for S. \triangleright Definition 5.0.10 A derivation $\emptyset \vdash_{\mathcal{C}} A$ is called a proof of A and if one exists (write $\vdash_{\mathcal{C}} \mathbf{A}$) then \mathbf{A} is called a \mathcal{C} -theorem. \triangleright **Definition 5.0.11** an inference rule \mathcal{I} is called admissible in \mathcal{C} , if the extension of \mathcal{C} by \mathcal{I} does not yield new theorems. JACOBS UNIVERSIT © (C): Michael Kohlhase 17 ^aEDNOTE: MK: this should become a view!

Inference rules are relations on formulae represented by formula schemata (where boldface, uppercase letters are used as meta-variables for formulae). For instance, in Example 5.0.7 the inference rule $\frac{\mathbf{A} \Rightarrow \mathbf{B} \ \mathbf{A}}{\mathbf{B}}$ was applied in a situation, where the meta-variables \mathbf{A} and \mathbf{B} were instantiated by the formulae P and $Q \Rightarrow P$.

As axioms do not have assumptions, they can be added to a derivation at any time. This is just what we did with the axioms in Example 5.0.7.

Properties of Calculi

In general formulae can be used to represent facts about the world as propositions; they have a semantics that is a mapping of formulae into the real world (propositions are mapped to truth values.) We have seen two relations on formulae: the entailment relation and the deduction relation. The first one is defined purely in terms of the semantics, the second one is given by a calculus, i.e. purely syntactically. Is there any relation between these relations?



Ideally, both relations would be the same, then the calculus would allow us to infer all facts that can be represented in the given formal language and that are true in the real world, and only those. In other words, our representation and inference is faithful to the world.

A consequence of this is that we can rely on purely syntactical means to make predictions about the world. Computers rely on formal representations of the world; if we want to solve a problem on our computer, we first represent it in the computer (as data structures, which can be seen as a formal language) and do syntactic manipulations on these structures (a form of calculus). Now, if the provability relation induced by the calculus and the validity relation coincide (this will be quite difficult to establish in general), then the solutions of the program will be correct, and we will find all possible ones. Of course, the logics we have studied so far are very simple, and not able to express interesting facts about the world, but we will study them as a simple example of the fundamental problem of Computer Science: How do the formal representations correlate with the real world.

Within the world of logics, one can derive new propositions (the *conclusions*, here: *Socrates is mortal*) from given ones (the *premises*, here: *Every human is mortal* and *Sokrates is human*). Such derivations are *proofs*.

In particular, logics can describe the internal structure of real-life facts; e.g. individual things, actions, properties. A famous example, which is in fact as old as it appears, is illustrated in the slide below.



If a logic is correct, the conclusions one can prove are true (= hold in the real world) whenever the premises are true. This is a miraculous fact (think about it!)

Part II

First-Order Logic and Inference

Chapter 7 First-Order Logic

First-order logic is the most widely used formal system for modelling knowledge and inference processes. It strikes a very good bargain in the trade-off between expressivity and conceptual and computational complexity. To many people first-order logic is "the logic", i.e. the only logic worth considering, its applications range from the foundations of mathematics to natural language semantics.

First-Order Predicate Logic (PL^1)			
\triangleright Coverage: We can talk about	(All humans are mortal)		
individual things and denote them by variables or constants			
▷ properties of individuals,	of individuals, (e.g. being human or mortal)		
▷ relations of individuals,	(e.g. <i>sibling_of</i> relationship)		
▷ functions on individuals,	(e.g. the <i>father_of</i> function)		
We can also state the existence of an individual with a certain property, or the universality of a property.			
\triangleright But we cannot state assertions like			
\triangleright There is a surjective function from the natural numbers into the reals.			
First-Order Predicate Logic has many good properties (complete calculi, compactness, unitary, linear unification,)			
\triangleright But too weak for formalizing:	(at least directly)		
⊳ natural numbers, torsion groups, calculus,			
\triangleright generalized quantifiers (most, at least three, some,)			
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We will now introduce the syntax and semantics of first-order logic. This introduction differs from what we commonly see in undergraduate textbooks on logic in the treatment of substitutions in the presence of bound variables. These treatments are non-syntactic, in that they take the renaming of bound variables (α -equivalence) as a basic concept and directly introduce captureavoiding substitutions based on this. But there is a conceptual and technical circularity in this approach, since a careful definition of α -equivalence needs substitutions. In this Chapter we follow Peter Andrews' lead from [And02] and break the circularity by introducing syntactic substitutions, show a substitution value lemma with a substitutability condition, use that for a soundness proof of α -renaming, and only then introduce capture-avoiding substitutions on this basis. This can be done for any logic with bound variables, we go through the details for first-order logic here as an example.

7.1 First-Order Logic: Syntax and Semantics

The syntax and semantics of first-order logic is systematically organized in two distinct layers: one for truth values (like in propositional logic) and one for individuals (the new, distinctive feature of first-order logic).

The first step of defining a formal language is to specify the alphabet, here the first-order signatures and their components.



We make the deliberate, but non-standard design choice here to include Skolem constants into the signature from the start. These are used in inference systems to give names to objects and construct witnesses. Other than the fact that they are usually introduced by need, they work exactly like regular constants, which makes the inclusion rather painless. As we can never predict how many Skolem constants we are going to need, we give ourselves countably infinitely many for every arity. Our supply of individual variables is countably infinite for the same reason.

The formulae of first-order logic is built up from the signature and variables as terms (to represent individuals) and propositions (to represent propositions). The latter include the propositional connectives, but also quantifiers.



Note: that we only need e.g. conjunction, negation, and universal quantification, all other logical constants can be defined from them (as we will see when we have fixed their interpretations).

The introduction of quantifiers to first-order logic brings a new phenomenon: variables that are under the scope of a quantifiers will behave very differently from the ones that are not. Therefore we build up a vocabulary that distinguishes the two.

Free and Bound Variables \triangleright Definition 7.1.8 We call an occurrence of a variable X bound in a formula **A**, iff it occurs in a sub-formula $\forall X \cdot \mathbf{B}$ of **A**. We call a variable occurrence free otherwise. For a formula A, we will use BVar(A) (and free(A)) for the set of bound (free) variables of A, i.e. variables that have a free/bound occurrence in A. \triangleright Definition 7.1.9 We define the set free(A) of free variables of a formula A inductively: $free(X) := \{X\}$ $\begin{aligned} &\operatorname{free}(f(\mathbf{A}_1,\ldots,\mathbf{A}_n)) := \bigcup_{1 \leq i \leq n} \operatorname{free}(\mathbf{A}_i) \\ &\operatorname{free}(p(\mathbf{A}_1,\ldots,\mathbf{A}_n)) := \bigcup_{1 \leq i \leq n} \operatorname{free}(\mathbf{A}_i) \end{aligned}$ $\operatorname{free}(\neg \mathbf{A}) := \operatorname{free}(\mathbf{A})$ $\operatorname{free}(\mathbf{A} \wedge \mathbf{B}) := \operatorname{free}(\mathbf{A}) \cup \operatorname{free}(\mathbf{B})$ $\operatorname{free}(\forall X \cdot \mathbf{A}) := \operatorname{free}(\mathbf{A}) \setminus \{X\}$ \triangleright Definition 7.1.10 We call a formula A closed or ground, iff free(A) = \emptyset . We call a closed proposition a sentence, and denote the set of all ground terms with $cwff_{\iota}(\Sigma_{\iota})$ and the set of sentences with $cwff_{\iota}(\Sigma_{\iota})$.

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We will be mainly interested in (sets of) sentences – i.e. closed propositions – as the representations of meaningful statements about individuals. Indeed, we will see below that free variables do not gives us expressivity, since they behave like constants and could be replaced by them in all situations, except the recursive definition of quantified formulae. Indeed in all situations where variables occur freely, they have the character of meta-variables, i.e. syntactic placeholders that can be instantiated with terms when needed in an inference calculus.

The semantics of first-order logic is a Tarski-style set-theoretic semantics where the atomic syntactic entities are interpreted by mapping them into a well-understood structure, a first-order universe that is just an arbitrary set.



We do not have to make the universe of truth values part of the model, since it is always the same; we determine the model by choosing a universe and an interpretation function.

Given a first-order model, we can define the evaluation function as a homomorphism over the construction of formulae.

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The only new (and interesting) case in this definition is the quantifier case, there we define the value of a quantified formula by the value of its scope – but with an extended variable assignment. Note that by passing to the scope **A** of $\forall x. \mathbf{A}$, the occurrences of the variable x in **A** that were bound in $\forall x. \mathbf{A}$ become free and are amenable to evaluation by the variable assignment $\psi := \varphi, [a/X]$. Note that as an extension of φ , the assignment ψ supplies exactly the right value for x in **A**. This variability of the variable assignment in the definition value function justifies the somewhat complex setup of first-order evaluation, where we have the (static) interpretation function for the symbols from the signature and the (dynamic) variable assignment for the variables.

Note furthermore, that the value $\mathcal{I}_{\varphi}(\exists x. \mathbf{A})$ of $\exists x. \mathbf{A}$, which we have defined to be $\neg (\forall x. \neg \mathbf{A})$ is true, iff it is not the case that $\mathcal{I}_{\varphi}(\forall x. \neg \mathbf{A}) = \mathcal{I}_{\psi}(\neg \mathbf{A}) = \mathsf{F}$ for all $\mathsf{a} \in \mathcal{D}_{\iota}$ and $\psi := \varphi, [a/X]$. This is the case, iff $\mathcal{I}_{\psi}(\mathbf{A}) = \mathsf{T}$ for some $\mathsf{a} \in \mathcal{D}_{\iota}$. So our definition of the existential quantifier yields the appropriate semantics.

7.2 First-Order Substitutions

We will now turn our attention to substitutions, special formula-to-formula mappings that operationalize the intuition that (individual) variables stand for arbitrary terms.

Substitutions on Terms \triangleright Intuition: If **B** is a term and X is a variable, then we denote the result of systematically replacing all occurrences of X in a term A by B with $[\mathbf{B}/X](\mathbf{A})$. \triangleright Problem: What about [Z/Y], [Y/X](X), is that Y or Z? \triangleright Folklore: [Z/Y], [Y/X](X) = Y, but [Z/Y]([Y/X](X)) = Z of course. (Parallel application) \triangleright Definition 7.2.1 We call $\sigma: wff_{\ell}(\Sigma_{\ell}) \to wff_{\ell}(\Sigma_{\ell})$ a substitution, iff $\sigma(f(\mathbf{A}_{1}, \ldots, \mathbf{A}_{n})) =$ $f(\sigma(\mathbf{A}_1),\ldots,\sigma(\mathbf{A}_n))$ and the support $\operatorname{supp}(\sigma) := \{X \mid \sigma(X) \neq X\}$ of σ is finite. \triangleright Observation 7.2.2 Note that a substitution σ is determined by its values on variables alone, thus we can write σ as $\sigma|_{\mathcal{V}_{\iota}} = \{[\sigma(X)/X] | X \in \operatorname{supp}(\sigma)\}.$ \triangleright Notation 7.2.3 We denote the substitution σ with supp $(\sigma) = \{x^i \mid 1 \le i \le n\}$ and $\sigma(x^i) = \mathbf{A}_i$ by $[\mathbf{A}_1/x^1], \dots, [\mathbf{A}_n/x^n]$. \triangleright Example 7.2.4 [a/x], [f(b)/y], [a/z] instantiates g(x, y, h(z)) to g(a, f(b), h(a)). \triangleright Definition 7.2.5 We call $intro(\sigma) := \bigcup_{X \in supp(\sigma)} free(\sigma(X))$ the set of variables introduced by σ . JACOBS (C): Michael Kohlhase 26

The extension of a substitution is an important operation, which you will run into from time to time. Given a substitution σ , a variable x, and an expression \mathbf{A} , σ , $[\mathbf{A}/x]$ extends σ with a new value for x. The intuition is that the values right of the comma overwrite the pairs in the substitution on the left, which already has a value for x, even though the representation of σ may not show it.



Note that the use of the comma notation for substitutions defined in Notation 7.2.3 is consistent with substitution extension. We can view a substitution [a/x], [f(b)/y] as the extension of the empty substitution (the identity function on variables) by [f(b)/y] and then by [a/x]. Note furthermore, that substitution extension is not commutative in general.

For first-order substitutions we need to extend the substitutions defined on terms to act on propositions. This is technically more involved, since we have to take care of bound variables.



Here we come to a conceptual problem of most introductions to first-order logic: they directly define substitutions to be capture-avoiding by stipulating that bound variables are renamed in

the to ensure substitutability. But at this time, we have not even defined alphabetic renaming yet, and cannot formally do that without having a notion of substitution. So we will refrain from introducing capture-avoiding substitutions until we have done our homework.

We now introduce a central tool for reasoning about the semantics of substitutions: the "substitutionvalue Lemma", which relates the process of instantiation to (semantic) evaluation. This result will be the motor of all soundness proofs on axioms and inference rules acting on variables via substitutions. In fact, any logic with variables and substitutions will have (to have) some form of a substitution-value Lemma to get the meta-theory going, so it is usually the first target in any development of such a logic.

We establish the substitution-value Lemma for first-order logic in two steps, first on terms, where it is very simple, and then on propositions, where we have to take special care of substitutability.

Substitution Value Lemma for Terms \triangleright Lemma 7.2.11 Let A and B be terms, then $\mathcal{I}_{\omega}([\mathbf{B}/X]\mathbf{A}) = \mathcal{I}_{\psi}(\mathbf{A})$, where $\psi = \varphi, [\mathcal{I}_{\varphi}(\mathbf{B})/X].$ \triangleright **Proof**: by induction on the depth of **A**: **P.1.1 depth=0**: **P.1.1.1** Then **A** is a variable (say Y), or constant, so we have three cases **P.1.1.1.1** $\mathbf{A} = Y = X$: then $\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A})) = \mathcal{I}_{\varphi}([\mathbf{B}/X](X)) = \mathcal{I}_{\varphi}(\mathbf{B}) = \mathcal{I}_{\varphi}(\mathbf{B})$ $\psi(X) = \mathcal{I}_{\psi}(X) = \mathcal{I}_{\psi}(\mathbf{A}).$ **P.1.1.1.2** $\mathbf{A} = Y \neq X$: then $\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A})) = \mathcal{I}_{\varphi}([\mathbf{B}/X](Y)) = \mathcal{I}_{\varphi}(Y) =$ $\varphi(Y) = \psi(Y) = \mathcal{I}_{\psi}(Y) = \mathcal{I}_{\psi}(\mathbf{A}).$ **P.1.1.1.3** A is a constant: analogous to the preceding case $(Y \neq X)$ **P.1.1.2** This completes the base case (depth = 0). **P.1.2 depth** > 0: then $\mathbf{A} = f(\mathbf{A}_1, \dots, \mathbf{A}_n)$ and we have $\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A})) = \mathcal{I}(f)(\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A}_1)), \dots, \mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A}_n)))$ $= \mathcal{I}(f)(\mathcal{I}_{\psi}(\mathbf{A}_1),\ldots,\mathcal{I}_{\psi}(\mathbf{A}_n))$ $= \mathcal{I}_{\psi}(\mathbf{A}).$ by inductive hypothesis P.1.2.2 This completes the inductive case, and we have proven the assertion C JACOBS UNIVERST (c): Michael Kohlhase 29

We now come to the case of propositions. Note that we have the additional assumption of substitutability here.

Substitution Value Lemma for Propositions $\triangleright \text{ Lemma 7.2.12 Let } \mathbf{B} \in wff_{\iota}(\Sigma_{\iota}) \text{ be substitutable for } X \text{ in } \mathbf{A} \in wff_{o}(\Sigma),$ $then \mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A})) = \mathcal{I}_{\psi}(\mathbf{A}), \text{ where } \psi = \varphi, [\mathcal{I}_{\varphi}(\mathbf{B})/X].$ $\triangleright \text{ Proof: by induction on the number } n \text{ of connectives and quantifiers in } \mathbf{A}$



To understand the proof full, you should look out where the substitutability is actually used.

Armed with the substitution value lemma, we can now define alphabetic renaming and show it to be sound with respect to the semantics we defined above. And this soundness result will justify the definition of capture-avoiding substitution we will use in the rest of the course.

7.3 Alpha-Renaming for First-Order Logic

Armed with the substitution value lemma we can now prove one of the main representational facts for first-order logic: the names of bound variables do not matter; they can be renamed at liberty without changing the meaning of a formula.



We have seen that naive substitutions can lead to variable capture. As a consequence, we always have to presuppose that all instantiations respect a substitutability condition, which is quite tedious. We will now come up with an improved definition of substitution application for firstorder logic that does not have this problem.

Avoiding Variable Capture by Built-in α -renaming



Inference in First-Order Logic

In this Chapter we will introduce inference systems (calculi) for first-order logic and study their properties, in particular soundness and completeness.

8.1 First-Order Calculi

In this section we will introduce two reasoning calculi for first-order logic, both were invented by Gerhard Gentzen in the 1930's and are very much related. The "natural deduction" calculus was created in order to model the natural mode of reasoning e.g. in everyday mathematical practice. This calculus was intended as a counter-approach to the well-known Hilbert-style calculi, which were mainly used as theoretical devices for studying reasoning in principle, not for modeling particular reasoning styles.

The "sequent calculus" was a rationalized version and extension of the natural deduction calculus that makes certain meta-proofs simpler to push through².

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Both calculi have a similar structure, which is motivated by the human-orientation: rather than using a minimal set of inference rules, they provide two inference rules for every connective and quantifier, one "introduction rule" (an inference rule that derives a formula with that symbol at the head) and one "elimination rule" (an inference rule that acts on a formula with this head and derives a set of subformulae).

This allows us to introduce the calculi in two stages, first for the propositional connectives and then extend this to a calculus for first-order logic by adding rules for the quantifiers.

8.1.1 Propositional Natural Deduction Calculus

We will now introduce the "natural deduction" calculus for propositional logic. The calculus was created in order to model the natural mode of reasoning e.g. in everyday mathematical practice. This calculus was intended as a counter-approach to the well-known Hilbert style calculi, which were mainly used as theoretical devices for studying reasoning in principle, not for modeling particular reasoning styles.

Rather than using a minimal set of inference rules, the natural deduction calculus provides two/three inference rules for every connective and quantifier, one "introduction rule" (an inference rule that derives a formula with that symbol at the head) and one "elimination rule" (an inference rule that acts on a formula with this head and derives a set of subformulae).



 $^{^{2}}$ EdNote: say something about cut elimination/analytical calculi somewhere



The most characteristic rule in the natural deduction calculus is the $\Rightarrow I$ rule. It corresponds to the mathematical way of proving an implication $\mathbf{A} \Rightarrow \mathbf{B}$: We assume that \mathbf{A} is true and show \mathbf{B} from this assumption. When we can do this we discharge (get rid of) the assumption and conclude $\mathbf{A} \Rightarrow \mathbf{B}$. This mode of reasoning is called hypothetical reasoning. Note that the local hypothesis is discharged by the rule $\Rightarrow I$, i.e. it cannot be used in any other part of the proof. As the $\Rightarrow I$ rules may be nested, we decorate both the rule and the corresponding assumption with a marker (here the number 1).

Let us now consider an example of hypothetical reasoning in action.



One of the nice things about the natural deduction calculus is that the deduction theorem is almost trivial to prove. In a sense, the triviality of the deduction theorem is the central idea of the calculus and the feature that makes it so natural.

A Deduction Theorem for \mathcal{ND}^0 \triangleright Theorem 8.1.2 $\mathcal{H}, \mathbf{A} \vdash_{\mathcal{ND}^0} \mathbf{B}$, iff $\mathcal{H} \vdash_{\mathcal{ND}^0} \mathbf{A} \Rightarrow \mathbf{B}$.


Another characteristic of the natural deduction calculus is that it has inference rules (introduction and elimination rules) for all connectives. So we extend the set of rules from Definition 8.1.1 for disjunction, negation and falsity.



To obtain a first-order calculus, we have to extend \mathcal{ND}^0 with (introduction and elimination) rules for the quantifiers.

First-Order Natural Deduction $(\mathcal{ND}^1; \text{ Gentzen [Gen35]})$ \triangleright Rules for propositional connectives just as always \triangleright Definition 8.1.4 (New Quantifier Rules) The first-order natural deduction calculus \mathcal{ND}^1 extends \mathcal{ND}^0 by the following four rules $\frac{\mathbf{A}}{\forall X.\mathbf{A}} \forall I^* \qquad \frac{\forall X.\mathbf{A}}{[\mathbf{B}/X](\mathbf{A})} \forall E$ $[[c/X](\mathbf{A})]^1$ $\frac{[\mathbf{B}/X](\mathbf{A})}{\exists X.\mathbf{A}} \exists I \qquad \frac{\exists X.\mathbf{A}}{\mathbf{C}} \exists E^1$

* means that	${\bf A}$ does not depend on any hypot	hesis in which X is fr	ree.
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The intuition behind the rule $\forall I$ is that a formula \mathbf{A} with a (free) variable X can be generalized to $\forall X.\mathbf{A}$, if X stands for an arbitrary object, i.e. there are no restricting assumptions about X. The $\forall E$ rule is just a substitution rule that allows to instantiate arbitrary terms \mathbf{B} for X in \mathbf{A} . The $\exists I$ rule says if we have a witness \mathbf{B} for X in \mathbf{A} (i.e. a concrete term \mathbf{B} that makes \mathbf{A} true), then we can existentially close \mathbf{A} . The $\exists E$ rule corresponds to the common mathematical practice, where we give objects we know exist a new name c and continue the proof by reasoning about this concrete object c. Anything we can prove from the assumption $[c/X](\mathbf{A})$ we can prove outright if $\exists X.\mathbf{A}$ is known.

One of the nice things about the natural deduction calculus is that the deduction theorem is almost trivial to prove. In a sense, the triviality of the deduction theorem is the central idea of the calculus and the feature that makes it so natural.

A Deduction Theorem for \mathcal{ND}^0 \triangleright Theorem 8.1.5 $\mathcal{H}, \mathbf{A} \vdash_{\mathcal{ND}^0} \mathbf{B}$, iff $\mathcal{H} \vdash_{\mathcal{ND}^0} \mathbf{A} \Rightarrow \mathbf{B}$. \triangleright Proof: We show the two directions separately P.1 If $\mathcal{H}, \mathbf{A} \vdash_{\mathcal{ND}^0} \mathbf{B}$, then $\mathcal{H} \vdash_{\mathcal{ND}^0} \mathbf{A} \Rightarrow \mathbf{B}$ by $\Rightarrow I$, and P.2 If $\mathcal{H} \vdash_{\mathcal{ND}^0} \mathbf{A} \Rightarrow \mathbf{B}$, then $\mathcal{H}, \mathcal{A} \vdash_{\mathcal{ND}^0} \mathbf{A} \Rightarrow \mathbf{B}$ by weakening and $\mathcal{H}, \mathcal{A} \vdash_{\mathcal{ND}^0} \mathbf{B}$ by $\Rightarrow E$.

This is the classical formulation of the calculus of natural deduction. To prepare the things we want to do later (and to get around the somewhat un-licensed extension by hypothetical reasoning in the calculus), we will reformulate the calculus by lifting it to the "judgements level". Instead of postulating rules that make statements about the validity of propositions, we postulate rules that make state about derivability. This move allows us to make the respective local hypotheses in ND derivations into syntactic parts of the objects (we call them "sequents") manipulated by the inference rules.

Natural Deduction in Sequent Calculus Formulation
▷ Idea: Explicit representation of hypotheses (lift calculus to judgments)
▷ Definition 8.1.6 A judgment is a meta-statement about the provability of propositions
▷ Definition 8.1.7 A sequent is a judgment of the form H ⊢ A about the provability of the formula A from the set H of hypotheses.
▷ Idea: Reformulate ND rules so that they act on sequents



Sequent-Style Rules for Natural Deduction> Definition 8.1.9 The following inference rules make up the sequent calculus $\overline{\Gamma, A \vdash A}^{Ax} \qquad \frac{\Gamma \vdash B}{\Gamma, A \vdash B} \text{ weaken} \qquad \overline{\Gamma \vdash A \lor A} \frac{TND}{\Gamma \vdash A \lor B} \frac{\Gamma \vdash A \land B}{\Gamma \vdash A \land B} \wedge E_l \qquad \frac{\Gamma \vdash A \land B}{\Gamma \vdash B} \wedge E_r$ $\frac{\Gamma \vdash A}{\Gamma \vdash A \lor B} \lor I \qquad \frac{\Gamma \vdash A \land B}{\Gamma \vdash A \lor B} \wedge E_l \qquad \frac{\Gamma \vdash A \land B}{\Gamma \vdash C} \lor E$ $\frac{\Gamma \vdash A}{\Gamma \vdash A \lor B} \forall I \qquad \frac{\Gamma \vdash A \lor B}{\Gamma \vdash A \lor B} \Rightarrow E$ $\frac{\Gamma, A \vdash B}{\Gamma \vdash A \Rightarrow B} \Rightarrow I \qquad \frac{\Gamma \vdash A \Rightarrow B}{\Gamma \vdash B} \Rightarrow E$ $\frac{\Gamma, A \vdash B}{\Gamma \vdash A \Rightarrow B} \Rightarrow I \qquad \frac{\Gamma \vdash A \Rightarrow B}{\Gamma \vdash B} \Rightarrow E$ $\frac{\Gamma \vdash A \rightarrow F}{\Gamma \vdash A} = F I \qquad \frac{\Gamma \vdash A}{\Gamma \vdash A} = F E$ (C: Michael Kohlhase

First-Order Natural Deduction in Sequent Formulation \triangleright Rules for propositional connectives just as always \triangleright Definition 8.1.10 (New Quantifier Rules) $\frac{\Gamma \vdash \mathbf{A} \ X \notin \operatorname{free}(\Gamma)}{\Gamma \vdash \forall X \cdot \mathbf{A}} \forall I$ $\frac{\Gamma \vdash [\mathbf{B}/X](\mathbf{A})}{\Gamma \vdash \exists X \cdot \mathbf{A}} \exists I$ $\frac{\Gamma \vdash \exists X \cdot \mathbf{A} \ \Gamma, [c/X](\mathbf{A}) \vdash \mathbf{C} \ c \in \Sigma_0^{sk} \operatorname{new}}{\Gamma \vdash \mathbf{C}} \exists E$ ©: Michael Kohlhase

We leave the soundness result for the first-order natural deduction calculus to the reader and turn to the complenesss result, which is much more involved and interesting.

8.2 Abstract Consistency and Model Existence

We will now come to an important tool in the theoretical study of reasoning calculi: the "abstract consistency"/"model existence" method. This method for analyzing calculi was developed by Jaako Hintikka, Raymond Smullyann, and Peter Andrews in 1950-1970 as an encapsulation of similar constructions that were used in completeness arguments in the decades before.³

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The basic intuition for this method is the following: typically, a logical system $S = \langle \mathcal{L}, \mathcal{K}, \models \rangle$ has multiple calculi, human-oriented ones like the natural deduction calculi and machine-oriented ones like the automated theorem proving calculi. All of these need to be analyzed for completeness (as a basic quality assurance measure).

A completeness proof for a calculus C for S typically comes in two parts: one analyzes C-consistency (sets that cannot be refuted in C), and the other construct K-models for C-consistent sets.

In this situation the "abstract consistency"/"model existence" method encapsulates the model construction process into a meta-theorem: the "model existence" theorem. This provides a set of syntactic ("abstract consistency") conditions for calculi that are sufficient to construct models.

With the model existence theorem it suffices to show that C-consistency is an abstract consistency property (a purely syntactic task that can be done by a C-proof transformation argument) to obtain a completeness result for C.



The proof of the model existence theorem goes via the notion of a Hintikka set, a set of formulae with very strong syntactic closure properties, which allow to read off models. Jaako Hintikka's original idea for completeness proofs was that for every complete calculus C and every C-consistent set one can induce a Hintikka set, from which a model can be constructed. This can be considered as a first model existence theorem. However, the process of obtaining a Hintikka set for a set C-consistent set Φ of sentences usually involves complicated calculus-dependent constructions.

In this situation, Raymond Smullyann was able to formulate the sufficient conditions for the existence of Hintikka sets in the form of "abstract consistency properties" by isolating the calculusindependent parts of the Hintikka set construction. His technique allows to reformulate Hintikka sets as maximal elements of abstract consistency classes and interpret the Hintikka set construction as a maximizing limit process.

³EdNote: cite the original papers!

To carry out the "model-existence"/"abstract consistency" method, we will first have to look at the notion of consistency.

Consistency and refutability are very important notions when studying the completeness for calculi; they form syntactic counterparts of satisfiability.



It is very important to distinguish the syntactic C-refutability and C-consistency from satisfiability, which is a property of formulae that is at the heart of semantics. Note that the former specify the calculus (a syntactic device) while the latter does not. In fact we should actually say S-satisfiability, where $S = \langle \mathcal{L}, \mathcal{K}, \models \rangle$ is the current logical system.

Even the word "contradiction" has a syntactical flavor to it, it translates to "saying against each other" from its latin root.

The notion of an "abstract consistency class" provides the a calculus-independent notion of "consistency": A set Φ of sentences is considered "consistent in an abstract sense", iff it is a member of an abstract consistency class ∇ .

Abstract Consistency

- \triangleright Definition 8.2.6 Let ∇ be a family of sets. We call ∇ closed under subsets, iff for each $\Phi \in \nabla$, all subsets $\Psi \subseteq \Phi$ are elements of ∇ .
- \triangleright Notation 8.2.7 We will use $\Phi * \mathbf{A}$ for $\Phi \cup \{\mathbf{A}\}$.
- \triangleright Definition 8.2.8 A family $\nabla \subseteq wff_o(\Sigma)$ of sets of formulae is called a (first-order) abstract consistency class, iff it is closed under subsets, and for each $\Phi \in \nabla$
 - ∇_{c}) $\mathbf{A} \notin \Phi$ or $\neg \mathbf{A} \notin \Phi$ for atomic $\mathbf{A} \in wff_{o}(\Sigma)$.
 - ∇_{\neg}) $\neg \neg \mathbf{A} \in \Phi$ implies $\Phi * \mathbf{A} \in \nabla$
 - ∇_{\wedge}) ($\mathbf{A} \wedge \mathbf{B}$) $\in \Phi$ implies ($\Phi \cup {\{\mathbf{A}, \mathbf{B}\}}$) $\in \nabla$

 $\nabla_{\forall}) \text{ If } (\forall X \cdot \mathbf{A}) \in \Phi, \text{ then } \Phi * [\mathbf{B}/X](\mathbf{A}) \in \nabla \text{ for each closed term } \mathbf{B}.$ $\nabla_{\exists}) \text{ If } \neg (\forall X \cdot \mathbf{A}) \in \Phi \text{ and } c \text{ is an individual constant that does not occur in } \Phi, \text{ then } \Phi * \neg [c/X](\mathbf{A}) \in \nabla$ C: Michael Kohlhase 44

The conditions are very natural: Take for instance ∇_c , it would be foolish to call a set Φ of sentences "consistent under a complete calculus", if it contains an elementary contradiction. The next condition ∇_{\neg} says that if a set Φ that contains a sentence $\neg \neg \mathbf{A}$ is "consistent", then we should be able to extend it by \mathbf{A} without losing this property; in other words, a complete calculus should be able to recognize \mathbf{A} and $\neg \neg \mathbf{A}$ to be equivalent.

We will carry out the proof here, since it gives us practice in dealing with the abstract consistency properties.

Actually we are after abstract consistency classes that have an even stronger property than just being closed under subsets. This will allow us to carry out a limit construction in the Hintikka set extension argument later.

Compact Collections> Definition 8.2.9 We call a collection ∇ of sets compact, iff for any set Φ
we have
 $\Phi \in \nabla$, iff $\Psi \in \nabla$ for every finite subset Ψ of Φ .> Lemma 8.2.10 If ∇ is compact, then ∇ is closed under subsets.> Proof:P.1 Suppose $S \subseteq T$ and $T \in \nabla$.P.2 Every finite subset A of S is a finite subset of T.P.3 As ∇ is compact, we know that $A \in \nabla$.P.4 Thus $S \in \nabla$. \square \square \square \square \square \square \square \square

The property of being closed under subsets is a "downwards-oriented" property: We go from large sets to small sets, compactness (the interesting direction anyways) is also an "upwards-oriented" property. We can go from small (finite) sets to large (infinite) sets. The main application for the compactness condition will be to show that infinite sets of formulae are in a family ∇ by testing all their finite subsets (which is much simpler).

The main result here is that abstract consistency classes can be extended to compact ones. The proof is quite tedious, but relatively straightforward. It allows us to assume that all abstract consistency classes are compact in the first place (otherwise we pass to the compact extension).

Compact Abstract Consistency Classes

▷ Lemma 8.2.11 Any first-order abstract consistency class can be extended to a compact one.

 \triangleright **Proof**:

P.1 We choose $\nabla' := \{ \Phi \subseteq cwff_o(\Sigma_\iota) \mid \text{every finite subset of } \Phi \text{ is in } \nabla \}.$



Hintikka sets are sets of sentences with very strong analytic closure conditions. These are motivated as maximally consistent sets i.e. sets that already contain everything that can be consistently added to them.

abla-Hintikka Set

- \triangleright Definition 8.2.12 Let ∇ be an abstract consistency class, then we call a set $\mathcal{H} \in \nabla$ a ∇ -Hintikka Set, iff \mathcal{H} is maximal in ∇ , i.e. for all \mathbf{A} with $\mathcal{H} * \mathbf{A} \in \nabla$ we already have $\mathbf{A} \in \mathcal{H}$.
- \triangleright Theorem 8.2.13 (Hintikka Properties) Let ∇ be an abstract consistency class and \mathcal{H} be a ∇ -Hintikka set, then

 \mathcal{H}_c) For all $\mathbf{A} \in wff_o(\Sigma)$ we have $\mathbf{A} \notin \mathcal{H}$ or $\neg \mathbf{A} \notin \mathcal{H}$. \mathcal{H}_{\neg}) If $\neg \neg \mathbf{A} \in \mathcal{H}$ then $\mathbf{A} \in \mathcal{H}$.

 \mathcal{H}_{\wedge}) If $(\mathbf{A} \wedge \mathbf{B}) \in \mathcal{H}$ then $\mathbf{A}, \mathbf{B} \in \mathcal{H}$.

 \mathcal{H}_{\vee}) If $\neg (\mathbf{A} \land \mathbf{B}) \in \mathcal{H}$ then $\neg \mathbf{A} \in \mathcal{H}$ or $\neg \mathbf{B} \in \mathcal{H}$.

 \mathcal{H}_{\forall}) If $(\forall X.A) \in \mathcal{H}$, then $[\mathbf{B}/X](\mathbf{A}) \in \mathcal{H}$ for each closed term \mathbf{B} .

 \mathcal{H}_{\exists}) If $\neg (\forall X \cdot \mathbf{A}) \in \mathcal{H}$ then $\neg [\mathbf{B}/X](\mathbf{A}) \in \mathcal{H}$ for some term closed term \mathbf{B} .

Proof:



The following theorem is one of the main results in the "abstract consistency"/"model existence" method. For any abstract consistent set Φ it allows us to construct a Hintikka set \mathcal{H} with $\Phi \in \mathcal{H}$.

P.4 Extension Theorem \triangleright Theorem 8.2.14 If ∇ is an abstract consistency class and $\Phi \in \nabla$ finite, then there is a ∇ -Hintikka set \mathcal{H} with $\Phi \subseteq \mathcal{H}$. \triangleright **Proof**: Wlog. assume that ∇ compact (else use compact extension) **P.1** Choose an enumeration $\mathbf{A}^1, \mathbf{A}^2, \ldots$ of $cwff_o(\Sigma_{\iota})$ and c^1, c^2, \ldots of Σ_0^{sk} . **P.2** and construct a sequence of sets H^i with $H^0 := \Phi$ and $H^{n+1} := \begin{cases} H^n & \text{if } H^n * \mathbf{A}^n \notin \nabla \\ H^n \cup \{\mathbf{A}^n, \neg [c^n/X](\mathbf{B})\} & \text{if } H^n * \mathbf{A}^n \in \nabla \text{ and } \mathbf{A}^n = \neg (\forall X \cdot \mathbf{B}) \\ H^n * \mathbf{A}^n & \text{else} \end{cases}$ **P.3** Note that all $H^i \in \nabla$, choose $\mathcal{H} := \bigcup_{i \in \mathbb{N}} H^i$ **P.4** $\Psi \subseteq \mathcal{H}$ finite implies there is a $j \in \mathbb{N}$ such that $\Psi \subseteq H^j$, **P.5** so $\Psi \in \nabla$ as ∇ closed under subsets and $\mathcal{H} \in \nabla$ as ∇ is compact. **P.6** Let $\mathcal{H} * \mathbf{B} \in \nabla$, then there is a $j \in \mathbb{N}$ with $\mathbf{B} = \mathbf{A}^{j}$, so that $\mathbf{B} \in H^{j+1}$ and $H^{j+1} \subset \mathcal{H}$ **P.7** Thus \mathcal{H} is ∇ -maximal JACOBS UNIVERSITY (c): Michael Kohlhase 48

Note that the construction in the proof above is non-trivial in two respects. First, the limit construction for \mathcal{H} is not executed in our original abstract consistency class ∇ , but in a suitably extended one to make it compact — the original would not have contained \mathcal{H} in general. Second, the set \mathcal{H} is not unique for Φ , but depends on the choice of the enumeration of $cwff_o(\Sigma_{\iota})$. If we pick a different enumeration, we will end up with a different \mathcal{H} . Say if \mathbf{A} and $\neg \mathbf{A}$ are both

 ∇ -consistent⁴ with Φ , then depending on which one is first in the enumeration \mathcal{H} , will contain EdN:4 that one; with all the consequences for subsequent choices in the construction process.



Thus a valuation is a weaker notion of evaluation in first-order logic; the other direction is also true, even though the proof of this result is much more involved: The existence of a first-order valuation that makes a set of sentences true entails the existence of a model that satisfies it.⁵

EdN:5

Valuation and Satisfiability \triangleright Lemma 8.2.17 If ν : $cwff_{\rho}(\Sigma_{\iota}) \rightarrow \mathcal{D}_{\rho}$ is a valuation and $\Phi \subseteq cwff_{\rho}(\Sigma_{\iota})$ with $\nu(\Phi) = \{\mathsf{T}\}, \text{ then } \Phi \text{ is satisfiable.}$ \triangleright **Proof**: We construct a model for Φ . **P.1** Let $\mathcal{D}_{\iota} := cwff_{\iota}(\Sigma_{\iota})$, and $\triangleright \mathcal{I}(f) \colon \mathcal{D}_{\iota}^{k} \to \mathcal{D}_{\iota}; \langle \mathbf{A}_{1}, \dots, \mathbf{A}_{k} \rangle \mapsto f(\mathbf{A}_{1}, \dots, \mathbf{A}_{k}) \text{ for } f \in \Sigma^{f}$ $\triangleright \mathcal{I}(p) \colon \mathcal{D}_{\iota}^{k} \to \mathcal{D}_{o}; \langle \mathbf{A}_{1}, \dots, \mathbf{A}_{k} \rangle \mapsto \nu(p(\mathbf{A}_{1}, \dots, \mathbf{A}_{n})) \text{ for } p \in \Sigma^{p}.$ **P.2** Then variable assignments into \mathcal{D}_{t} are ground substitutions. **P.3** We show $\mathcal{I}_{\varphi}(\mathbf{A}) = \varphi(\mathbf{A})$ for $\mathbf{A} \in wff_{\iota}(\Sigma_{\iota})$ by induction on \mathbf{A} **P.3.1** $\mathbf{A} = X$: then $\mathcal{I}_{\varphi}(\mathbf{A}) = \varphi(X)$ by definition. $\begin{array}{lll} \mathbf{P.3.2} \ \mathbf{A} \ = \ f(\mathbf{A}_1, \dots, \mathbf{A}_n) \text{:} & \text{then} \ \mathcal{I}_{\varphi}(\mathbf{A}) \ = \ \mathcal{I}(f)(\mathcal{I}_{\varphi}(\mathbf{A}_1), \dots, \mathcal{I}_{\varphi}(\mathbf{A}_n)) \ = \\ \mathcal{I}(f)(\varphi(\mathbf{A}_1), \dots, \varphi(\mathbf{A}_n)) \ = \ f(\varphi(\mathbf{A}_1), \dots, \varphi(\mathbf{A}_n)) \ = \ \varphi(f(\mathbf{A}_1, \dots, \mathbf{A}_n)) \ = \end{array}$ $\varphi(\mathbf{A})$ **P.4** We show $\mathcal{I}_{\varphi}(\mathbf{A}) = \nu(\varphi(\mathbf{A}))$ for $\mathbf{A} \in wff_{\rho}(\Sigma)$ by induction on \mathbf{A} $\begin{array}{ll} \mathbf{P.4.1} \ \mathbf{A} \ = \ p(\mathbf{A}_1, \dots, \mathbf{A}_n): & \text{then } \mathcal{I}_{\varphi}(\mathbf{A}) \ = \ \mathcal{I}(p)(\mathcal{I}_{\varphi}(\mathbf{A}_1), \dots, \mathcal{I}_{\varphi}(\mathbf{A}_n)) \ = \\ \mathcal{I}(p)(\varphi(\mathbf{A}_1), \dots, \varphi(\mathbf{A}_n)) \ = \ \nu(p(\varphi(\mathbf{A}_1), \dots, \varphi(\mathbf{A}_n))) \ = \ \nu(\varphi(p(\mathbf{A}_1, \dots, \mathbf{A}_n))) \ = \\ \end{array}$ $\nu(\varphi(\mathbf{A}))$ **P.4.2** $\mathbf{A} = \neg \mathbf{B}$: then $\mathcal{I}_{\varphi}(\mathbf{A}) = \top$, iff $\mathcal{I}_{\varphi}(\mathbf{B}) = \nu(\varphi(\mathbf{B})) = \mathsf{F}$, iff $\nu(\varphi(\mathbf{A})) = \mathsf{F}$ Т. **P.4.3** $\mathbf{A} = \mathbf{B} \wedge \mathbf{C}$: similar

⁴EDNOTE: introduce this above

 $^{^5\}mathrm{EdNote}\colon$ I think that we only get a semivaluation, look it up in Andrews.





Model Existence			
ho Theorem 8.2.1 and $\mathcal H$ a $ abla$ -Hintik	8 (Hintikka-Lemma) If $ abla$ is a set, then $\mathcal H$ is satisfiable.	n abstract consist	ency class
⊳ Proof:			
P.1 we define $ u(A)$	$\mathbf{A}):=T, ext{ iff } \mathbf{A}\in\mathcal{H},$		
$\mathbf{P.2}$ then $ u$ is a va	luation by the Hintikka set prope	rties.	
$\mathbf{P.3}$ We have $ u(\mathcal{H}$	$)=\{T\}$, so $\mathcal H$ is satisfiable.		
$Display extbf{Theorem 8.2.1}$ and $\Phi \in abla,$ then Φ	9 (Model Existence) If ∇ is an Φ is satisfiable.	n abstract consist	ency class
Proof:			
$ ho \operatorname{\mathbf{P.1}}$ There is a $ abla$	Hintikka set ${\mathcal H}$ with $\Phi\!\subseteq\!{\mathcal H}$	(Extension	Theorem)
We know that \mathcal{H} is satisfiable. (Hintikka-Lemma)			a-Lemma)
In particular, $\Phi \subseteq \mathcal{H}$ is satisfiable. \Box			
			-
CO Some Rights frager ved	©: Michael Kohlhase	51	

8.3 A Completeness Proof for First-Order ND

With the model existence proof we have introduced in the last section, the completeness proof for first-order natural deduction is rather simple, we only have to check that ND-consistency is an abstract consistency property.

P.2 P.3 Consistency, Refutability and Abstract Consistency
▷ Theorem 8.3.1 (Non-Refutability is an Abstract Consistency Property) Γ := {Φ ⊆ cwff_o(Σ_ι) | Φ not ND¹−refutable} is an abstract consistency class.
▷ Proof: We check the properties of an ACC
P.1 If Φ is non-refutable, then any subset is as well, so Γ is closed under subsets.
P.2 We show the abstract consistency conditions ∇_{*} for Φ ∈ Γ.
P.2.1 ∇_c: We have to show that A ∉ Φ or ¬ A ∉ Φ for atomic A ∈ wff_o(Σ).



This directly yields two important results that we will use for the completeness analysis.

Henkin's Theorem
\triangleright Corollary 8.3.2 (Henkin's Theorem) Every ND^1 -consistent set of sentences has a model.
⊳ Proof:
${f P.1}$ Let Φ be a ${\cal N\!D}^1$ -consistent set of sentences.
${f P.2}$ The class of sets of $N\!D^1$ -consistent propositions constitute an abstract consistency class
P.3 Thus the model existence theorem guarantees a model for Φ .
\triangleright Corollary 8.3.3 (Löwenheim&Skolem Theorem) Satisfiable set Φ of first-order sentences has a countable model.
▷ Proof Sketch: The model we constructed is countable, since the set of ground terms is.
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Now, the completeness result for first-order natural deduction is just a simple argument away. We also get a compactness theorem (almost) for free: logical systems with a complete calculus are always compact.





8.4 Limits of First-Order Logic

We will now come to the limits of first-order Logic.⁶



EdN:6

 $^{^{6}\}mathrm{EdNOTE}$: MK: also present the theorem (whose name I forgot) that show that FOL is the "strongest logic" for first-order models. Maybe also the interpolation theorem.

Chapter 9

First-Order Inference with Tableaux

9.1 First-Order Tableaux



Tableau calculi develop a formula in a tree-shaped arrangement that represents a case analysis on when a formula can be made true (or false). Therefore the formulae are decorated with exponents that hold the intended truth value.

On the left we have a refutation tableau that analyzes a negated formula (it is decorated with the intended truth value F). Both branches contain an elementary contradiction \perp .

On the right we have a model generation tableau, which analyzes a positive formula (it is decorated with the intended truth value \top . This tableau uses the same rules as the refutation tableau, but makes a case analysis of when this formula can be satisfied. In this case we have a closed branch and an open one, which corresponds a model).

Now that we have seen the examples, we can write down the tableau rules formally.



These inference rules act on tableaux have to be read as follows: if the formulae over the line appear in a tableau branch, then the branch can be extended by the formulae or branches below the line. There are two rules for each primary connective, and a branch closing rule that adds the special symbol \perp (for unsatisfiability) to a branch.

We use the tableau rules with the convention that they are only applied, if they contribute new material to the branch. This ensures termination of the tableau procedure for propositional logic (every rule eliminates one primary connective).

Definition 9.1.4 We will call a closed tableau with the signed formula \mathbf{A}^{α} at the root a tableau refutation for \mathcal{A}^{α} .

The saturated tableau represents a full case analysis of what is necessary to give \mathbf{A} the truth value α ; since all branches are closed (contain contradictions) this is impossible.

Definition 9.1.5 We will call a tableau refutation for \mathbf{A}^{f} a tableau proof for \mathbf{A} , since it refutes the possibility of finding a model where \mathbf{A} evaluates to F . Thus \mathbf{A} must evaluate to T in all models, which is just our definition of validity.

Thus the tableau procedure can be used as a calculus for propositional logic. In contrast to the calculus in section ?sec.hilbert? it does not prove a theorem **A** by deriving it from a set of axioms, but it proves it by refuting its negation. Such calculi are called negative or test calculi. Generally negative calculi have computational advantages over positive ones, since they have a built-in sense of direction.

We have rules for all the necessary connectives (we restrict ourselves to \land and \neg , since the others can be expressed in terms of these two via the propositional identities above. For instance, we can write $\mathbf{A} \lor \mathbf{B}$ as $\neg (\neg \mathbf{A} \land \neg \mathbf{B})$, and $\mathbf{A} \Rightarrow \mathbf{B}$ as $\neg \mathbf{A} \lor \mathbf{B}, \ldots$)

We will now extend the propositional tableau techiques to first-order logic. We only have to add two new rules for the universal quantifiers (in positive and negative polarity).



The rule \mathcal{T}_1 : \forall rule operationalizes the intuition that a universally quantified formula is true, iff all of the instances of the scope are. To understand the \mathcal{T}_1 : \exists rule, we have to keep in mind that $\exists X.\mathbf{A}$ abbreviates $\neg (\forall X.\neg \mathbf{A})$, so that we have to read $\forall X.\mathbf{A}^{\mathsf{F}}$ existentially — i.e. as $\exists X.\neg \mathbf{A}^{\mathsf{T}}$, stating that there is an object with property $\neg \mathbf{A}$. In this situation, we can simply give this object a name: c, which we take from our (infinite) set of witness constants Σ_0^{sk} , which we have given ourselves expressly for this purpose when we defined first-order syntax. In other words $[c/X](\neg \mathbf{A})^{\mathsf{T}} = [c/X](\mathbf{A})^{\mathsf{F}}$ holds, and this is just the conclusion of the \mathcal{T}_1 : \exists rule.

Note that the $\mathcal{T}_1:\forall$ rule is computationally extremely inefficient: we have to guess an (i.e. in a search setting to systematically consider all) instance $\mathbf{C} \in wff_{\iota}(\Sigma_{\iota})$ for X. This makes the rule infinitely branching.

9.2 Free Variable Tableaux

In the next calculus we will try to remedy the computational inefficiency of the $\mathcal{T}_1: \forall$ rule. We do this by delaying the choice in the universal rule.



Metavariables: Instead of guessing a concrete instance for the universally quantified variable as in the \mathcal{T}_1 : \forall rule, \mathcal{T}_1^f : \forall instantiates it with a new meta-variable Y, which will be instantiated by need

in the course of the derivation.

Skolem terms as witnesses: The introduction of meta-variables makes is necessary to extend the treatment of witnesses in the existential rule. Intuitively, we cannot simply invent a new name, since the meaning of the body **A** may contain meta-variables introduced by the \mathcal{T}_1^f : \forall rule. As we do not know their values yet, the witness for the existential statement in the antecedent of the \mathcal{T}_1^f : \exists rule needs to depend on that. So witness it using a witness term, concretely by applying a Skolem function to the meta-variables in **A**.

Instantiating Metavariables: Finally, the $\mathcal{T}_1^f : \perp$ rule completes the treatment of meta-variables, it allows to instantiate the whole tableau in a way that the current branch closes. This leaves us with the problem of finding substitutions that make two terms equal.

Multiplicity in Tableaux

- $\vartriangleright \textbf{Observation 9.2.1 All } \mathcal{T}_1^f \textit{ rules except } \mathcal{T}_1^f{:} \forall \textit{ only need to be applied once.}$
- \triangleright Example 9.2.2 A tableau proof for $(p(a) \lor p(b)) \Rightarrow (\exists x.p(x)).$

Start, close branch	use \mathcal{T}_1^f : $orall$ again	
	$(p(a) \lor p(b)) \Rightarrow (\exists x \cdot p(x))^{f}$	
$(p(a) \lor p(b)) \Rightarrow (\exists x \cdot p(x))^{f}$	$p(a) \lor p(b)^{t}$	
$p(a) \lor p(b)^{t}$	$\exists x . p(x)^{\dagger}$	
$\exists x . p(x)^{f}$	$\forall x \cdot \neg p(x)^{t}$	
$\forall x \neg p(x)^{t}$	$ eg p(a)^{t}$	
$\neg p(y)^{t}$	$p(a)^{f}$	
$p(y)^{f}$	$p(a)^{t} \mid p(b)^{t}$	
$p(a)^{t} \mid p(b)^{t}$	\perp $\neg p(z)^{t}$	
$\perp : [a/x]$	$p(z)^{f}$	
	$ \cdot \hat{b}/z $	

- \triangleright **Definition 9.2.3** Let \mathcal{T} be a tableau for **A**, and a positive occurrence of $\forall x.\mathbf{B}$ in **A**, then we call the number of applications of $\mathcal{T}_1^f:\forall$ to $\forall x.\mathbf{B}$ its multiplicity.
- \triangleright Observation 9.2.4 Given a prescribed multiplicity for each positive \forall , saturation with \mathcal{T}_1^f terminates.
- \triangleright Proof Sketch: All \mathcal{T}_1^f rules reduce the number of connectives and negative \forall or the multiplicity of positive \forall .
- \triangleright Theorem 9.2.5 \mathcal{T}_1^f is only complete with unbounded multiplicities.

 \triangleright Proof Sketch: Otherwise validity in PL^1 would be decidable.

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Treating \mathcal{T}_1^f : \perp

- Dash The $\mathcal{T}_1^f : \perp$ rule instantiates the whole tableau.
- Dash There may be more than one $\mathcal{T}_1^f : \perp$ opportunity on a branch

 \triangleright Example 9.2.6 Choosing which matters – this tableau does not close!

$$\begin{aligned} \exists x \cdot (p(a) \land p(b) \Rightarrow p(x)) \land (q(b) \Rightarrow q(x))^{\mathsf{f}} \\ (p(a) \land p(b) \Rightarrow p(y)) \land (q(b) \Rightarrow q(y))^{\mathsf{f}} \\ p(a) \Rightarrow p(b) \Rightarrow p(y)^{\mathsf{f}} \\ p(a)^{\mathsf{t}} \\ p(b)^{\mathsf{t}} \\ p(y)^{\mathsf{f}} \\ \bot : [a/y] \end{aligned} | \begin{aligned} q(b) \Rightarrow q(y)^{\mathsf{f}} \\ q(b)^{\mathsf{t}} \\ q(y)^{\mathsf{f}} \end{aligned}$$

choosing the other $\mathcal{T}_1^f :\perp$ in the left branch allows closure.

 \triangleright Two ways of systematic proof search in \mathcal{T}_1^f :

 \triangleright backtracking search over \mathcal{T}_1^f : \perp opportunities

 $_{arphi}$ saturate without \mathcal{T}_{1}^{f} :ot and find spanning matings

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(later)

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9.3 First-Order Unification

We will now look into the problem of finding a substitution σ that make two terms equal (we say it unifies them) in more detail. The presentation of the unification algorithm we give here "transformation-based" this has been a very influential way to treat certain algorithms in theoretical computer science.

A transformation-based view of algorithms: The "transformation-based" view of algorithms divides two concerns in presenting and reasoning about algorithms according to Kowalski's slogan⁷

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computation = logic + control

The computational paradigm highlighted by this quote is that (many) algorithms can be thought of as manipulating representations of the problem at hand and transforming them into a form that makes it simple to read off solutions. Given this, we can simplify thinking and reasoning about such algorithms by separating out their "logical" part, which deals with is concerned with how the problem representations can be manipulated in principle from the "control" part, which is concerned with questions about when to apply which transformations.

It turns out that many questions about the algorithms can already be answered on the "logic" level, and that the "logical" analysis of the algorithm can already give strong hints as to how to optimize control.

In fact we will only concern ourselves with the "logical" analysis of unification here.

The first step towards a theory of unification is to take a closer look at the problem itself. A first set of examples show that we have multiple solutions to the problem of finding substitutions that make two terms equal. But we also see that these are related in a systematic way.



The idea behind a most general unifier is that all other unifiers can be obtained from it by (further) instantiation. In an automated theorem proving setting, this means that using most general unifiers is the least committed choice — any other choice of unifiers (that would be necessary for completeness) can later be obtained by other substitutions.

Note that there is a subtlety in the definition of the ordering on substitutions: we only compare on a subset of the variables. The reason for this is that we have defined substitutions to be total on (the infinite set of) variables for flexibility, but in the applications (see the definition of a most general unifiers), we are only interested in a subset of variables: the ones that occur in the initial problem formulation. Intuitively, we do not care what the unifiers do off that set. If we did not have the restriction to the set W of variables, the ordering relation on substitutions would become much too fine-grained to be useful (i.e. to guarantee unique most general unifiers in our case).

 $^{^7\}mathrm{EdNote:}$ find the reference, and see what he really said

Now that we have defined the problem, we can turn to the unification algorithm itself. We will define it in a way that is very similar to logic programming: we first define a calculus that generates "solved forms" (formulae from which we can read off the solution) and reason about control later. In this case we will reason that control does not matter.



In principle, unification problems are sets of equations, which we write as conjunctions, since all of them have to be solved for finding a unifier. Note that it is not a problem for the "logical view" that the representation as conjunctions induces an order, since we know that conjunction is associative, commutative and idempotent, i.e. that conjuncts do not have an intrinsic order or multiplicity, if we consider two equational problems as equal, if they are equivalent as propositional formulae. In the same way, we will abstract from the order in equations, since we know that the equality relation is symmetric. Of course we would have to deal with this somehow in the implementation (typically, we would implement equational problems as lists of pairs), but that belongs into the "control" aspect of the algorithm, which we are abstracting from at the moment.

Solved forms and Most General Unifiers \triangleright Definition 9.3.5 We call a pair $\mathbf{A} = \mathbf{B}^{?} \mathbf{B}$ solved in a unification problem \mathcal{E} , iff $\mathbf{A} = X, \mathcal{E} = X = {}^{?} \mathbf{A} \wedge \mathcal{E}, \text{ and } X \notin (\operatorname{free}(\mathbf{A}) \cup \operatorname{free}(\mathcal{E})).$ We call an unification problem \mathcal{E} a solved form, iff all its pairs are solved. \triangleright Lemma 9.3.6 Solved forms are of the form $X^1 = {}^{?} \mathbf{B}^1 \land \ldots \land X^n = {}^{?} \mathbf{B}^n$ where the X^i are distinct and $X^i \notin \text{free}(\mathbf{B}^j)$. \triangleright Definition 9.3.7 Any substitution $\sigma = [\mathbf{B}^1/X^1], \dots, [\mathbf{B}^n/X^n]$ induces a solved unification problem $\mathcal{E}_{\sigma} := (X^1 = \mathbf{B}^1 \land \dots \land X^n = \mathbf{B}^n).$ \triangleright Lemma 9.3.8 If $\mathcal{E} = X^1 = {}^? \mathbf{B}^1 \land \ldots \land X^n = {}^? \mathbf{B}^n$ is a solved form, then \mathcal{E} has the unique most general unifier $\sigma_{\mathcal{E}} := [\mathbf{B}^1/X^1], \dots, [\mathbf{B}^n/X^n].$ \triangleright **Proof**: Let $\theta \in \mathbf{U}(\mathcal{E})$ **P.1** then $\theta(X^i) = \theta(\mathbf{B}^i) = \theta \circ \sigma_{\mathcal{E}}(X^i)$ **P.2** and thus $\theta = \theta \circ \sigma_{\mathcal{E}}[\operatorname{supp}(\sigma)]$. Note: we can rename the introduced variables in most general unifiers! JACOBS UNIVERST © (C): Michael Kohlhase 65

It is essential to our "logical" analysis of the unification algorithm that we arrive at equational problems whose unifiers we can read off easily. Solved forms serve that need perfectly as Lemma 9.3.8 shows. Given the idea that unification problems can be expressed as formulae, we can express the algorithm in three simple rules that transform unification problems into solved forms (or unsolvable ones).



The decomposition rule \mathcal{U} dec is completely straightforward, but note that it transforms one unification pair into multiple argument pairs; this is the reason, why we have to directly use unification problems with multiple pairs in \mathcal{U} .

Note furthermore, that we could have restricted the \mathcal{U} triv rule to variable-variable pairs, since for any other pair, we can decompose until only variables are left. Here we observe, that constantconstant pairs can be decomposed with the \mathcal{U} dec rule in the somewhat degenerate case without arguments.

Finally, we observe that the first of the two variable conditions in \mathcal{U} elim (the "occurs-in-check") makes sure that we only apply the transformation to unifiable unification problems, whereas the second one is a termination condition that prevents the rule to be applied twice.

The notion of completeness and correctness is a bit different than that for calculi that we compare to the entailment relation. We can think of the "logical system of unifiability" with the model class of sets of substitutions, where a set satisfies an equational problem \mathcal{E} , iff all of its members are unifiers. This view induces the soundness and completeness notions presented above.

The three meta-properties above are relatively trivial, but somewhat tedious to prove, so we leave the proofs as an exercise to the reader.

We now fortify our intuition about the unification calculus by two examples. Note that we only need to pursue one possible \mathcal{U} derivation since we have confluence.

Unification Examples

Example 9.3.14 Two similar unification problems:



We will now convince ourselves that there cannot be any infinite sequences of transformations in \mathcal{U} . Termination is an important property for an algorithm.

The proof we present here is very typical for termination proofs. We map unification problems into a partially ordered set $\langle S, \prec \rangle$ where we know that there cannot be any infinitely descending sequences (we think of this as measuring the unification problems). Then we show that all transformations in \mathcal{U} strictly decrease the measure of the unification problems and argue that if there were an infinite transformation in \mathcal{U} , then there would be an infinite descending chain in S, which contradicts our choice of $\langle S, \prec \rangle$.

The crucial step in in coming up with such proofs is finding the right partially ordered set. Fortunately, there are some tools we can make use of. We know that $\langle \mathbb{N}, < \rangle$ is terminating, and there are some ways of lifting component orderings to complex structures. For instance it is wellknown that the lexicographic ordering lifts a terminating ordering to a terminating ordering on finite-dimensional Cartesian spaces. We show a similar, but less known construction with multisets for our proof.

Unification (Termination) \triangleright Definition 9.3.15 Let S and T be multisets and \prec a partial ordering on $S \cup T$. Then we define $(S \prec^m T)$, iff $S = C \uplus T'$ and $T = C \uplus \{t\}$, where $s \prec t$ for all $s \in S'$. We call \prec^m the multiset ordering induced by \prec .

 \triangleright Lemma 9.3.16 If \prec is total/terminating on S, then \prec^m is total/terminating on $\mathcal{P}(S)$.

ho Lemma 9.3.17 ${\cal U}$ is terminating

(any *U*-derivation is finite)

 \rhd Proof: We prove termination by mapping ${\cal U}$ transformation into a Noetherian space.

P.1 Let $\mu(\mathcal{E}) := \langle n, \mathcal{N} \rangle$, where

 $\triangleright m$ is the number of unsolved variables in ${\cal E}$

 $\triangleright \mathcal{N}$ is the multiset of term depths in \mathcal{E}

- **P.2** The lexicographic order \prec on pairs $\mu(\mathcal{E})$ is decreased by all inference rules.
- $\mathbf{P.2.1}~\mathcal{U}~\mathrm{dec}$ and $\mathcal{U}~\mathrm{triv}$ decrease the multiset of term depths without increasing the unsolved variables



But it is very simple to create terminating calculi, e.g. by having no inference rules. So there is one more step to go to turn the termination result into a decidability result: we must make sure that we have enough inference rules so that any unification problem is transformed into solved form if it is unifiable.



9.4 Efficient Unification

Complexity of Unification $\triangleright \text{ Observation: Naive unification is exponential in time and space.}$ $\triangleright \text{ consider the terms}$ $s_n = f(f(x_0, x_0), f(f(x_1, x_1), f(\dots, f(x_{n-1}, x_{n-1})) \dots))$ $t_n = f(x_1, f(x_2, f(x_3, f(\dots, x_n) \dots)))$ $\triangleright \text{ The most general unifier of } s_n \text{ and } t_n \text{ is}$ $[f(x_0, x_0)/x_1], [f(f(x_0, x_0), f(x_0, x_0))/x_2], [f(f(f(x_0, x_0), f(x_0, x_0)), f(f(x_0, x_0, f(x_0, x_0)))/x_3], \dots$ $\triangleright \text{ it contains } \sum_{i=1}^n 2^i = 2^{n+1} - 2 \text{ occurrences of the variable } x_0. \text{ (exponential)}$



Directed Acyclic Graphs (DAGs)

 \vartriangleright use directed acyclic graphs for the term representation

- ▷ variables my only occur once in the DAG
- ▷ subterms can be referenced multiply
- > Observation 9.4.1 Terms can be transformed into DAGs in linear time





DAG Unification Algorithm

- \triangleright Definition 9.4.3 We say that $X^1 = {}^{?} \mathbf{B}^1 \land \ldots \land X^n = {}^{?} \mathbf{B}^n$ is a DAG solved form, iff the X^i are distinct and $X^i \notin \text{free}(\mathbf{B}^j)$ for $i \leq j$
- \triangleright **Definition 9.4.4** The inference system \mathcal{DU} contains rules \mathcal{U} dec and \mathcal{U} triv from \mathcal{U} plus the following:

$$\frac{\mathcal{E} \wedge X = {}^{?} \mathbf{A} \wedge X = {}^{?} \mathbf{B} \ \mathbf{A}, \mathbf{B} \notin \mathcal{V}_{\iota} \ |\mathbf{A}| \leq |\mathbf{B}|}{\mathcal{E} \wedge X = {}^{?} \mathbf{A} \wedge \mathbf{A} = {}^{?} \mathbf{B}} \mathcal{D}\mathcal{U} \text{ merge}$$

$$\frac{\mathcal{E} \wedge X = {}^{?} Y \quad X \neq Y \quad X, Y \in \operatorname{free}(\mathcal{E})}{[Y/X](\mathcal{E}) \wedge X = {}^{?} Y} \mathcal{D}\mathcal{U} \text{ evar}$$

where $|\mathbf{A}|$ is the number of symbols in \mathbf{A} .

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Unification by DAG-chase



Algorithm unify

 \triangleright Input: symmetric pairs of nodes in DAGs

- \rhd linear in space, since no new nodes are created, and at most one link per variable.
- \triangleright consider terms $f(s_n, f(t'_n, x_n)), f(t_n, f(s'_n, y_n)))$, where $s'_n = [y_i/x_i](s_n)$ und $t'_n = [y_i/x_i](t_n)$.

 \triangleright unify needs exponentially many recursive calls to unify the nodes x_n and y_n . (they are unified after n calls, but checking needs the time)

 \triangleright Idea: Also bind the function nodes, if the arguments are unified.

 $\begin{array}{l} \text{unify}(n.f,m.g) = \text{if } g! = f \text{ then false} \\ \text{else union}(n,m); \\ \text{forall } (i,j) => \text{unify}(\text{find}(i),\text{find}(j)) \text{ (chld } m,\text{chld } n) \\ \text{end} \end{array}$

- > this only needs linearly many recursive calls as it directly returns with true or makes a node inaccessible for find.
- \triangleright linearly many calls to linear procedures give quadratic runtime.

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Spanning Matings for \mathcal{T}_1^f : ot

- \triangleright **Observation 9.4.5** \mathcal{T}_1^f without $\mathcal{T}_1^f : \perp$ is terminating and confluent for given multiplicities.
- \triangleright Idea: Saturate without \mathcal{T}_1^f : \perp and treat all cuts at the same time.
- $$\begin{split} & \mathbf{Definition} \ \mathbf{9.4.6} \ \mathsf{Let} \ \mathcal{T} \ \mathsf{be} \ \mathsf{a} \ \mathcal{T}_1^f \ \mathsf{tableau}, \ \mathsf{then} \ \mathsf{we} \ \mathsf{call} \ \mathsf{a} \ \mathsf{unification} \ \mathsf{problem} \\ & \mathcal{E} := (\mathbf{A}_1 = \stackrel{?}{\cdot} \mathbf{A}_1 \wedge \ldots \wedge \mathbf{A}_n = \stackrel{?}{\cdot} \mathbf{B}_n) \ \mathsf{a} \ \mathsf{mating} \ \mathsf{for} \ \mathcal{T}, \ \mathsf{iff} \ \mathbf{A}_i^t \ \mathsf{and} \ \mathbf{B}_i^f \ \mathsf{occur} \ \mathsf{in} \ \mathcal{T}. \end{split}$$



Now that we understand basic unification theory, we can come to the meta-theoretical properties of the tableau calculus, which we now discuss to make the understanding of first-order inference complete.

9.5 Soundness and Completeness of First-Order Tableaux

For the soundness result, we recap the definition of soundness for test calculi from the propositional case.

Soundness	(Tableau)		
⊳ Idea: A tes are unsatisf	t calculus is sound, iff it preserves satis iable.	fiability and the goal	formulae
\triangleright Definition	${f n}$ ${f 9.5.1}$ A labeled formula ${f A}^lpha$ is valid	d under $arphi$, iff $\mathcal{I}_arphi(\mathbf{A})$	$= \alpha$.
$Descript{Definition} \mathcal{P}$ in \mathcal{T} , i.e.	${f n}\; {f 9.5.2} \; {f A}\; {f tableau}\; {\cal T}$ is satisfiable, if if the set of formulae in ${\cal P}$ is satisfia	f there is a satisfiabl ble.	e branch
Demma 9.5.3 Tableau rules transform satisfiable tableaux into satisfiable ones.			
⊳ Theorem there is a ci	9.5.4 (Soundness) A set Φ of pro- losed tableau $\mathcal T$ for Φ^{f} .	positional formulae is	s valid, if
\triangleright Proof : by c	contradiction: Suppose Φ is not valid.		
${f P.1}$ then th ${f P.2}$ so ${\cal T}$ is	e initial tableau is satisfiable satisfiable, by Lemma 9.5.3.	$(\Phi^{f}$ sa	tisfiable)
$\mathbf{P.3}$ there is	a satisfiable branch	(by d	efinition)
$\mathbf{P.4}$ but all	branches are closed	(7	⊂ closed)
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Thus we only have to prove Lemma 9.5.3, this is relatively easy to do. For instance for the first rule: if we have a tableau that contains $\mathbf{A} \wedge \mathbf{B}^{t}$ and is satisfiable, then it must have a satisfiable branch. If $\mathbf{A} \wedge \mathbf{B}^{t}$ is not on this branch, the tableau extension will not change satisfiability, so we

can assue that it is on the satisfiable branch and thus $\mathcal{I}_{\varphi}(\mathbf{A} \wedge \mathbf{B}) = \mathsf{T}$ for some variable assignment φ . Thus $\mathcal{I}_{\varphi}(\mathbf{A}) = \mathsf{T}$ and $\mathcal{I}_{\varphi}(\mathbf{B}) = \mathsf{T}$, so after the extension (which adds the formulae \mathbf{A}^{t} and \mathbf{B}^{t} to the branch), the branch is still satisfiable. The cases for the other rules are similar.

The soundness of the first-order free-variable tableaux calculus can be established a simple induction over the size of the tableau.



The only interesting steps are the cut rule, which can be directly handled by the substitution value lemma, and the rule for the existential quantifier, which we do in a separate lemma.

Soundness of \mathcal{T}_{1}^{f} : \exists \triangleright Lemma 9.5.7 \mathcal{T}_{1}^{f} : \exists transforms satisfiable tableaux into satisfiable ones. \triangleright Proof: Let \mathcal{T}' be obtained by applying \mathcal{T}_{1}^{f} : \exists to $\forall X \cdot \mathbf{A}^{f}$ in \mathcal{T} , extending it with $[f(X^{1}, ..., X^{n})/X](\mathbf{A})^{f}$, where $W := \text{free}(\forall X \cdot \mathbf{A}) = \{X^{1}, ..., X^{k}\}$ P.1 Let \mathcal{T} be satisfiable in $\mathcal{M} := \langle \mathcal{D}, \mathcal{I} \rangle$, then $\mathcal{I}_{\varphi}(\forall X \cdot \mathbf{A}) = \mathsf{F}$. P.2 We need to find a model \mathcal{M}' that satisfies \mathcal{T}' (find interpretation for f) P.3 By definition $\mathcal{I}_{\varphi,[a/X]}(\mathbf{A}) = \mathsf{F}$ for some $a \in \mathcal{D}$ (depends on $\varphi|_{W}$) P.4 Let $g: \mathcal{D}^{k} \to \mathcal{D}$ be defined by $g(a_{1}, ..., a_{k}) := a$, if $\varphi(X^{i}) = a_{i}$ P.5 choose $\mathcal{M}' = \langle \mathcal{D}, \mathcal{I}' \rangle$ with $\mathcal{I}' := \mathcal{I}, [g/f]$, then by subst. value lemma $\mathcal{I}'_{\varphi}([f(X^{1}, ..., X^{k})/X](\mathbf{A})) = \mathcal{I}'_{\varphi, [\mathcal{I}'_{\varphi}(f(X^{1}, ..., X^{k}))/X]}(\mathbf{A}))$ $= \mathcal{I}'_{\varphi, [a/X]}(\mathbf{A}) = \mathsf{F}$

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This proof is paradigmatic for soundness proofs for calculi with Skolemization. We use the axiom of choice at the meta-level to choose a meaning for the Skolem function symbol.

Armed with the Model Existence Theorem for first-order logic (Theorem 8.2.19), the completeness of first-order tableaux is similarly straightforward. We just have to show that the collection of tableau-irrefutable sentences is an abstract consistency class, which is a simple prooftransformation exercise in all but the universal quantifier case, which we postpone to its own Lemma.



So we only have to treat the case for the universal quantifier. This is what we usually call a "lifting argument", since we have to transform ("lift") a proof for a formula $\theta(\mathbf{A})$ to one for \mathbf{A} . In the case of tableaux we do that by an induction on the tableau refutation for $\theta(\mathbf{A})$ which creates a tableau-isomorphism to a tableau refutation for \mathbf{A} .

Tableau-Lifting

- \triangleright **Theorem 9.5.9** If \mathcal{T}_{θ} is a closed tableau for a st $\theta(\Phi)$ of formulae, then there is a closed tableau \mathcal{T} for Φ .
- \triangleright Proof: by induction over the structure of \mathcal{T}_{θ} we build an isomorphic tableau \mathcal{T} , and a tableau-isomorphism $\omega \colon \mathcal{T} \to \mathcal{T}_{\theta}$, such that $\omega(\mathbf{A}) = \theta(\mathbf{A})$.

P.1 only the tableau-substitution rule is interesting.

- **P.2** Let $\theta(\mathbf{A}^i)^{\mathsf{t}}$ and $\theta(\mathbf{B}^i)^{\mathsf{f}}$ cut formulae in the branch Θ^i_{θ} of \mathcal{T}_{θ}
- **P.3** there is a joint unifier σ of $\theta(\mathbf{A}^1) = \theta(\mathbf{B}^1) \land \ldots \land \theta(\mathbf{A}^n) = \theta(\mathbf{B}^n)$
- $\mathbf{P.4}$ thus $\sigma\circ\theta$ is a unifier of \mathbf{A} and \mathbf{B}

P.5 hence there is a most general unifier ρ of $\mathbf{A}^1 = {}^? \mathbf{B}^1 \land \ldots \land \mathbf{A}^n = {}^? \mathbf{B}^n$

P.6 so Θ is closed

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Again, the "lifting lemma for tableaux" is paradigmatic for lifting lemmata for other refutation calculi.

Part III

Higher-Order Logic and λ -Calculus

In this Part we set the stage for a deeper discussions of the logical foundations of mathematics by introducing a particular higher-order logic, which gets around the limitations of first-order logic — the restriction of quantification to individuals. This raises a couple of questions (paradoxes, comprehension, completeness) that have been very influential in the development of the logical systems we know today.

Therefore we use the discussion of higher-order logic as an introduction and motivation for the λ -calculus, which answers most of these questions in a term-level, computation-friendly system.

The formal development of the simply typed λ -calculus and the establishment of its (metalogical) properties will be the body of work in this Part. Once we have that we can reconstruct a clean version of higher-order logic by adding special provisions for propositions.

Chapter 10

Higher-Order Predicate Logic

The main motivation for higher-order logic is to allow quantification over classes of objects that are not individuals — because we want to use them as functions or predicates, i.e. apply them to arguments in other parts of the formula.

Higher-Order Predicate Logic (PL Ω)> Quantification over functions and Predicates: $\forall P.\exists F.P(a) \lor \neg P(F(a))$ > Comprehension: (Existence of Functions) $\exists F.\forall X.FX = \mathbf{A}$ e.g. $f(x) = 3x^2 + 5x - 7$ > Extensionality: (Equality of functions and truth values) $\forall F.\forall G.(\forall X.FX = GX) \Rightarrow F = G$ $\forall P.\forall Q.(P \Leftrightarrow Q) \Leftrightarrow P = Q$ > Leibniz Equality: (Indiscernability) $\mathbf{A} = \mathbf{B}$ for $\forall P.P\mathbf{A} \Rightarrow P\mathbf{B}$ ©: Michael Kohlhase

Indeed, if we just remove the restriction on quantification we can write down many things that are essential on everyday mathematics, but cannot be written down in first-order logic. But the naive logic we have created (BTW, this is essentially the logic of Frege [Fre79]) is much too expressive, it allows us to write down completely meaningless things as witnessed by Russell's paradox.

Problems with PL Ω \triangleright Problem: Russell's Antinomy: $\forall Q.\mathcal{M}(Q) \Leftrightarrow \neg Q(Q)$ \triangleright the set \mathcal{M} of all sets that do not contain themselves \triangleright Question: Is $\mathcal{M} \in \mathcal{M}$? Answer: $\mathcal{M} \in \mathcal{M}$ iff $\mathcal{M} \notin \mathcal{M}$. \triangleright What has happened? the predicate Q has been applied to itself \triangleright Solution for this course: Forbid self-applications by types!! $\triangleright \iota, o$ (type of individuals, truth values), $\alpha \to \beta$ (function type) \triangleright right associative bracketing: $\alpha \to \beta \to \gamma$ abbreviates $\alpha \to (\beta \to \gamma)$



The solution to this problem turns out to be relatively simple with the benefit of hindsight: we just introduce a syntactic device that prevents us from writing down paradoxical formulae. This idea was first introduced by Russell and Whitehead in their Principia Mathematica [WR10].

Their system of "ramified types" was later radically simplified by Alonzo Church to the form we use here in [Chu40]. One of the simplifications is the restriction to unary functions that is made possible by the fact that we can re-interpret binary functions as unary ones using a technique called "Currying" after the Logician Haskell Brooks Curry (*1900, †1982). Of course we can extend this to higher arities as well. So in theory we can consider *n*-ary functions as syntactic sugar for suitable higher-order functions. The vector notation for types defined above supports this intuition.

Types

> Types are semantic annotations for terms that prevent antinomies
> Definition 10.0.1 Given a set β T of base types, construct function types: α → β is the type of functions with domain type α and range type β. We call the closure T of B T under function types the set of types over B T.
> Definition 10.0.2 We will use ι for the type of individuals and o for the type of truth values.
> The type constructor is used as a right-associative operator, i.e. we use α → β → γ as an abbreviation for α → (β → γ)
> We will use a kind of vector notation for function types, abbreviating α₁ → ... → α_n - β with α_n → β.

Armed with a system of types, we can now define a typed higher-order logic, by insisting that all formulae of this logic be well-typed. One advantage of typed logics is that the natural classes of objects that have otherwise to be syntactically kept apart in the definition of the logic (e.g. the term and proposition levels in first-order logic), can now be distinguished by their type, leading to a much simpler exposition of the logic. Another advantage is that concepts like connectives that were at the language level e.g. in PL^0 , can be formalized as constants in the signature, which again makes the exposition of the logic more flexible and regular. We only have to treat the quantifiers at the language level (for the moment).

Well-Typed Formulae (PL Ω) \triangleright signature $\Sigma = \bigcup_{\alpha \in \mathcal{T}} \Sigma_{\alpha}$ with \triangleright connectives: $\neg \in \Sigma_{o \to o}$ { $\forall , \land, \Rightarrow, \Leftrightarrow \ldots$ } $\subseteq \Sigma_{o \to o \to o}$ \triangleright variables $\mathcal{V}_{\mathcal{T}} = \bigcup_{\alpha \in \mathcal{T}} \mathcal{V}_{\alpha}$, such that every \mathcal{V}_{α} countably infinite.



The semantics is similarly regular: We have universes for every type, and all functions are "typed functions", i.e. they respect the types of objects. Other than that, the setup is very similar to what we already know.



We now go through a couple of examples of what we can express in $PL\Omega$, and that works out very straightforwardly. For instance, we can express equality in $PL\Omega$ by Leibniz equality, and it has the right meaning.

Equality

- \triangleright "Leibniz equality" (Indiscernability) $\mathbf{Q}^{\alpha}\mathbf{A}_{\alpha}\mathbf{B}_{\alpha} = \forall P_{\alpha \to o} \cdot P\mathbf{A} \Leftrightarrow P\mathbf{B}$
- \triangleright not that $\forall P_{\alpha \to o} \cdot P \mathbf{A} \Rightarrow P \mathbf{B}$ (get the other direction by instantiating P with Q, where $QX \Leftrightarrow \neg PX$)
- \triangleright Theorem 10.0.6 If $\mathcal{M} = \langle \mathcal{D}, \mathcal{I} \rangle$ is a standard model, then $\mathcal{I}_{\varphi}(\mathbf{Q}^{lpha})$ is the



Another example are the Peano Axioms for the natural numbers, though we omit the proofs of adequacy of the axiomatization here.

Example: Peano Axioms for the Natural Numbers $\triangleright \Sigma = \{ [\mathbb{N} : \iota \to o], [0 : \iota], [s : \iota \to \iota] \}$ $\triangleright \mathbb{N}0$ (0 is a natural number) $\vartriangleright \forall X_{\iota} . \mathbb{N}X \Rightarrow \mathbb{N}(sX)$ (the successor of a natural number is natural) $\rhd \neg (\exists X_{\iota} \, \mathbb{N} X \land sX = 0)$ (0 has no predecessor) $\triangleright \forall X_{\iota} \forall Y_{\iota} (sX = sY) \Rightarrow X = Y$ (the successor function is injective) $\triangleright \forall P_{\iota \to o} \cdot P0 \Rightarrow (\forall X_{\iota} \cdot \mathbb{N}X \Rightarrow PX \Rightarrow P(sX)) \Rightarrow (\forall Y_{\iota} \cdot \mathbb{N}Y \Rightarrow P(Y))$ induction axiom: all properties P, that hold of 0, and with every n for its successor s(n), hold on all \mathbb{N} JACOBS (C): Michael Kohlhase 87

Finally, we show the expressivity of $PL\Omega$ by formalizing a version of Cantor's theorem.

Expressive Formalism for Mathematics $\triangleright \text{ Example 10.0.8 (Cantor's Theorem) The cardinality of a set is smaller$ than that of its power set. $<math display="block">\triangleright \text{ smaller-card}(M, N) := \neg (\exists F. \text{surjective}(F, M, N))$ $\triangleright \text{ surjective}(F, M, N) := (\forall X \in M. \exists Y \in N. FY = X)$ $\triangleright \text{ Example 10.0.9 (Simplified Formalization)} \neg (\exists F_{\iota \to \iota \to \iota}. \forall G_{\iota \to \iota}. \exists J_{\iota}. FJ = G)$ $\triangleright \text{ Standard-Benchmark for higher-order theorem provers}$



The simplified formulation of Cantor's theorem in Example 10.0.9 uses the universe of type ι for the set S and universe of type $\iota \to \iota$ for the power set rather than quantifying over S explicitly. The next concern is to find a calculus for PL Ω .

We start out with the simplest one we can imagine, a Hilbert-style calculus that has been adapted to higher-order logic by letting the inference rules range over $PL\Omega$ formulae and insisting that substitutions are well-typed.



Not surprisingly, \mathcal{H}_{Ω} is sound, but it shows big problems with completeness. For instance, if we turn to a proof of Cantor's theorem via the well-known diagonal sequence argument, we will have to construct the diagonal sequence as a function of type $\iota \to \iota$, but up to now, we cannot in \mathcal{H}_{Ω} . Unlike mathematical practice, which silently assumes that all functions we can write down in closed form exists, in logic, we have to have an axiom that guarantees (the existence of) such a function: the comprehension axioms.

Hilbert-Calculus \mathcal{H}_{Ω} (continued) \triangleright valid sentences that are not \mathcal{H}_{Ω} -theorems: ▷ Cantor's Theorem: $\neg (\exists F_{\iota \to \iota \to \iota} \, \cdot \, \forall G_{\iota \to \iota} \, \cdot \, (\forall K_\iota \, \cdot \, (\mathbb{N}K) \Rightarrow \mathbb{N}(GK)) \Rightarrow (\exists J_\iota \, \cdot \, (\mathbb{N}J) \land FJ = G))$ (There is no surjective mapping from ${\mathbb N}$ into the set ${\mathcal F}({\mathbb N};,)\,{\mathbb N}$ of natural number sequences) \triangleright proof attempt fails at the subgoal $\exists G_{\iota \to \iota}, \forall X_{\iota}, GX = s(fXX)$ \triangleright Comprehension $\exists F_{\alpha \to \beta} . \forall X_{\alpha} . FX = \mathbf{A}_{\beta}$ (for every variable X_{α} and every term $\mathbf{A} \in wff_{\beta}(\Sigma, \mathcal{V}_{\mathcal{T}})$) \triangleright extensionality $\mathbf{Ext}^{\alpha\,\beta}$ $\forall F_{\alpha \to \beta} \; \forall G_{\alpha \to \beta} \; (\forall X_{\alpha} \; FX = GX) \Rightarrow F = G$ $\forall F_o, \forall G_o, (F \Leftrightarrow G) \Leftrightarrow F = G$ $\mathbf{Ext}^{\mathbf{o}}$ complete? cannot be!! [Göd31] \triangleright correct!

Actually it turns out that we need more axioms to prove elementary facts about mathematics: the extensionality axioms. But even with those, the calculus cannot be complete, even though empirically it proves all mathematical facts we are interested in.

 Way Out: Henkin-Semantics

 ▷ Gödel's incompleteness theorem only holds for standard semantics

 ▷ find generalization that admits complete calculi:

 ▷ Idea: generalize so that the carrier only contains those functions that are requested by the comprehension axioms.

 ▷ Theorem 10.0.13 (Henkin 1950) H_Ω is complete wrt. this semantics.

 ▷ Proof Sketch: more models ~> less valid sentences (these are H_Ω-theorems)

 □

 ▷ Henkin-models induce sensible measure of completeness for higher-order logic.

Actually, there is another problem with PL Ω : The comprehension axioms are computationally very problematic. First, we observe that they are equality axioms, and thus are needed to show that two objects of PL Ω are equal. Second we observe that there are countably infinitely many of them (they are parametric in the term **A**, the type α and the variable name), which makes dealing with them difficult in practice. Finally, axioms with both existential and universal quantifiers are always difficul to reason with.

Therefore we would like to have a formulation of higher-order logic without comprehension axioms. In the next slide we take a close look at the comprehension axioms and transform them into a form without quantifiers, which will turn out useful.

From Comprehension to β -Conversion $\exists F_{\alpha \to \beta} . \forall X_{\alpha} . FX = \mathbf{A}_{\beta} \text{ for arbitrary variable } X_{\alpha} \text{ and term } \mathbf{A} \in wff_{\beta}(\Sigma, \mathcal{V}_{T}) \text{ (for each term } \mathbf{A} \text{ and each variable } X \text{ there is a function } f \in \mathcal{D}_{\alpha \to \beta}, \text{ with } f(\varphi(X)) = \mathcal{I}_{\varphi}(\mathbf{A}))$ $\triangleright \text{ schematic in } \alpha, \beta, X_{\alpha} \text{ and } \mathbf{A}_{\beta}, \text{ very inconvenient for deduction}$ $\triangleright \text{ Transformation in } \mathcal{H}_{\Omega}$ $\triangleright \exists F_{\alpha \to \beta} . \forall X_{\alpha} . FX = \mathbf{A}_{\beta}$ $\triangleright \forall X_{\alpha} . (\lambda X_{\alpha} . \mathbf{A})X = \mathbf{A}_{\beta} (\exists E)$ Call the function F whose existence is guaranteed " $(\lambda X_{\alpha} . \mathbf{A})$ " $\triangleright (\lambda X_{\alpha} . \mathbf{A})\mathbf{B} = [\mathbf{B}/X]\mathbf{A}_{\beta} (\forall E), \text{ in particular for } \mathbf{B} \in wff_{\alpha}(\Sigma, \mathcal{V}_{T}).$ $\triangleright \text{ Definition 10.0.14 Axiom of } \beta\text{-equality: } (\lambda X_{\alpha} . \mathbf{A})\mathbf{B} = [\mathbf{B}/X](\mathbf{A}_{\beta})$ $\triangleright \text{ new formulae } (\lambda\text{-calculus [Church 1940]})$


In a similar way we can treat (functional) extensionality.

From Extensionality to η -Conversion \triangleright Definition 10.0.15 Extensionality Axiom: $\forall F_{\alpha \to \beta} . \forall G_{\alpha \to \beta} . (\forall X_{\alpha} . FX = GX) \Rightarrow F = G$ \triangleright Idea: Maybe we can get by with a simplified equality schema here as well. \triangleright Definition 10.0.16 We say that A and λX_{α} . AX are η -equal, (write $A_{\alpha \to \beta} =_{\eta}$ $(\lambda X_{\alpha} \cdot \mathbf{A}X)$, if), iff $X \notin \text{free}(\mathbf{A})$. \triangleright Theorem 10.0.17 η -equality and Extensionality are equivalent \triangleright **Proof**: We show that η -equality is special case of extensionality; the converse entailment is trivial **P.1** Let $\forall X_{\alpha}$. $\mathbf{A}X = \mathbf{B}X$, thus $\mathbf{A}X = \mathbf{B}X$ with $\forall E$ **P.2** λX_{α} **A** $X = \lambda X_{\alpha}$ **B**X, therefore **A** = **B** with η **P.3** Hence $\forall F_{\alpha \to \beta}$, $\forall G_{\alpha \to \beta}$, $(\forall X_{\alpha}, FX = GX) \Rightarrow F = G$ by twice $\forall I$. \triangleright Axiom of truth values: $\forall F_o \ \forall G_o \ (F \Leftrightarrow G) \Leftrightarrow F = G$ unsolved. JACOBS UNIVERSI **ि** मण्डाव्यात्वाः (C): Michael Kohlhase 93

The price to pay is that we need to pay for getting rid of the comprehension and extensionality axioms is that we need a logic that systematically includes the λ -generated names we used in the transformation as (generic) witnesses for the existential quantifier. Alonzo Church did just that with his "simply typed λ -calculus" which we will introduce next.

Chapter 11

Simply Typed λ -Calculus

In this section we will present a logic that can deal with functions – the simply typed λ -calculus. It is a typed logic, so everything we write down is typed (even if we do not always write the types down).

Simply typed λ -Calculus (Syntax) $\triangleright \text{ Signature } \Sigma = \bigcup_{\alpha \in \mathcal{T}} \Sigma_{\alpha} \text{ (includes countably infinite Signatures } \Sigma_{\alpha}^{Sk} \text{ of Skolem}$ contants). $\triangleright \mathcal{V}_{\mathcal{T}} = \bigcup_{\alpha \in \mathcal{T}} \mathcal{V}_{\alpha}$, such that \mathcal{V}_{α} are countably infinite \triangleright Definition 11.0.1 We call the set $wff_{\alpha}(\Sigma, \mathcal{V}_{\mathcal{T}})$ defined by the rules $\triangleright \mathcal{V}_{\alpha} \cup \Sigma_{\alpha} \subseteq wff_{\alpha}(\Sigma, \mathcal{V}_{\mathcal{T}})$ $\triangleright \text{ If } \mathbf{C} \in wf\!f_{\alpha \to \beta}(\Sigma, \mathcal{V}_{\mathcal{T}}) \text{ and } \mathbf{A} \in wf\!f_{\alpha}(\Sigma, \mathcal{V}_{\mathcal{T}}) \text{, then } (\mathbf{CA}) \in wf\!f_{\beta}(\Sigma, \mathcal{V}_{\mathcal{T}})$ $\triangleright \text{ If } \mathbf{A} \in wf\!f_{\alpha}(\Sigma, \mathcal{V}_{\mathcal{T}}) \text{, then } (\lambda X_{\beta} \cdot \mathbf{A}) \in wf\!f_{\beta \to \alpha}(\Sigma, \mathcal{V}_{\mathcal{T}})$ the set of well-typed formula e of type α over the signature Σ and use $w\!f\!f_{\mathcal{T}}(\Sigma, \mathcal{V}_{\mathcal{T}}) :=$ \triangleright Definition 11.0.2 We will call all occurrences of the variable X in A bound in $\lambda X \cdot A$. Variables that are not bound in **B** are called free in **B**. \triangleright Substitutions are well-typed, i.e. $\sigma(X_{\alpha}) \in wff_{\alpha}(\Sigma, \mathcal{V}_{\mathcal{T}})$ and capture-avoiding. \triangleright Definition 11.0.3 (Simply Typed λ -Calculus) The simply typed λ -calculus Λ^{\rightarrow} over a signature Σ has the formulae $wff_{\tau}(\Sigma, \mathcal{V}_{\tau})$ (they are called λ -terms) and the following equalities: $\triangleright \alpha$ conversion: $(\lambda X \cdot \mathbf{A}) =_{\alpha} (\lambda Y \cdot [Y/X](\mathbf{A}))$ $\triangleright \beta$ conversion: $(\lambda X \cdot \mathbf{A})\mathbf{B} =_{\beta} [\mathbf{B}/X](\mathbf{A})$ $\triangleright \eta$ conversion: $(\lambda X \cdot AX) =_{\eta} A$ œ JACOBS UNIVERST (C): Michael Kohlhase 94

The intuitions about functional structure of λ -terms and about free and bound variables are encoded into three transformation rules Λ^{\rightarrow} : The first rule (α -conversion) just says that we can rename bound variables as we like. β -conversion codifies the intuition behind function application by replacing bound variables with argument. The equality relation induced by the η -reduction is a special case of the extensionality principle for functions (f = g iff f(a) = g(a) for all possible arguments a): If we apply both sides of the transformation to the same argument – say **B** and then we arrive at the right hand side, since $(\lambda X_{\alpha} \cdot \mathbf{A}X)\mathbf{B} =_{\beta} \mathbf{AB}$.

We will use a set of bracket elision rules that make the syntax of Λ^{\rightarrow} more palatable. This makes Λ^{\rightarrow} expressions look much more like regular mathematical notation, but hides the internal structure. Readers should make sure that they can always reconstruct the brackets to make sense of the syntactic notions below.



Intuitively, $\lambda X \cdot \mathbf{A}$ is the function f, such that $f(\mathbf{B})$ will yield \mathbf{A} , where all occurrences of the formal parameter X are replaced by $\mathbf{B}^{.8}$

EdN:8

In this presentation of the simply typed λ -calculus we build-in α -equality and use capture-avoiding substitutions directly. A clean introduction would followed the steps in Chapter 6 by introducing substitutions with a substitutability condition like the one in Definition 7.2.10, then establishing the soundness of α conversion, and only then postulating defining capture-avoiding substitution application as in Definition 7.3.3. The development for Λ^{\rightarrow} is directly parallel to the one for PL¹, so we leave it as an exercise to the reader and turn to the computational properties of the λ -calculus.

Computationally, the λ -calculus obtains much of its power from the fact that two of its three equalities can be oriented into a reduction system. Intuitively, we only use the equalities in one direction, i.e. in one that makes the terms "simpler". If this terminates (and is confluent), then we can establish equality of two λ -terms by reducing them to normal forms and comparing them structurally. This gives us a decision procedure for equality. Indeed, we have these properties in Λ^{\rightarrow} as we will see below.

 $\alpha \beta \eta - \text{Equality (Overview)}$ $\triangleright \text{ reduction with } \begin{cases} \beta : (\lambda X \cdot \mathbf{A}) \mathbf{B} \rightarrow_{\beta} [\mathbf{B}/X](\mathbf{A}) \\ \eta : (\lambda X \cdot \mathbf{A}X) \rightarrow_{\eta} \mathbf{A} \end{cases} \text{ under } =_{\alpha} : \begin{cases} \lambda X \cdot \mathbf{A} \\ =_{\alpha} \\ \lambda Y \cdot [Y/X](\mathbf{A}) \end{cases}$ $\triangleright \text{ Theorem 11.0.7 } \beta \eta \text{-reduction is well-typed, terminating and confluent in the presence of } =_{\alpha} \text{-conversion.}$

 \rhd Definition 11.0.8 (Normal Form) We call a $\lambda\text{-term}~\mathbf{A}$ a normal form (in

⁸EDNOTE: rationalize the semantic macros for syntax!

a reduction system ${\mathcal E}$), iff no rule (from ${\mathcal E}$) can be applied to ${f A}.$

 \triangleright Corollary 11.0.9 $\beta\eta$ -reduction yields unique normal forms (up to α -equivalence).

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We will now introduce some terminology to be able to talk about λ -terms and their parts.



 η long forms are structurally convenient since for them, the structure of the term is isomorphic to the structure of its type (argument types correspond to binders): if we have a term **A** of type $\overline{\alpha_n} \to \beta$ in η -long form, where $\beta \in \mathcal{B} \mathcal{T}$, then **A** must be of the form $\lambda \overline{X_{\alpha}}^n$. **B**, where **B** has type β . Furthermore, the set of η -long forms is closed under β -equality, which allows us to treat the two equality theories of Λ^{\rightarrow} separately and thus reduce argumentational complexity.

Chapter 12

Computational Properties of λ -Calculus

As we have seen above, the main contribution of the λ -calculus is that it casts the comprehension and (functional) extensionality axioms in a way that is more amenable to automation in reasoning systems, since they can be oriented into a confluent and terminating reduction system. In this Chapter we prove the respective properties. We start out with termination, since we will need it later in the proof of confluence.

12.1 Termination of β -reduction

We will use the termination of β reduction to present a very powerful proof method, called the "logical relations method", which is one of the basic proof methods in the repertoire of a proof theorist, since it can be extended to many situations, where other proof methods have no chance of succeeding.

Before we start into the termination proof, we convince ourselves that a straightforward induction over the structure of expressions will not work, and we need something more powerful.



The overall shape of the proof is that we reason about two relations: SR and LR between λ -terms and their types. The first is the one that we are interested in, $LR(\mathbf{A}, \alpha)$ essentially states the property that $\beta\eta$ reduction terminates at **A**. Whenever the proof needs to argue by induction on types it uses the "logical relation" \mathcal{LR} , which is more "semantic" in flavor. It coincides with \mathcal{SR} on base types, but is defined via a functionality property.

Relations SR and LR \triangleright Definition 12.1.2 A is called strongly reducing at type α (write $\mathcal{SR}(\mathbf{A}, \alpha)$), iff each chain β -reductions from A terminates. \triangleright We define a logical relation \mathcal{LR} inductively on the structure of the type $\triangleright \alpha$ base type: $\mathcal{LR}(\mathbf{A}, \alpha)$, iff $\mathcal{SR}(\mathbf{A}, \alpha)$ $\triangleright \mathcal{LR}(\mathbf{C}, \alpha \to \beta)$, iff $\mathcal{LR}(\mathbf{CA}, \beta)$ for all $\mathbf{A} \in wff_{\alpha}(\Sigma, \mathcal{V}_{\mathcal{T}})$ with $\mathcal{LR}(\mathbf{A}, \alpha)$. **Proof:** Termination Proof \triangleright P.1 $\mathcal{LR} \subseteq \mathcal{SR}$ (Lemma 12.1.4 b)) $\mathbf{A} \in wff_{\alpha}(\Sigma, \mathcal{V}_{\mathcal{T}}) \text{ implies } \mathcal{LR}(\mathbf{A}, \alpha)$ (Theorem 12.1.8 with $\sigma = \emptyset$) thus $\mathcal{SR}(\mathbf{A}, \alpha)$. \square P.2 P.3 Lemma 12.1.3 (SR is closed under subterms) If $SR(\mathbf{A}, \alpha)$ and \mathbf{B}_{β} is a subterm of **A**, then $SR(\mathbf{B}, \beta)$. \triangleright Proof Idea: Every infinite β -reduction from **B** would be one from **A**. JACOBS UNIVERSIT 99 (c): Michael Kohlhase

The termination proof proceeds in two steps, the first one shows that \mathcal{LR} is a sub-relation of \mathcal{SR} , and the second that \mathcal{LR} is total on λ -terms. Together they give the termination result.

The next result proves two important technical side results for the termination proofs in a joint induction over the structure of the types involved. The name "rollercoaster lemma" alludes to the fact that the argument starts with base type, where things are simple, and iterates through the two parts each leveraging the proof of the other to higher and higher types.

 $\mathcal{LR} \subseteq \mathcal{SR} \text{ (Rollercoaster Lemma)}$ $\triangleright \text{ Lemma 12.1.4 (Rollercoaster Lemma)}$ $a) If h is a constant or variable of type \overline{\alpha_n} \to \alpha \text{ and } \mathcal{SR}(\mathbf{A}^i, \alpha^i), \text{ then } \mathcal{LR}(h\overline{\mathbf{A}^n}, \alpha).$ $b) \mathcal{LR}(\mathbf{A}, \alpha) \text{ implies } \mathcal{SR}(\mathbf{A}, \alpha).$ Proof: we prove both assertions by simultaneous induction on α $\triangleright \text{ P.1.1 } \alpha \text{ base type:}$ P.1.1.1.1 a): $h\overline{\mathbf{A}^n}$ is strongly reducing, since the \mathbf{A}^i are (brackets!)
P.1.1.1.2 so $\mathcal{LR}(h\overline{\mathbf{A}^n}, \alpha)$ as α is a base type ($\mathcal{SR} = \mathcal{LR}$)
P.1.1.1.2 b): by definition $\alpha = \beta \to \gamma:$ PR122.1.1 a): Let $\mathcal{LR}(\mathbf{B}, \beta).$ P.1.2.1.1.2 by IH b) we have $\mathcal{SR}(\mathbf{B}, \beta)$, and $\mathcal{LR}((h\overline{\mathbf{A}^n})\mathbf{B}, \gamma)$ by IH a)



The part of the rollercoaster lemma we are really interested in is part b). But part a) will become very important for the case where n = 0; here it states that constants and variables are \mathcal{LR} . The next step in the proof is to show that all well-formed formulae are \mathcal{LR} . For that we need to prove closure of \mathcal{LR} under $=_{\beta}$ expansion

 β -Expansion Lemma \triangleright Lemma 12.1.5 If $\mathcal{LR}([\mathbf{B}/X](\mathbf{A}), \alpha)$ and $\mathcal{LR}(\mathbf{B}, \beta)$ for $X_{\beta} \notin \text{free}(\mathbf{B})$, then $\mathcal{LR}((\lambda X_{\alpha}, \mathbf{A})\mathbf{B}, \alpha).$ ⊳ Proof: **P.1** Let $\alpha = \overline{\gamma_i} \to \delta$ where δ base type and $\mathcal{LR}(\mathbf{C}^i, \gamma^i)$ **P.2** It is sufficient to show that $\mathcal{SR}(((\lambda X \cdot A)B)\overline{C}, \delta)$, as δ base type **P.3** We have $\mathcal{LR}([\mathbf{B}/X](\mathbf{A})\overline{\mathbf{C}}, \delta)$ by hypothesis and definition of \mathcal{LR} . **P.4** thus $\mathcal{SR}([\mathbf{B}/X](\mathbf{A})\overline{\mathbf{C}}, \delta)$, as δ base type. **P.5** in particular $\mathcal{SR}([\mathbf{B}/X](\mathbf{A}), \alpha)$ and $\mathcal{SR}(\mathbf{C}^i, \gamma^i)$ (subterms) **P.6** $SR(\mathbf{B},\beta)$ by hypothesis and Lemma 12.1.4 **P.7** So an infinite reduction from $((\lambda X.A)B)\overline{C}$ cannot solely consist of redexes from $[\mathbf{B}/X](\mathbf{A})$ and the \mathbf{C}^i . **P.8** so an infinite reduction from $((\lambda X, \mathbf{A})\mathbf{B})\overline{\mathbf{C}}$ must have the form $((\lambda X \cdot \mathbf{A})\mathbf{B})\overline{\mathbf{C}} \rightarrow^*_{\beta} ((\lambda X \cdot \mathbf{A}')\mathbf{B}')\overline{\mathbf{C}'}$ $\rightarrow^1_{\beta} [\mathbf{B}'/X](\mathbf{A}')\overline{\mathbf{C}'}$ $\rightarrow^*{}_{\beta}$... where $\mathbf{A} \rightarrow^*{}_{\beta} \mathbf{A}'$, $\mathbf{B} \rightarrow^*{}_{\beta} \mathbf{B}'$ and $\mathbf{C}^i \rightarrow^*{}_{\beta} \mathbf{C}^{i'}$ **P.9** so we have $[\mathbf{B}/X](\mathbf{A}) \rightarrow^*{}_{\beta} [\mathbf{B}'/X](\mathbf{A}')$ P.10 so we have the infinite reduction $[\mathbf{B}/X](\mathbf{A})\overline{\mathbf{C}} \rightarrow^*_{\beta} [\mathbf{B}'/X](\mathbf{A}')\overline{\mathbf{C}'}$ $\rightarrow^*{}_{\beta}$... which contradicts our assumption

$\succ \text{ Lemma 12.1.6 } (\mathcal{LR} \text{ is closed under } \beta \text{-expansion})$ If $\mathbf{C} \rightarrow_{\beta} \mathbf{D}$ and $\mathcal{LR}(\mathbf{D}, \alpha)$, so is $\mathcal{LR}(\mathbf{C}, \alpha)$.			
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Note that this Lemma is one of the few places in the termination proof, where we actually look at the properties of $=_{\beta}$ reduction.

We now prove that every well-formed formula is related to its type by \mathcal{LR} . But we cannot prove this by a direct induction. In this case we have to strengthen the statement of the theorem – and thus the inductive hypothesis, so that we can make the step cases go through. This is common for non-trivial induction proofs. Here we show instead that *every instance* of a well-formed formula is related to its type by \mathcal{LR} ; we will later only use this result for the cases of the empty substitution, but the stronger assertion allows a direct induction proof.

 $\mathbf{A} \in wff_{\alpha}(\Sigma, \mathcal{V}_{\mathcal{T}})$ implies $\mathcal{LR}(\mathbf{A}, \alpha)$ \triangleright Definition 12.1.7 We write $\mathcal{LR}(\sigma)$ if $\mathcal{LR}(\sigma(X_{\alpha}), \alpha)$ for all $X \in \operatorname{supp}(\sigma)$. \triangleright Theorem 12.1.8 If $\mathbf{A} \in wff_{\alpha}(\Sigma, \mathcal{V}_{\mathcal{T}})$, then $\mathcal{LR}(\sigma(\mathbf{A}), \alpha)$ for any substitution σ with $\mathcal{LR}(\sigma)$. \triangleright **Proof**: by induction on the structure of **A P.1.1** $\mathbf{A} = X_{\alpha} \in \operatorname{supp}(\sigma)$: then $\mathcal{LR}(\sigma(\mathbf{A}), \alpha)$ by assumption **P.1.2** $\mathbf{A} = X \notin \operatorname{supp}(\sigma)$: then $\sigma(\mathbf{A}) = \mathbf{A}$ and $\mathcal{LR}(\mathbf{A}, \alpha)$ by Lemma 12.1.4 with n = 0. **P.1.3** $\mathbf{A} \in \Sigma$: then $\sigma(\mathbf{A}) = \mathbf{A}$ as above **P.1.4 A** = **BC**: by IH $\mathcal{LR}(\sigma(\mathbf{B}), \gamma \to \alpha)$ and $\mathcal{LR}(\sigma(\mathbf{C}), \gamma)$ **P.1.4.2** so $\mathcal{LR}(\sigma(\mathbf{B})\sigma(\mathbf{C}), \alpha)$ by definition of \mathcal{LR} . **P.1.5** $\mathbf{A} = \lambda X_{\beta} \cdot \mathbf{C}_{\gamma}$: Let $\mathcal{LR}(\mathbf{B}, \beta)$ and $\theta := \sigma, [\mathbf{B}/X]$, then θ meets the conditions of the IH. **P.1.5.2** Moreover $\sigma(\lambda X_{\beta}, \mathbf{C}_{\gamma})\mathbf{B} \rightarrow_{\beta} \sigma, [\mathbf{B}/X](\mathbf{C}) = \theta(\mathbf{C}).$ **P.1.5.3** Now, $\mathcal{LR}(\theta(\mathbf{C}), \gamma)$ by IH and thus $\mathcal{LR}(\sigma(\mathbf{A})\mathbf{B}, \gamma)$ by Lemma 12.1.6. **P.1.5.4** So $\mathcal{LR}(\sigma(\mathbf{A}), \alpha)$ by definition of \mathcal{LR} . (C): Michael Kohlhase 102

In contrast to the proof of the roller coaster Lemma above, we prove the assertion here by an induction on the structure of the λ -terms involved. For the base cases, we can directly argue with the first assertion from Lemma 12.1.4, and the application case is immediate from the definition of \mathcal{LR} . Indeed, we defined the auxiliary relation \mathcal{LR} exclusively that the application case – which cannot be proven by a direct structural induction; remember that we needed induction on types in Lemma 12.1.4– becomes easy.

The last case on λ -abstraction reveals why we had to strengthen the inductive hypothesis: $=_{\beta}$ reduction introduces a substitution which may increase the size of the subterm, which in turn keeps us from applying the inductive hypothesis. Formulating the assertion directly under all possible \mathcal{LR} substitutions unblocks us here.

This was the last result we needed to complete the proof of termiation of β -reduction.

Remark: If we are only interested in the termination of head reductions, we can get by with a much simpler version of this lemma, that basically relies on the uniqueness of head β reduction.

Closure under Head β -Expansion (weakly reducing)	
\triangleright Lemma 12.1.9 (\mathcal{LR} is closed under head β -expansion) If $\mathbf{C} \rightarrow^{h}_{\beta} \mathbf{D}$ and $\mathcal{LR}(\mathbf{D}, \alpha)$, so is $\mathcal{LR}(\mathbf{C}, \alpha)$.	
\rhd Proof: by induction over the structure of α	
P.1.1 α base type:	
$\mathbf{P.1.1.1}$ we have $\mathcal{SR}(\mathbf{D}, lpha)$ by definition	
P.1.1.2 so $\mathcal{SR}(\mathbf{C}, \alpha)$, since head reduction is unique	
P.1.1.3 and thus $\mathcal{LR}(\mathbf{C}, \alpha)$.	
P.1.2 $\alpha = \beta \rightarrow \gamma$:	
P.1.2.1 Let $\mathcal{LR}(\mathbf{B},\beta)$, by definition we have $\mathcal{LR}(\mathbf{DB},\gamma)$.	
P.1.2.2 but $\mathbf{CB} \rightarrow^h_{\beta} \mathbf{DB}$, so $\mathcal{LR}(\mathbf{CB}, \gamma)$ by IH	
P.1.2.3 and $\mathcal{LR}(\mathbf{C}, \alpha)$ by definition.	
Note: This result only holds for weak reduction (any chain of β head reductions terminates) for strong reduction we need a stronger Lemma.	
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For the termination proof of head β -reduction we would just use the same proof as above, just for a variant of SR, where $SRA \alpha$ that only requires that the head reduction sequence out of **A** terminates. Note that almost all of the proof except Lemma 12.1.3 (which holds by the same argument) is invariant under this change. Indeed Rick Statman uses this observation in [Sta85] to give a set of conditions when logical relations proofs work.

12.2 Confluence of $\beta \eta$ Conversion

We now turn to the confluence for $\beta\eta$, i.e. that the order of reductions is irrelevant. This entails the uniqueness of $\beta\eta$ normal forms, which is very useful.

Intuitively confluence of a relation R means that "anything that flows apart will come together again." – and as a consequence normal forms are unique if they exist. But there is more than one way of formalizing that intuition.

▷ Confluence

- \triangleright Definition 12.2.1 (Confluence) Let $R \subseteq A^2$ be a relation on a set A, then we say that
 - $\triangleright \text{ has a diamond property, iff for every } a, b, c \in A \text{ with } a \rightarrow^1_R b \ a \rightarrow^1_R c \text{ there} \\ \text{ is a } d \in A \text{ with } b \rightarrow^1_R d \text{ and } c \rightarrow^1_R d.$
 - $\triangleright \text{ is confluent, iff for every } a, b, c \in A \text{ with } a \to_R^* b \ a \to_R^* c \text{ there is a } d \in A \text{ with } b \to_R^* d \text{ and } c \to_R^* d.$



The diamond property is very simple, but not many reduction relations enjoy it. Confluence is the notion that that directly gives us unique normal forms, but is difficult to prove via a digram chase, while weak confluence is amenable to this, does not directly give us confluence.

We will now relate the three notions of confluence with each other: the diamond property (sometimes also called strong confluence) is stronger than confluence, which is stronger than weak confluence



Note that Newman's Lemma cannot be proven by a tiling argument since we cannot control the growth of the tiles. There is a nifty proof by Gérard Huet [Hue80] that is worth looking at.

After this excursion into the general theory of reduction relations, we come back to the case at hand: showing the confluence of $\beta\eta$ -reduction.

 η is very well-behaved – i.e. confluent and terminating





For β -reduction the situation is a bit more involved, but a simple diagram chase is still sufficient to prove weak confluence, which gives us confluence via Newman's Lemma



There is one reduction in the diagram in the proof of Lemma 12.2.7 which (note that **B** can occur multiple times in $[\mathbf{B}/X](\mathbf{A})$) is not necessary single-step. The diamond property is broken by the outer two reductions in the diagram as well.

We have shown that the β and η reduction relations are terminating and confluent and terminating individually, now, we have to show that $\beta\eta$ is a well. For that we introduce a new concept.

Commuting Relations

 $\triangleright \text{ Definition 12.2.9 Let } A \text{ be a set, then we say that re$ $lations } \mathcal{R} \in A^2 \text{ and } \mathcal{S} \in A^2 \text{ commute, if } X \to_{\mathcal{R}} Y \text{ and } X \to_{\mathcal{S}} Z \text{ entail the existence of a } W \in A \text{ with } Y \to_{\mathcal{S}} W \text{ and } Z \to_{\mathcal{R}} W.$



 \triangleright Observation 12.2.10 If \mathcal{R} and \mathcal{S} commute, then $\rightarrow_{\mathcal{R}}$ and $\rightarrow_{\mathcal{S}}$ do as well.

$ hightarrow {f Observation 12.2.11} \; {\cal R}$ is confluent, if ${\cal R}$ commutes with itself.			
\triangleright Lemma 12.2.12 If \mathcal{R} and \mathcal{S} are terminating and confluent relations such that $\rightarrow^*_{\mathcal{R}}$ and $\rightarrow^*_{\mathcal{S}}$ commute, then $\rightarrow^*_{\mathcal{R}\cup\mathcal{S}}$ is confluent.			
\triangleright Proof Sketch: As \mathcal{R} and \mathcal{S} commute, we can reorder any reduction sequence so that all \mathcal{R} -reductions precede all \mathcal{S} -reductions. As \mathcal{R} is terminating and confluent, the \mathcal{R} -part ends in a unique normal form, and as \mathcal{S} is normalizing it must lead to a unique normal form as well.			
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This directly gives us our goal.

$eta \eta$ is conflu	ent		
⊳ Lemma 12	$.2.13 ightarrow^*{}_eta$ and $ ightarrow^*{}_\eta$ commute.		
▷ Proof Sketch: diagram chase			
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Chapter 13

The Semantics of the Simply Typed λ -Calculus

The semantics of Λ^{\rightarrow} is structured around the types. Like the models we discussed before, a model (we call them "algebras", since we do not have truth values in Λ^{\rightarrow}) is a pair $\langle \mathcal{D}, \mathcal{I} \rangle$, where \mathcal{D} is the universe of discourse and \mathcal{I} is the interpretation of constants.



13.1 Soundness of the Simply Typed λ -Calculus

We will now show is that $\alpha\beta\eta$ -reduction does not change the value of formulae, i.e. if $\mathbf{A} =_{\alpha\beta\eta} \mathbf{B}$, then $\mathcal{I}_{\varphi}(\mathbf{A}) = \mathcal{I}_{\varphi}(\mathbf{B})$, for all \mathcal{D} and φ . We say that the reductions are sound. As always, the main tool for proving soundess is a substitution value lemma. It works just as always and verifies that we the definitions are in our semantics plausible. Substitution Value Lemma for λ -Terms > Lemma 13.1.1 (Substitution Value Lemma) Let A and B be terms, then $\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A})) = \mathcal{I}_{\psi}(\mathbf{A})$, where $\psi = \varphi, [\mathcal{I}_{\varphi}(\mathbf{B})/X]$ \triangleright **Proof**: by induction on the depth of **A** P.1 we have five cases **P.1.1** $\mathbf{A} = X$: Then $\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A})) = \mathcal{I}_{\varphi}([\mathbf{B}/X](X)) = \mathcal{I}_{\varphi}(\mathbf{B}) = \psi(X) = \psi(X)$ $\mathcal{I}_{\psi}(X) = \mathcal{I}_{\psi}(\mathbf{A}).$ **P.1.2** $\mathbf{A} = Y \neq X$ and $Y \in \mathcal{V}_{\mathcal{T}}$: then $\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A})) = \mathcal{I}_{\varphi}([\mathbf{B}/X](Y)) =$ $\mathcal{I}_{\varphi}(Y) = \varphi(Y) = \psi(Y) = \mathcal{I}_{\psi}(Y) = \mathcal{I}_{\psi}(\mathbf{A}).$ **P.1.3** $\mathbf{A} \in \Sigma$: This is analogous to the last case. **P.1.4** $\mathbf{A} = \mathbf{CD}$: then $\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A})) = \mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{CD})) = \mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{C})[\mathbf{B}/X](\mathbf{D})) = \mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{CD})) = \mathcal{I}_{\varphi}([\mathbf{B}/$ $\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{C}))(\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{D}))) = \mathcal{I}_{\psi}(\mathbf{C})(\mathcal{I}_{\psi}(\mathbf{D})) = \mathcal{I}_{\psi}(\mathbf{C}\mathbf{D}) = \mathcal{I}_{\psi}(\mathbf{A})$ **P.1.5** $\mathbf{A} = \lambda Y_{\alpha} \cdot \mathbf{C}$: **P.1.5.1** We can assume that $X \neq Y$ and $Y \notin \text{free}(\mathbf{B})$ **P.1.5.2** Thus for all $a \in \mathcal{D}_{\alpha}$ we have $\mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A}))(a) = \mathcal{I}_{\varphi}([\mathbf{B}/X](\lambda Y.\mathbf{C}))(a) =$ $\mathcal{I}_{\varphi}(\lambda Y \cdot [\mathbf{B}/X](\mathbf{C}))(a) = \mathcal{I}_{\varphi,[a/Y]}([\mathbf{B}/X](\mathbf{C})) = \mathcal{I}_{\psi,[a/Y]}(\mathbf{C}) = \mathcal{I}_{\psi}(\lambda Y \cdot \mathbf{C})(a)$ $\mathcal{I}_{\psi}(\mathbf{A})(a)$ JACOBS UNIVERSITY (C): Michael Kohlhase 111

Soundness of $\alpha\beta\eta$ -Equality

 $\triangleright \text{ Theorem 13.1.2 Let } \mathcal{A} := \langle \mathcal{D}, \mathcal{I} \rangle \text{ be a } \Sigma \text{-algebra and } Y \notin \text{free}(\mathbf{A}), \text{ then } \mathcal{I}_{\varphi}(\lambda X \cdot \mathbf{A}) = \mathcal{I}_{\varphi}(\lambda Y \cdot [Y/X]\mathbf{A}) \text{ for all assignments } \varphi.$

 \triangleright **Proof**: by substitution value lemma

$$\begin{aligned} \mathcal{I}_{\varphi}(\lambda Y \cdot [Y/X]\mathbf{A}) @ \mathbf{a} &= \mathcal{I}_{\varphi,[a/Y]}([Y/X](\mathbf{A})) \\ &= \mathcal{I}_{\varphi,[a/X]}(\mathbf{A}) \\ &= \mathcal{I}_{\varphi}(\lambda X \cdot \mathbf{A}) @ \mathbf{a} \end{aligned}$$

 \triangleright Theorem 13.1.3 If $\mathcal{A} := \langle \mathcal{D}, \mathcal{I} \rangle$ is a Σ -algebra and X not bound in \mathbf{A} , then $\mathcal{I}_{\varphi}((\lambda X \cdot \mathbf{A})\mathbf{B}) = \mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A})).$

 \triangleright **Proof**: by substitution value lemma again

$$\begin{aligned} \mathcal{I}_{\varphi}((\lambda X.\mathbf{A})\mathbf{B}) &= \mathcal{I}_{\varphi}(\lambda X.\mathbf{A}) @ \mathcal{I}_{\varphi}(\mathbf{B}) \\ &= \mathcal{I}_{\varphi,[\mathcal{I}_{\varphi}(\mathbf{B})/X]}(\mathbf{A}) \\ &= \mathcal{I}_{\varphi}([\mathbf{B}/X](\mathbf{A})) \end{aligned}$$

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Soundness of $\alpha\beta\eta$ (continued)

 $\triangleright \text{ Theorem 13.1.4 If } X \notin \text{free}(\mathbf{A}), \text{ then } \mathcal{I}_{\varphi}(\lambda X \cdot \mathbf{A}X) = \mathcal{I}_{\varphi}(\mathbf{A}) \text{ for all } \varphi.$ $\triangleright \text{ Proof: by calculation}$ $\mathcal{I}_{\varphi}(\lambda X \cdot \mathbf{A}X) @ \mathbf{a} = \mathcal{I}_{\varphi,[\mathbf{a}/X]}(\mathbf{A}X)$ $= \mathcal{I}_{\varphi,[\mathbf{a}/X]}(\mathbf{A}) @ \mathcal{I}_{\varphi,[\mathbf{a}/X]}(X)$ $= \mathcal{I}_{\varphi}(\mathbf{A}) @ \mathcal{I}_{\varphi,[\mathbf{a}/X]}(X) \text{ as } X \notin \text{free}(\mathbf{A}).$ $= \mathcal{I}_{\varphi}(\mathbf{A}) @ \mathbf{a}$ $\triangleright \text{ Theorem 13.1.5 } \alpha \beta \eta \text{-equality is sound wrt. } \Sigma \text{-algebras. (if } \mathbf{A} =_{\alpha\beta\eta} \mathbf{B}, \text{ then } \mathcal{I}_{\varphi}(\mathbf{A}) = \mathcal{I}_{\varphi}(\mathbf{B}) \text{ for all assignments } \varphi)$ $\textcircled{C: Michael Kohlhase} \qquad 113$

13.2 Completeness of $\alpha\beta\eta$ -Equality

We will now show is that $\alpha\beta\eta$ -equality is complete for the semantics we defined, i.e. that whenever $\mathcal{I}_{\varphi}(\mathbf{A}) = \mathcal{I}_{\varphi}(\mathbf{B})$ for all variable assignments φ , then $\mathbf{A} =_{\alpha\beta\eta} \mathbf{B}$. We will prove this by a model existence argument: we will construct a model $\mathcal{M} := \langle \mathcal{D}, \mathcal{I} \rangle$ such that if $\mathbf{A} \neq_{\alpha\beta\eta} \mathbf{B}$ then $\mathcal{I}_{\varphi}(\mathbf{A}) \neq \mathcal{I}_{\varphi}(\mathbf{B})$ for some φ .

As in other completeness proofs, the model we will construct is a "ground term model", i.e. a model where the carrier (the frame in our case) consists of ground terms. But in the λ -calculus, we have to do more work, as we have a non-trivial built-in equality theory; we will construct the "ground term model" from sets of normal forms. So we first fix some notations for them.

Normal Forms in the simply typed λ -calculus $\triangleright \text{ Definition 13.2.1 We call a term } \mathbf{A} \in wff_{\mathcal{T}}(\Sigma, \mathcal{V}_{\mathcal{T}}) \text{ a } \beta \text{ normal form iff} \text{ there is no } \mathbf{B} \in wff_{\mathcal{T}}(\Sigma, \mathcal{V}_{\mathcal{T}}) \text{ with } \mathbf{A} \rightarrow_{\beta} \mathbf{B}.$ We call $\mathbf{N} \neq \beta$ normal form of \mathbf{A} , iff \mathbf{N} is a β -normal form and $\mathbf{A} \rightarrow_{\beta} \mathbf{N}$. We denote the set of β -normal forms with $wff_{\mathcal{T}}(\Sigma, \mathcal{V}_{\mathcal{T}}) \downarrow_{\beta\eta}$. $\triangleright \text{ We have just proved that } \beta\eta\text{-reduction is terminating and confluent, so we have}$ $\triangleright \text{ Corollary 13.2.2 (Normal Forms) Every } \mathbf{A} \in wff_{\mathcal{T}}(\Sigma, \mathcal{V}_{\mathcal{T}}) \text{ has a unique } \beta \text{ normal form } (\beta\eta, \log \beta\eta \text{ normal form}), \text{ which we denote by } \mathbf{A} \downarrow_{\beta} (\mathbf{A} \downarrow_{\beta\eta} + \mathbf{A} \downarrow_{\beta\eta}^{l})$ $\widehat{\mathbb{C}} : \text{Michael Kohlhase} \qquad 114$

The term frames will be a quotient spaces over the equality relations of the λ -calculus, so we introduce this construction generally.

Frames and Quotients

- \triangleright **Definition 13.2.3** Let \mathcal{D} be a frame and \sim a typed equivalence relation on \mathcal{D} , then we call \sim a congruence on \mathcal{D} , iff $f \sim f'$ and $g \sim g'$ imply $f(g) \sim f'(g')$.
- \triangleright **Definition 13.2.4** We call a congruence \sim functional, iff for all $f, g \in \mathcal{D}_{\alpha \to \beta}$ the fact that $f(a) \sim g(a)$ holds for all $a \in \mathcal{D}_{\alpha}$ implies that $f \sim g$.



To apply this result, we have to establish that $\beta\eta$ -equality is a functional congruence. We first establish $\beta\eta$ as a functional congruence on $wff_{\mathcal{T}}(\Sigma, \mathcal{V}_{\mathcal{T}})$ and then specialize this result to show that is also functional on $c wff_{\mathcal{T}}(\Sigma)$ by a grounding argument.

 $\beta\eta$ -Equivalence as a Functional Congruence \triangleright Lemma 13.2.7 $\beta\eta$ -equality is a functional congruence on wff $_{\tau}(\Sigma, \mathcal{V}_{\tau})$. \triangleright Proof: Let $\mathbf{AC} =_{\beta\eta} \mathbf{BC}$ for all \mathbf{C} and $X \in (\mathcal{V}_{\gamma} \setminus (\operatorname{free}(\mathbf{A}) \cup \operatorname{free}(\mathbf{B})))$. **P.1** then (in particular) $\mathbf{A}X =_{\beta\eta} \mathbf{B}X$, and **P.2** $(\lambda X \cdot AX) =_{\beta\eta} (\lambda X \cdot BX)$, since $\beta\eta$ -equality acts on subterms. **P.3** By definition we have $\mathbf{A} =_{\eta} (\lambda X_{\alpha} \cdot \mathbf{A} X) =_{\beta \eta} (\lambda X_{\alpha} \cdot \mathbf{B} X) =_{\eta} \mathbf{B}$. \triangleright **Definition 13.2.8** We call an injective substitution σ : free(**C**) $\rightarrow \Sigma$ a grounding substitution for $\mathbf{C} \in wff_{\mathcal{T}}(\Sigma, \mathcal{V}_{\mathcal{T}})$, iff no $\sigma(X)$ occurs in \mathbf{C} . Observation: They always exist, since all Σ_{α} are infinite and free(C) is finite. \bowtie Theorem 13.2.9 $\beta\eta$ -equality is a functional congruence on $c \, wff_{\tau}(\Sigma)$. \triangleright **Proof**: We use Lemma 13.2.7 **P.1** Let $\mathbf{A}, \mathbf{B} \in c \, wf\!\!f_{(\alpha \to \beta)}(\Sigma)$, such that $\mathbf{A} \neq_{\beta \eta} \mathbf{B}$. **P.2** As $\beta\eta$ is functional on $wff_{\tau}(\Sigma, \mathcal{V}_{\tau})$, there must be a **C** with $\mathbf{AC} \neq_{\beta\eta} \mathbf{BC}$. **P.3** Now let $\mathbf{C}' := \sigma(\mathbf{C})$, for a grounding substitution σ . **P.4** Any $\beta\eta$ conversion sequence for $\mathbf{AC}' \neq_{\beta\eta} \mathbf{BC}'$ induces one for $\mathbf{AC} \neq_{\beta\eta}$ BC. **P.5** Thus we have shown that $\mathbf{A} \neq_{\beta\eta} \mathbf{B}$ entails $\mathbf{AC}' \neq_{\beta\eta} \mathbf{BC}'$. V JACOBS UNIVERSI C (C): Michael Kohlhase 116

Note that: the result for $c \, wff_{\mathcal{T}}(\Sigma)$ is sharp. For instance, if $\Sigma = \{c_i\}$, then $(\lambda X \cdot X) \neq_{\beta\eta} (\lambda X \cdot c)$,

but $(\lambda X \cdot X)c =_{\beta\eta}c =_{\beta\eta}(\lambda X \cdot c)c$, as $\{c\} = c \, wff_{\iota}(\Sigma)$ (it is a relatively simple exercise to extend this problem to more than one constant). The problem here is that we do not have a constant d_{ι} that would help distinguish the two functions. In $wff_{\mathcal{T}}(\Sigma, \mathcal{V}_{\mathcal{T}})$ we could always have used a variable.

This completes the preparation and we can define the notion of a term algebra, i.e. a Σ -algebra whose frame is made of $\beta\eta$ -normal λ -terms.



And as always, once we have a term model, showing completeness is a rather simple exercise. We can see that $\alpha\beta\eta$ -equality is complete for the class of Σ -algebras, i.e. if the equation $\mathbf{A} = \mathbf{B}$ is valid, then $\mathbf{A} =_{\alpha\beta\eta} \mathbf{B}$. Thus $\alpha\beta\eta$ equivalence fully characterizes equality in the class of all Σ -algebras.

Completetness of $\alpha\beta\eta$ -Equality

- \triangleright Theorem 13.2.12 $\mathbf{A} = \mathbf{B}$ is valid in the class of Σ -algebras, iff $\mathbf{A} =_{\alpha\beta\eta} \mathbf{B}$.
- \triangleright Proof: For A, B closed this is a simple consequence of the fact that $\mathcal{T}_{\beta\eta}$ is a Σ -algebra.
 - **P.1** If $\mathbf{A} = \mathbf{B}$ is valid in all Σ -algebras, it must be in $\mathcal{T}_{\beta\eta}$ and in particular $\mathbf{A}\!\!\downarrow_{\beta\eta} = \mathcal{I}^{\beta\eta}(\mathbf{A}) = \mathcal{I}^{\beta\eta}(\mathbf{B}) = \mathbf{B}\!\!\downarrow_{\beta\eta}$ and therefore $\mathbf{A} =_{\alpha\beta\eta} \mathbf{B}$.
 - P.2 If the equation has free variables, then the argument is more subtle.
 - **P.3** Let σ be a grounding substitution for **A** and **B** and φ the induced variable assignment.
 - **P.4** Thus $\mathcal{I}^{\beta \eta}{}_{\varphi}(\mathbf{A}) = \mathcal{I}^{\beta \eta}{}_{\varphi}(\mathbf{B})$ is the $\beta \eta$ -normal form of $\sigma(\mathbf{A})$ and $\sigma(\mathbf{B})$.
 - **P.5** Since φ is a structure preserving homomorphism on well-formed formulae, $\varphi^{-1}(\mathcal{I}^{\beta \eta}{}_{\varphi}(\mathbf{A}))$ is the is the $\beta\eta$ -normal form of both \mathbf{A} and \mathbf{B} and thus $\mathbf{A} =_{\alpha\beta\eta} \mathbf{B}.$

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Theorem 13.2.12 and Theorem 13.1.5 complete our study of the sematnics of the simply-typed λ -calculus by showing that it is an adequate logic for modeling (the equality) of functions and their applications.

Chapter 14

Simply Typed λ -Calculus via Inference Systems

Now, we will look at the simply typed λ -calculus again, but this time, we will present it as an inference system for well-typedness jugdments. This more modern way of developing type theories is known to scale better to new concepts.

Simply Typed λ -Ca	lculus as an Inference S	ystem: Terms	
\triangleright Idea: Develop the λ -ca	alculus in two steps		
▷ A context-free gran	nmar for "raw λ -terms" (for the z	structure)	
▷ Identify the well-typ	ped λ -terms in that (cook	them until well-typed)	
⊳ Definition 14.0.1 A calculus: Ω Γ Α	grammar for the raw terms of $a :== c \mid \alpha \to \alpha$ $b :== \cdot \mid \Sigma, [c: type] \mid \Sigma, [c: \alpha]$ $c :== \cdot \mid \Gamma, [x: \alpha]$ $c :== c \mid X \mid \mathbf{A}^{1}\mathbf{A}^{2} \mid \lambda X_{\alpha}.\mathbf{A}$	f the simply typed λ - $[\alpha]$	
Then: Define all the operations that are possible at the "raw terms level", e.g. realize that signatures and contexts are partial functions to types.			
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Simply Typed λ -Calculus as an Inference System: Judgments

▷ Definition 14.0.2 Judgments make statements about complex properties of the syntactic entities defined by the grammar.

 \triangleright **Definition 14.0.3** Judgments for the simply typed λ -calculus

$\vdash \Sigma : sig$	Σ is a well-formed signature
$\Sigma \vdash \alpha : type$	$lpha$ is a well-formed type given the type assumptions in Σ
$\Sigma \vdash \Gamma : \operatorname{ctx}$	Γ is a well-formed context given the type assumptions in Σ
$\Gamma \vdash_{\Sigma} \mathbf{A} \colon \alpha$	A has type $lpha$ given the type assumptions in Σ and Γ



Example: A Well-Formed Signature

 $\triangleright \ \mathsf{Let} \ \Sigma := [\alpha: \mathrm{type}], [f: \alpha \to \alpha \to \alpha], \ \mathsf{then} \ \Sigma \ \mathsf{is a well-formed signature, since} \\ \text{we have derivations} \ \mathcal{A} \ \mathsf{and} \ \mathcal{B}$

$$\frac{\vdash \cdot : \text{sig}}{\vdash [\alpha : \text{type}] : \text{sig}} \text{sig:type} \qquad \frac{\mathcal{A} \quad [\alpha : \text{type}](\alpha) = \text{type}}{[\alpha : \text{type}] \vdash \alpha : \text{type}} \text{typ:start}$$

and with these we can construct the derivation $\ensuremath{\mathcal{C}}$







 $\beta \eta$ -Equality by Inference Rules: Multi-Step Reduction

 $arproptom \mathsf{Multi-Step-Reduction} (+ \in \{\alpha, \beta, \eta\})$ $\frac{\Gamma \vdash_{\Sigma} \mathbf{A} \rightarrow^{1}_{+} \mathbf{B}}{\Gamma \vdash_{\Sigma} \mathbf{A} \rightarrow^{*}_{+} \mathbf{B}} \mathsf{ms:start} \qquad \frac{\Gamma \vdash_{\Sigma} \mathbf{A} : \alpha}{\Gamma \vdash_{\Sigma} \mathbf{A} \rightarrow^{*}_{+} \mathbf{A}} \mathsf{ms:ref}$ $\frac{\Gamma \vdash_{\Sigma} \mathbf{A} \rightarrow^{*}_{+} \mathbf{B} \ \Gamma \vdash_{\Sigma} \mathbf{B} \rightarrow^{*}_{+} \mathbf{C}}{\Gamma \vdash_{\Sigma} \mathbf{A} \rightarrow^{*}_{+} \mathbf{C}} \mathsf{ms:trans}$ $arproptom \mathsf{Congruence Relation} \qquad \frac{\Gamma \vdash_{\Sigma} \mathbf{A} \rightarrow^{*}_{+} \mathbf{B}}{\Gamma \vdash_{\Sigma} \mathbf{A} =_{+} \mathbf{B}} \mathsf{eq:start}$ $\frac{\Gamma \vdash_{\Sigma} \mathbf{A} =_{+} \mathbf{B}}{\Gamma \vdash_{\Sigma} \mathbf{B} =_{+} \mathbf{A}} \mathsf{eq:sym} \qquad \frac{\Gamma \vdash_{\Sigma} \mathbf{A} =_{+} \mathbf{B} \ \Gamma \vdash_{\Sigma} \mathbf{B} =_{+} \mathbf{C}}{\Gamma \vdash_{\Sigma} \mathbf{A} =_{+} \mathbf{C}} \mathsf{eq:trans}$ $\mathbb{O}: \mathsf{Michael Kohlhase} \qquad 125 \qquad \mathbf{V}_{\mathsf{Max}}$

Chapter 15

Higher-Order Unification

We now come to a very important (if somewhat non-trivial and under-appreciated) algorithm: higher-order unification, i.e. unification in the simply typed λ -calculus, i.e. unification modulo $\alpha\beta\eta$ equality.

15.1 Higher-Order Unifiers

Before we can start solving the problem of higher-order unification, we have to become clear about the terms we want to use. It turns out that "most general $\alpha\beta\eta$ unifiers may not exist – as Theorem 15.1.5 shows, there may be infinitely descending chains of unifiers that become more an more general. Thus we will have to generalize our concepts a bit here.

HOU: Complete Sets of Unifiers ▷ Question: Are there most general higher-order Unifiers? \triangleright Answer: What does that mean anyway? \triangleright Definition 15.1.1 $\sigma =_{\beta\eta} \rho[W]$, iff $\sigma(X) =_{\alpha\beta\eta} \rho(X)$ for all $X \in W$. $\sigma =_{\beta\eta}$ $\rho[\mathcal{E}]$ iff $\sigma =_{\beta\eta} \rho[\text{free}(\mathcal{E})]$ \triangleright Definition 15.1.2 σ is more general than θ on W ($\sigma \leq_{\beta\eta} \theta[W]$), iff there is a substitution ρ with $\theta =_{\beta\eta} \rho \circ \sigma[W]$. \triangleright Definition 15.1.3 $\Psi \subseteq U(\mathcal{E})$ is a complete set of unifiers, iff for all unifiers $\theta \in \mathbf{U}(\mathcal{E})$ there is a $\sigma \in \Psi$, such that $\sigma \leq_{\beta\eta} \theta[\mathcal{E}]$. \triangleright **Definition 15.1.4** If $\Psi \subseteq \mathbf{U}(\mathcal{E})$ is complete, then $\leq_{\beta\eta}$ -minimal elements $\sigma \in$ Ψ are most general unifiers of \mathcal{E} . \triangleright Theorem 15.1.5 The set $\{[\lambda uv.hu/F]\} \cup \{\sigma_i \mid i \in \mathbb{N}\}$ where $\sigma_i := [\lambda uv g_n u(u(h_1^n uv)) \dots (u(h_n^n uv))/F], [\lambda v z/X]$ is a complete set of unifiers for the equation $FXa_{\iota} = {}^{?}FXb_{\iota}$, where F and Xare variables of types $(\iota \rightarrow \iota) \rightarrow \iota \rightarrow \iota$ and $\iota \rightarrow \iota$ Furthermore, σ_{i+1} is more general than σ_i .



The definition of a solved form in Λ^{\rightarrow} is just as always; even the argument that solved forms are most general unifiers works as always, we only need to take $\alpha\beta\eta$ equality into account at every level.

Unification> Definition 15.1.6 $X^1 = B^1 \land \ldots \land X^n = B^n$ is in solved form, if the X^i are distinct free variables $X^i \notin \text{free}(\mathbf{B}^j)$ and \mathbf{B}^j does not contain Skolem constants for all j.> Lemma 15.1.7 If $\mathcal{E} = X^1 = B^1 \land \ldots \land X^n = B^n$ is in solved form, then $\sigma_{\mathcal{E}} := [\mathbf{B}^1/X^1], \ldots, [\mathbf{B}^n/X^n]$ is the unique most general unifier of \mathcal{E} > Proof:P.1 $\sigma(X^i) =_{\alpha\beta\eta} \sigma(\mathbf{B}^i)$, so $\sigma \in \mathbf{U}(\mathcal{E})$ P.2 Let $\theta \in \mathbf{U}(\mathcal{E})$, then $\theta(X^i) =_{\alpha\beta\eta} \theta(\mathbf{B}^i) = \theta \circ \sigma(X^i)$ P.3 so $\theta \leq_{\beta\eta} \theta \circ \sigma[\mathcal{E}]$. \square \square </tr

15.2 Higher-Order Unification Transformations

We are now in a position to introduce the higher-order unifiation transformations. We proceed just like we did for first-order unification by casting the unification algorithm as a set of unification inference rules, leaving the control to a second layer of development.

We first look at a group of transformations that are (relatively) well-behaved and group them under the concept of "simplification", since (like the first-order transformation rules they resemble) have good properties. These are usually implemented in a group and applied eagerly.

Simplification \mathcal{SIM}

 \triangleright Definition 15.2.1 The higher-order simplification transformations \mathcal{SIM} con-

sist of the rules below.

$$\begin{split} \frac{(\lambda X_{\alpha}.\mathbf{A}) =^{?} (\lambda Y_{\alpha}.\mathbf{B}) \wedge \mathcal{E} \quad s \in \Sigma_{\alpha}^{Sk} \operatorname{new}}{[s/X](\mathbf{A}) =^{?} [s/Y](\mathbf{B}) \wedge \mathcal{E}} \mathcal{SIM}: \alpha \\ \frac{(\lambda X_{\alpha}.\mathbf{A}) =^{?} \mathbf{B} \wedge \mathcal{E} \quad s \in \Sigma_{\alpha}^{Sk} \operatorname{new}}{[s/X](\mathbf{A}) =^{?} \mathbf{B} s \wedge \mathcal{E}} \mathcal{SIM}: \eta \\ \frac{h \overline{\mathbf{U}^{n}} =^{?} h \overline{\mathbf{V}^{n}} \wedge \mathcal{E} \quad h \in (\Sigma \cup \Sigma^{Sk})}{\mathbf{U}^{1} =^{?} \mathbf{V}^{1} \wedge \ldots \wedge \mathbf{U}^{n} =^{?} \mathbf{V}^{n} \wedge \mathcal{E}} \mathcal{SIM}: \operatorname{dec} \\ \frac{\mathcal{E} \wedge X =^{?} \mathbf{A} \quad X \notin \operatorname{free}(\mathbf{A}) \quad \mathbf{A} \cap \Sigma^{Sk} = \emptyset \quad X \in \operatorname{free}(\mathcal{E})}{[\mathbf{A}/X](\mathcal{E}) \wedge X =^{?} \mathbf{A}} \mathcal{SIM}: \operatorname{elim} \\ \end{split}$$
After rule applications all λ -terms are reduced to head normal form.

$$\begin{split} \overbrace{\mathbb{C}: \text{Michael Kohlhase}}^{(\Sigma: Michael Kohlhase} 128 \end{split}$$

The main new feature of these rules (with respect to their first-order counterparts) is the handling of λ -binders. We eliminate them by replacing the bound variables by Skolem constants in the bodies: The $SIM: \alpha$ standardizes them to a single one using α -equality, and $SIM: \eta$ first η -expands the right-hand side (which must be of functional type) so that $SIM: \alpha$ applies. Given that we are setting bound variables free in this process, we need to be careful that we do not use them in the SIM:elim rule, as these would be variable-capturing.

Consider for instance the higher-order unification problem $(\lambda X \cdot X) = (\lambda Y \cdot W)$, which is unsolvable (the left hand side is the identity function and the right hand side some constant function – whose value is given by W). So after an application of $SIM : \alpha$, we have c = W, which looks like it could be a solved pair, but the elimination rule prevents that by insisting that instances may not contain Skolem Variables.

Conceptually, SIM is a direct generalization of first-order unification transformations, and shares it properties; even the proofs go correspondingly.

Properties of Simplification	
▷ Lemma 15.2.2 (Properties of SIM) SIM generalizes first-order uni- fication.	
\triangleright SIM is terminating and confluent up to $lpha$ -conversion	
$_{arsigma}$ Unique SIM normal forms exist (all pairs have the form $h\overline{\mathbf{U}^n}{=}^?k\overline{\mathbf{V}^m})$	
$\triangleright \text{ Lemma 15.2.3 } \mathbf{U}(\mathcal{E} \land \mathcal{E}_{\sigma}) = \mathbf{U}(\sigma(\mathcal{E}) \land \mathcal{E}_{\sigma}).$	
Proof: by the definitions	
$\triangleright \ \mathbf{P.1} \ lf \ \theta \in \mathbf{U}(\mathcal{E} \wedge \mathcal{E}_{\sigma}), \ then \ \theta \in (\mathbf{U}(\mathcal{E}) \cap \mathbf{U}(\mathcal{E}_{\sigma})).$	
So $\theta =_{\beta\eta} \theta \circ \sigma[\mathbf{supp}(\sigma)]$,	
and thus $(\theta \circ \sigma) \in \mathbf{U}(\mathcal{E})$, iff $\theta \in \mathbf{U}(\sigma(\mathcal{E}))$.	



Now that we have simplifiation out of the way, we have to deal with unification pairs of the form $h\overline{\mathbf{U}^n} = {}^? k\overline{\mathbf{V}^m}$. Note that the case where both h and k are constants is unsolvable, so we can assume that one of them is a variable. The unification problem $F_{\alpha \to \alpha}a = {}^? a$ is a particularly simple example; it has solutions $[\lambda X_{\alpha} \cdot a/F]$ and $[\lambda X_{\alpha} \cdot X/F]$. In the first, the solution comes by instantiating F with a λ -term of type $\alpha \to \alpha$ with head a, and in the second with a 1-projection term of type $\alpha \to \alpha$, which projects the head of the argument into the right position. In both cases, the solution came from a term with a given type and an appropriate head. We will look at the problem of finding such terms in more detail now.



For the construction of general bindings, note that their construction is completely driven by the intended type α and the (type of) the head h. Let us consider some examples.

Example 15.2.7 The following general bindings may be helpful: $\mathbf{G}_{\iota \to \iota}^{a_{\iota}}(\Sigma) = \lambda X_{\iota} . a, \mathbf{G}_{\iota \to \iota \to \iota}^{a_{\iota}}(\Sigma) = \lambda X_{\iota} Y_{\iota} . a, \mathbf{G}_{\iota \to \iota \to \iota}^{a_{\iota}}(\Sigma) = \lambda X_{\iota} Y_{\iota} . a (HXY)$, where H is of type $\iota \to \iota \to \iota$

We will now show that the general bindings defined in Definition 15.2.6 are indeed the most general λ -terms given their type and head.



With this result we can state the higher-order unification transformations.



Let us now fortify our intuition with a simple example.

\mathcal{HOU} Example

Example 15.2.10 Let $Q, w: \iota \to \iota, l: \iota \to \iota \to \iota$, and $j: \iota$, then we have the following derivation tree in HOU.



The first thing that meets the eye is that higher-order unification is branching. Indeed, for flex/rigid pairs, we have to systematically explore the possibilities of binding the head variable the imitation binding and all projection bindings. On the initial node, we have two bindings, the projection binding leads to an unsolvable unification problem, whereas the imitation binding leads to a unification problem that can be decomposed into two flex/rigid pairs. For the first one of them, we have a projection and an imitation binding, which we systematically explore recursively. Eventually, we arrive at four solutions of the initial problem.

The following encoding of natural number arithmetics into Λ^{\rightarrow} is useful for testing our unification algorithm

A Test Generator for Higher-Order Unification

- \triangleright Definition 15.2.11 (Church Numerals) We define closed λ -terms of type $\nu := (\alpha \to \alpha) \to \alpha \to \alpha$
 - ▷ Numbers: Church numerals: (*n*-fold iteration of arg1 starting from arg2)

$$n := (\lambda S_{\alpha \to \alpha} \cdot \lambda O_{\alpha} \cdot \underbrace{S(S \dots S}_{n}(O) \dots))$$

▷ Addition

(N-fold iteration of S from N)

 $+ := (\lambda N_{\nu} M_{\nu} \cdot \lambda S_{\alpha \to \alpha} \cdot \lambda O_{\alpha} \cdot NS(MSO))$

▷ Multiplication:

(*N*-fold iteration of MS (=+m) from *O*)

 $\cdot := (\lambda N_{\nu} M_{\nu} \cdot \lambda S_{\alpha \to \alpha} \cdot \lambda O_{\alpha} \cdot N(MS)O)$

- ▷ Observation 15.2.12 Subtraction and (integer) division on Church numberals can be automted via higher-order unification.
- \triangleright Example 15.2.13 5 2 by solving the unification problem $2 + x_{\nu} = {}^{?}5$

Equation solving for Church numerals yields a very nice generator for test cases for higher-order unification, as we know which solutions to expect.

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15.3 Properties of Higher-Order Unification

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We will now establish the properties of the higher-order unification problem and the algorithms we have introduced above. We first establish the unidecidability, since it will influence how we go about the rest of the properties.

We establish that higher-order unification is undecidable. The proof idea is a typical for undecidable proofs: we reduce the higher-order unification problem to one that is known to be undecidable: here, the solution of Diophantine equations \mathbb{N} .

Undecidability of	Higher-Order Unif	ication	
▷ Theorem 15.3.1 '82 [Gol81])	Second-order unification i	s undecidable	(Goldfarb
▷ Proof Sketch: Re equations)	eduction to Hilbert's tent	h problem (solving D (known to be ur	Diophantine Indecidable)
▷ Definition 15.3.2 form	2 We call an equation a Di	ophantine equation, if	it is of the
$\triangleright x_i x_j = x_k$			
$\triangleright x_i + x_j = x_k$			
$\triangleright x_i = c_j$ where c_j	$j \in \mathbb{N}$		
where the variables x_i range over \mathbb{N} .			
▷ These can be solved servation 15.2.12)	d by higher-order unificatio	on on Church numeral	s. (cf. Ob-
Theorem 15.3.3 The general solution for sets of Diophantine equations is undecidable. (Matijasevič 1970 [Mat70])			
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The argument undecidability proofs is always the same: If higher-order unification were decidable, then via the encoding we could use it to solve Diophantine equations, which we know we cannot by Matijasevič's Theorem.

The next step will be to analyze our transformations for higher-order unification for correctness and completeness, just like we did for first-order unification.

 $\begin{array}{l} \mathcal{HOU} \text{ is Correct} \\ & \triangleright \text{ Lemma 15.3.4 If } \mathcal{E} \vdash_{\mathcal{HOUfr}} \mathcal{E}' \text{ or } \mathcal{E} \vdash_{\mathcal{HOUff}} \mathcal{E}', \text{ then } \mathbf{U}(\mathcal{E}') \subseteq \mathbf{U}(\mathcal{E}). \\ & \triangleright \text{ Proof Sketch: } \mathcal{HOU}: \text{fr and } \mathcal{HOU}: \text{ff only add new pair. } \\ & \triangleright \text{ Corollary 15.3.5 } \mathcal{HOU} \text{ is correct: } \text{If } \mathcal{E} \vdash_{\mathcal{HOU}} \mathcal{E}', \text{ then } \mathbf{U}(\mathcal{E}') \subseteq \mathbf{U}(\mathcal{E}). \end{array}$

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Given that higher-order unification is not unitary and undecidable, we cannot just employ the notion of completeness that helped us in the analysis of first-order unification. So the first thing is to establish the condition we want to establish to see that \mathcal{HOU} gives a higher-order unification algorithm.



So we will embark on the details of the completeness proof. The first step is to define a measure that will guide the \mathcal{HOU} transformation out of a unification problem \mathcal{E} given a unifier θ of cE.



This measure will now guide the \mathcal{HOU} transformation in the sense that in any step it chooses whether to use \mathcal{HOU} : fr or \mathcal{HOU} : ff, and which general binding (by looking at what θ would do). We formulate the details in Theorem 15.3.9 and look at their consequences before we proove it.

Completeness of \mathcal{HOU} (μ -Prescription)



We now come to the proof of Theorem 15.3.9, which is a relatively simple consequence of Theorem 15.2.8.

Proof of Theorem 15.3.9 \triangleright Proof: **P.1** Let $\mathbf{A} = {}^{?} \mathbf{B}$ be an unsolved pair of the form $\mathbf{F}\overline{\mathbf{U}} = {}^{?} \mathbf{G}\overline{\mathbf{V}}$ in \mathcal{F} . **P.2** \mathcal{E} is a \mathcal{SIM} normal form, so **F** and **G** must be constants or variables, **P.3** but not the same constant, since otherwise SIM: dec would be applicable. **P.4** We can also exclude $\mathbf{A} =_{\alpha\beta\eta} \mathbf{B}$, as \mathcal{SIM} :triv would be be applicable. **P.5** If $\mathbf{F} = \mathbf{G}$ is a variable not in $\operatorname{supp}(\theta)$, then \mathcal{SIM} : dec appliccable. By correctness we have $\theta \in \mathbf{U}(\mathcal{E}')$ and $\mu(\mathcal{E}',\theta) \prec \mu(\mathcal{E},\theta)$, as $\mu_1(\mathcal{E}',\theta) \preceq$ $\mu_1(\mathcal{E}, \theta)$ and $\mu_2(\mathcal{E}') \prec \mu_2(\mathcal{E})$. **P.6** Otherwise we either have $\mathbf{F} \neq \mathbf{G}$ or $\mathbf{F} = \mathbf{G} \in \operatorname{supp}(\theta)$. **P.7** In both cases **F** or **G** is an unsolved variable $F \in \operatorname{supp}(\theta)$ of type α , since \mathcal{E} is unsolved. **P.8** Without loss of generality we choose $F = \mathbf{F}$. **P.9** By Theorem 15.2.8 there is a general binding $\mathbf{G} = \mathbf{G}^f_{\alpha}(\Sigma)$ and a substitution ρ with $\rho(\mathbf{G}) =_{\alpha\beta\eta} \theta(F)$. So, \triangleright if head(**G**) \notin supp(θ), then \mathcal{HOU} : fr is applicable, ▷ if head(**G**) \in supp(θ), then \mathcal{HOU} : ff is applicable. **P.10** Choose $\theta' := \theta \cup \rho$. Then $\theta =_{\beta\eta} \theta'[\mathcal{E}]$ and $\theta' \in \mathbf{U}(\mathcal{E}')$ by correctness. **P.11** \mathcal{HOU} : ff and \mathcal{HOU} : fr solve $F \in \operatorname{supp}(\theta)$ and replace F by $\operatorname{supp}(\rho)$ in the set of unsolved variable of \mathcal{E} . **P.12** so $\mu_1(\mathcal{E}', \theta') \prec \mu_1(\mathcal{E}, \theta)$ and thus $\mu(\mathcal{E}', \theta') \prec \mu(\mathcal{E}, \theta)$. 6 JACOBS UNIVERS (C): Michael Kohlhase 140

We now convince ourselves that if HOU terminates with a unification problem, then it is either solved – in which case we can read off the solution – or unsolvable.

Terminal *HOU*-problems are Solved or Unsolvable

$\triangleright \text{ Theorem 15.3.11 If } \mathcal{E} \text{ is a unsolved UP and } \theta \in \mathbf{U}(\mathcal{E}), \text{ then there is a } \mathcal{HOU}\text{-derivation } \mathcal{E} \vdash_{\mathcal{HOU}} \sigma_{\sigma}, \text{ with } \sigma \leq_{\beta\eta} \theta[\mathcal{E}].$			
$\triangleright \text{ Proof: Let } \mathcal{D} \colon \mathcal{E} \vdash_{\mathcal{HOU}} \mathcal{F} \text{ a maximal } \mu \text{-prescribed } \mathcal{HOU} \text{-derivation from } \mathcal{E}.$			
P.1 This must be finite, since \prec is well-founded (ind. over length n of \mathcal{D})			
${f P.2}$ If $n=0$, then ${\cal E}$ is solved and $\sigma_{\cal E}$ most general unifier			
$\mathbf{P.3}$ thus $\sigma_{\mathcal{E}} \leq_{eta\eta} heta[\mathcal{E}]$			
P.4 If $n > 0$, then there is a μ -prescribed step $\mathcal{E} \vdash_{\mathcal{HOU}} \mathcal{E}'$ and a substitution θ' as in Theorem 15.3.9.			
$\textbf{P.5} \text{ by IH there is a } \mathcal{HOU}\text{-derivation } \mathcal{E}' \vdash_{\mathcal{HOU}} \mathcal{F} \text{ with } \sigma_{\mathcal{F}} \leq_{\beta\eta} \theta'[\mathcal{E}'].$			
P.6 by correctness $\sigma_{\mathcal{F}} \in \mathbf{U}(\mathcal{E}') \subseteq \mathbf{U}(\mathcal{E})$.			
P.7 rules of \mathcal{HOU} only expand free variables, so $\sigma_{\mathcal{F}} \leq_{\beta\eta} \theta'[\mathcal{E}']$			
$\mathbf{P.8}$ Thus $\sigma_{\mathcal{F}} \leq_{eta\eta} heta'[\mathcal{E}]$,			
P.9 This completes the proof, since $\theta' =_{\beta\eta} \theta[\mathcal{E}]$ by Theorem 15.3.9. \Box			
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We now recap the properties of higher-order unification (HOU) to gain an overview.

Properties of	HO-Unification		
⊳ HOU is undec	idable, HOU need not have mos	st general unifiers	
▷ The HOU tra of higher-order	nsformation induce an algorithm [.] unifiers.	that enumerates a co	mplete set
$ hightarrow \mathcal{HOU}$:ff gives enormous degree of indeterminism			
▷ HOU is intractable in practice consider restricted fragments where it is!			
⊳ HO Matching	(decidable up to order four), He	O Patterns (unitary, li	near),
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15.4 Pre-Unification

We will now come to a variant of higher-order unification that is used in higher-order theorem proving, where we are only interested in the exgistence of a unifier – e.g. in mating-style tableaux. In these cases, we can do better than full higher-order unification.





The higher-order pre-unification algorithm can be obtained from \mathcal{HOU} by simply omitting the offending \mathcal{HOU} : ff rule.



15.5 Applications of Higher-Order Unification





Chapter 16

Simple Type Theory

In this Chapter we will revisit the higher-order predicate logic introduced in Chapter 9 with the base given by the simply typed λ -calculus. It turns out that we can define a higher-order logic by just introducing a type of propositions in the λ -calculus and extending the signatures by logical constants (connectives and quantifiers).



There is a more elegant way to treat quantifiers in HOL^{\rightarrow} . It builds on the realization that the λ -abstraction is the only variable binding operator we need, quantifiers are then modeled as second-order logical constants. Note that we do not have to change the syntax of HOL^{\rightarrow} to introduce quantifiers; only the "lexicon", i.e. the set of logical constants. Since Π^{α} and Σ^{α} are logical constants, we need to fix their semantics.

Higher-Order Abstract Syntax

- \rhd ldea: In $HOL^{\rightarrow},$ we already have variable binder: $\lambda,$ use that to treat quantification.
- \triangleright **Definition 16.0.2** We assume logical constants \prod^{α} and \sum^{α} of type $(\alpha \rightarrow o) \rightarrow$

Regain quantifiers as abbreviations:

о.

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$$(\forall X_{\alpha}.\mathbf{A}) := \prod_{\alpha}^{\alpha} (\lambda X_{\alpha}.\mathbf{A}) \qquad (\exists X_{\alpha}.\mathbf{A}) := \sum_{\alpha}^{\alpha} (\lambda X_{\alpha}.\mathbf{A})$$

 \triangleright Definition 16.0.3 We must fix the semantics of logical constants:

1) $\mathcal{I}(\Pi^{lpha})(p) = T$, iff $p(a) = T$ for all $a \in \mathcal{D}_{lpha}$	(i.e.	if p	is the	universa	l set)
2) $\mathcal{I}(\Sigma^{\alpha})(p) = T$, iff $p(a) = T$ for some $a \in \mathcal{D}$,	α	(i.e.	$\operatorname{iff} p$ i	s non-en	npty)

 \triangleright With this, we re-obtain the semantics we have given for quantifiers above:

$$\mathcal{I}_{\varphi}(\forall X_{\iota} \cdot \mathbf{A}) = \mathcal{I}_{\varphi}(\stackrel{\iota}{\Pi}(\lambda X_{\iota} \cdot \mathbf{A})) = \mathcal{I}(\stackrel{\iota}{\Pi})(\mathcal{I}_{\varphi}(\lambda X_{\iota} \cdot \mathbf{A})) = \mathsf{T}$$
iff $\mathcal{I}_{\varphi}(\lambda X_{\iota} \cdot \mathbf{A})(a) = \mathcal{I}_{[a/X],\varphi}(\mathbf{A}) = \mathsf{T}$ for all $a \in \mathcal{D}_{\alpha}$

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But there is another alternative of introducing higher-order logic due to Peter Andrews. Instead of using connectives and quantifiers as primitives and defining equality from them via the Leibniz indiscernability principle, we use equality as a primitive logical constant and define everything else from it.

Alternative: HOL⁼ \triangleright only one logical constant $q^{\alpha} \in \Sigma_{\alpha \to \alpha \to o}$ with $\mathcal{I}(q^{\alpha})(a,b) = \mathsf{T}$, iff a = b. \triangleright Definitions (D) and Notations (N) $\mathbf{A}_{\alpha} = \mathbf{B}_{\alpha}$ for $q^{\alpha} \mathbf{A}_{\alpha} \mathbf{B}_{\alpha}$ Ν for $q^o = q^o$ D Tfor $(\lambda X_o \cdot T) = (\lambda X_o \cdot X_o)$ D Ffor $q^{(\alpha \to o)}(\lambda X_{\alpha} \cdot T)$ D Π^{α} Ν $\forall X_{\alpha} \cdot \mathbf{A}$ for $\Pi^{\alpha}(\lambda X_{\alpha} \cdot \mathbf{A})$ for $\lambda X_o \cdot \lambda Y_o \cdot (\lambda G_{o \to o \to o} \cdot G_T T) = (\lambda G_{o \to o \to o} \cdot GXY)$ D Λ Ν $\mathbf{A} \wedge \mathbf{B}$ for $\wedge \mathbf{A}_{o}\mathbf{B}_{o}$ D for $\lambda X_o \cdot \lambda Y_o \cdot X = X \wedge Y$ \Rightarrow Ν $\mathbf{A} \Rightarrow \mathbf{B}$ for $\Rightarrow \mathbf{A}_{o}\mathbf{B}_{o}$ D for $q^o F$ for $\lambda X_o \cdot \lambda Y_o \cdot \neg (\neg X \land \neg Y)$ D V $\mathbf{A} \lor \mathbf{B}$ for $\forall \mathbf{A}_{o} \mathbf{B}_{o}$ Ν $\exists X_{\alpha} \cdot \mathbf{A}_{o}$ D for $\neg (\forall X_{\alpha} \cdot \neg \mathbf{A})$ $\mathbf{A}_{\alpha} \neq \mathbf{B}_{\alpha}$ for $\neg (q^{\alpha} \mathbf{A}_{\alpha} \mathbf{B}_{\alpha})$ Ν \triangleright yield the intuitive meanings for connectives and quantifiers. © (c): Michael Kohlhase 148

In a way, this development of higher-order logic is more foundational, especially in the context of Henkin semantics. There, Theorem 10.0.6 does not hold (see [And72] for details). Indeed the proof of Theorem 10.0.6 needs the existence of "singleton sets", which can be shown to be equivalent to the existence of the identity relation. In other words, Leibniz equality only denotes the equality
relation, if we have an equality relation in the models. However, the only way of enforcing this (remember that Henkin models only guarantee functions that can be explicitly written down as λ -terms) is to add a logical constant for equality to the signature.

We will conclude this section with a discussion on two additional "logical constants" (constants with a fixed meaning) that are needed to make any progress in mathematics. Just like above, adding them to the logic guarantees the existence of certain functions in Henkin models. The most important one is the description operator that allows us to make definite descriptions like "the largest prime number" or "the solution to the differential equation f' = f.





Chapter 17

Higher-Order Tableaux

In this Chapter we will extend the ideas from first-order tableaux to higher-order logic.

The rules fo standard tableaux are just like the ones for first-order logic, only that we can take advantage of higher-order abstract syntax for the quantifiers



Higher-order, free-variable tableaux work exactly like first-order tableaux, except that the cut rule uses higher-order unification.

Higher-Order Free-Variable Tableaus $(\mathcal{T}_{\omega} \text{ first try})$ \triangleright Definition 17.0.2 The \mathcal{T}_{ω} calculus consists of the propositional tableau rules plus $\frac{\prod \mathbf{A}^{t}}{\mathbf{A}X_{\alpha}^{t}}\mathcal{T}_{\omega}$: \forall $\frac{\prod \mathbf{A}^{f} \quad \text{free}(\mathbf{A}) = \{Y_{\alpha_{1}}^{1}, \dots, Y_{\alpha_{n}}^{n}\} \quad f \in \Sigma_{\alpha_{n} \to \alpha}^{Sk} \text{ new}}{\mathbf{A}(f\overline{Y^{n}})^{f}}\mathcal{T}_{\omega}$: \exists \triangleright Problem: Unification in Λ^{\rightarrow} is undecidable, so we need more Note that we cannot directly use the higher-order unification algorithm, since that is undecidable – this would not result in a fair proof search procedure. Therefore we reinterpret HOPU rules as tableau rules and mix them into the proof search procedure.

For the reinterpretation of \mathcal{HOU} rules into tableau rules we change notation of the unification pairs, using $\mathbf{A} \neq^{?} \mathbf{B}$ instead of $\mathbf{A} =^{?} \mathbf{B}$, since in the tableau setting we want to refute that \mathbf{A} and \mathbf{B} cannot be made equal instead of finding conditions that make them equal (as we did for unification). Correspondingly, we we do not use a "conjunction" of equations, but a disjunction (using tableau branches) of "disequations". But up to this "double negation" the unification algorithm stays the same.



Note that the elimination rule is particularly elegant in the tableau setting – it comes in the form of a closure rule: If we have a solved pair, then we can just make the branch unsatisfiable by applying its most general unifier to the whole tableau.

Note furthermore, that with the mixed propositional and pre-unification calculus in \mathcal{T}_{ω} , the decision whether to do regular or matings-style tableaux boils down to a decision of the strategy used to expand the \mathcal{T}_{ω} tableaux.

We will now fortify our intuition with an extended example: a \mathcal{T}_{ω} proof of (a version of) Cantor's theorem. The particular formulation we use below uses the whole universe of type ι for the set S and universe of type $\iota \to \iota$ for the power set.



We initialize the tableau with the three formulae discussed above, and then employ the \mathcal{T}_{ω} rules.

 \vartriangleright then we continue with unification tableau



In the higher-order unification tableau above we face the same problem we always face when we try to display the dynamics of free-variable tableaux: in the closure rules we have to instantiate the whole tableau. But this turns the tableau into a standard tableau. So we close the leftmost branch and apply the substitution to the branches to the right of the current branch only.

Note that at first sight $N \neq j G$ is not solved (and indeed unsolvable), since j is a Skolem constant. But we only need to forbid the Skolem constants that were introduced by the $SIM:\alpha$ and $SIM:\eta$ rules. So there is no problem here; since they were introduced by $\mathcal{T}_{\omega}:\exists$.

Even though we were successful in proving Cantor's theorem, \mathcal{T}_{ω} is not complete as we will see.



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We see that unlike in first-order unification we cannot obtain all necessary instantiations by unification. Indeed in the presence of predicate variables – in our example above we can view X_o as a nullary predicate – we have to allow instantiations with (all) logical connectives and quantifiers. Fortunately, we can do this in a minimally committing fashion via general bindings, unfortunately, we have to systematically try out all possible ones – which is costly, since there are infinitely many quantifiers.

Primitive Substitutions ho Unification is not sufficient for \mathcal{T}_ω > We need a rule that instantiates head variables with terms that introduce logical constants. \triangleright **Definition 17.0.6** We extend \mathcal{T}_{ω} with the rule \mathcal{T}_{ω} :prim. $\frac{X_{\alpha}\overline{\mathbf{U}^{n}}^{\alpha} \quad \mathbf{G} \in \mathbf{G}_{\alpha}^{k}(\Sigma) \quad k \in (\{\wedge, \neg\} \cup \{\prod^{\beta} \mid \beta \in \mathcal{T}\})}{X \neq^{?} \mathbf{G} \mid X_{\alpha}\overline{\mathbf{U}^{n}}^{\alpha}} \mathcal{T}_{\omega}:\mathsf{prim}$ We call $[\mathbf{G}/X]$ a primitive substitution. \triangleright In our example $\neg Q = \mathbf{G}_{o}^{\neg}(\Sigma).$ JACOBS UNIVERSI (C): Michael Kohlhase 157

There is another source of incompleteness as another example shows: we can have propositions embedded in formulae. Note that this is different from the situation in first-order logic, but quite natural in mathematics, e.g. for conditional statements of the form "if φ_o then \mathbf{A}_{α} else \mathbf{B}_{α} .", where φ is a proposition embedded in a term of type α .

Another Example

 $\triangleright \mathbf{A} = \neg (c_{o \to o} b_o) \lor (c \neg \neg b) \text{ is valid}$ $\triangleright \mathcal{T}_{\omega} \text{ proof attempt}$

$$(cb) \lor (c\neg \neg b)$$

$$\neg (cb)^{f}$$

$$c\neg \neg b^{f}$$

$$cb^{t}$$

$$cb \neq^{?} c\neg \neg b$$

$$b \neq^{?} \neg \neg b$$

and we are stuck (again)

- \triangleright Idea: theory unification with $X_o = \neg \neg X_o$
- \triangleright But the problem is more general: If $\mathbf{A} \Leftrightarrow \mathbf{B}$ valid, then $\neg(c\mathbf{A}) \land (c\mathbf{B})$ must be \mathcal{T}_{ω} -refutable.

▷ Solution: call to the theorem prover recursively.



The \mathcal{T}_{ω} :rec rule puts the propositional and unification rules of \mathcal{T}_{ω} at an equal footing. \mathcal{T}_{ω} can be seen as a calculus for theorem proving or as an unification algorithm that takes the theory of equivalence into account.

Each aspect of \mathcal{T}_{ω} can recurse into the the other; this is necessary, since in HOL^{\rightarrow} the propositional level – which has a fixed interpretation and therefore special \mathcal{T}_{ω} rules – and the term level – which is freely interpreted and must thus be handled by unification – can recurse arbitrarily.

To make matters worse, we also have a soundness problem that comes from Skolemization: we can prove a version of the Axiom of Choice that is known to be independent of HOL^{\rightarrow} , and thus should not be provable.



In this proof, the Skolem constant f introduced for the assumption $\forall X_{\alpha} . \exists Y_{\alpha} . RXY$ becomes available as an instance for the variable F in (used to require the existence of a choice operator).

Skolemization is not sound (Choice Proof)



In first-order logic, Skolemization is sound, since Skolem constants do not "lose their arguments", so they cannot be used to prove the axiom of choice.

The following part is still experimentals; not required for the course



Higher-Order Tableaux (final)

 \triangleright Higher-order tableaux are triples $\langle \Gamma \colon \mathcal{R} \rangle$. \mathcal{T}

 \triangleright propositional tableaux as always

(do not change Γ or \mathcal{R})

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 \triangleright New quantifier rules

$$\frac{\prod_{\alpha}^{\alpha} \mathbf{A}^{\mathsf{t}}}{\mathbf{A} X_{\alpha}^{\mathsf{t}}} \qquad \frac{\prod_{\alpha}^{\alpha} \mathbf{A}^{\mathsf{f}}}{\mathbf{A} Y^{-\mathsf{f}}}$$

where

$$> X, Y^{-} \notin \mathbf{dom}(\Gamma)$$

> $\Gamma' := \Gamma, [X : \alpha] \text{ and } \Gamma' := \Gamma, [Y^{-} : \alpha]$
> $\mathcal{R}' := \mathcal{R} \text{ and } \mathcal{R}' := \mathcal{R} \cup (\text{free}(\mathbf{A}) \times \{Y^{-}\}).$

- \triangleright substitution rule: If a path in $\langle \Gamma, [X : \alpha] : \mathcal{R} \rangle \cdot \mathcal{T}$ ends in an equation $X = {}^{?}\mathbf{A}$ with $\Gamma \vdash_{\Sigma} \overline{\mathcal{R}}(X, \mathbf{A})$, then generate $\langle \Gamma : \mathcal{R}(\mathbf{A}/X) \rangle \cdot [\mathbf{A}/X]\mathcal{T}$.
- $$\begin{split} & \succ \text{ Primitive Substitution: If } \langle \Gamma, [X:\alpha] \colon \mathcal{R} \rangle \cdot \mathcal{T} \text{ contains a formula } (X\overline{\mathbf{U}^n})^{\alpha} \text{, and} \\ & \mathbf{A} \in \mathbf{G}^k_{\alpha}(\Sigma, \Gamma, \mathcal{C}) \text{ with } k \in (\{\wedge, \neg\} \cup \{\Pi^{\beta} \mid \beta \in \mathcal{T}\}) \text{, then generate } \langle \Gamma \cup \mathcal{C} \colon \mathcal{R}(\mathbf{A}/X) \rangle \cdot [\mathbf{A}/X]\mathcal{T} \end{split}$$
- \triangleright Closed Tableau: every branch ends in a trivial equation $\mathbf{A} = {}^{?} \mathbf{A}$ or a pre-solved equation $F\overline{\mathbf{U}} \neq {}^{?} G\overline{\mathbf{V}}$.
- \vartriangleright tableau-substitution closes the respective branch
- $\vartriangleright \mathsf{Side} \mathsf{ conditions}$

$$\frac{(\lambda X_{\alpha} \cdot \mathbf{A}) \neq^{?} (\lambda Y_{\alpha} \cdot \mathbf{B}) \quad Z \notin \operatorname{dom}(\Gamma)}{[Z/X](\mathbf{A}) \neq^{?} Z(Y)(\mathbf{B})}$$

$$\frac{(\lambda X_{\alpha} \cdot \mathbf{A}) \neq^{?} \mathbf{B} \quad Z \notin \operatorname{dom}(\Gamma)}{[Z/X](\mathbf{A}) \neq^{?} \mathbf{B}Z}$$

where $\Gamma' = \Gamma, [Z^0 : \alpha]$ and $\mathcal{R}' := \mathcal{R}(Z/X)$

$$\frac{h\overline{\mathbf{U}^{n}}\neq^{?}h\overline{\mathbf{V}^{n}} \quad h\in(\Sigma\cup\operatorname{\mathbf{dom}}(\Gamma^{0})\cup\operatorname{\mathbf{dom}}(\Gamma^{-}))}{\mathbf{U}^{1}\neq^{?}\mathbf{V}^{1}\mid\ldots\mid\mathbf{U}^{n}\neq^{?}\mathbf{V}^{n}}$$
$$\frac{F\overline{\mathbf{U}}=^{?}h\overline{\mathbf{V}}\quad\Gamma(F)=\alpha\quad\Gamma\vdash_{\Sigma}\overline{\mathcal{R}}(F,\mathbf{G})}{F\neq^{?}\mathbf{G}\mid F\overline{\mathbf{U}}\neq^{?}h\overline{\mathbf{V}}}$$

Here we have

 $\triangleright \ \mathbf{G} \in \mathbf{G}^h(\Sigma, \Delta, \mathcal{C})$ $\triangleright \ \Gamma' = \Gamma \cup \mathcal{C} \text{ and } \mathcal{R}' := \mathcal{R}$

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Part IV

Axiomatic Set Theory (ZFC)

Sets are one of the most useful structures of mathematics. They can be used to form the basis for representing functions, ordering relations, groups, vector spaces, etc. In fact, they can be used as a foundation for all of mathematics as we know it. But sets are also among the most difficult structures to get right: we have already seen that "naive" conceptions of sets lead to inconsistencies that shake the foundations of mathematics.

There have been many attempts to resolve this unfortunate situation and come up a "foundation of mathematics": an inconsistency-free "foundational logic" and "foundational theory" on which all of mathematics can be built.

In this Part we will present the best-known such attempt – and an attempt it must remain as we will see – the axiomatic set theory by Zermelo and Fraenkel (ZFC), a set of axioms for first-order logic that carefully manage set comprehension to avoid introducing the "set of all sets" which leads us into the paradoxes.

Recommended Reading: The – historical and personal – background of the material covered in this Part is delightfully covered in [DPPDD09].

Chapter 18

Naive Set Theory

We will first recap "naive set theory" and try to formalize it in first-order logic to get a feeling for the problems involved and possible solutions.

(Naive) Set Theory [Can95, Can97] > Definition 18.0.1 A set is "everything that can form a unity in the face of God". (Georg Cantor (*1845, †1918)) \triangleright Example 18.0.2 (determination by elementhood relation \in) \triangleright "the set that consists of the number 7 and the prime divisors of 510510" \triangleright {7, c}, {1, 2, 3, 4, 5n, ...}, {x | x is an integer}, {X | P(X)} Questions (extensional/intensional): $\triangleright \quad \triangleright \text{ If } c = 7, \text{ is } \{7, c\} = \{7\}?$ $\triangleright \mathsf{ls} \{X \mid X \in \mathbb{N}, X \neq X\} = \{X \mid X \in \mathbb{N}, X^2 < 0\}?$ \triangleright yes \rightsquigarrow extensional; no \rightsquigarrow intensional; V JACOBS (C): Michael Kohlhase 163

Georg Cantor was the first to systematically develop a "set theory", introducing the notion of a "power set" and distinguishing finite from infinite sets – and the latter into denumerable and uncountable sets, basing notions of cardinality on bijections.

In doing so, he set a firm foundation for mathematics¹, even if that needed more work as was later discovered.

Now let us see whether we can write down the "theory of sets" as envisioned by Georg Cantor in first-order logic – which at the time Cantor published his seminal articles was just being invented by Gottlob Frege. The main idea here is to consider sets as individuals, and only introduce a single predicate – apart from equality which we consider given by the logic: the binary elementhood predicate.

(Naive) Set Theory: Formalization

¹David Hilbert famously exclaimed "No one shall expel us from the Paradise that Cantor has created" in [Hil26, p. 170]



The central here is the comprehension axiom that states that any set we can describe by writing down a frist-order formula \mathbf{E} – which usually contains the variable X – must exist. This is a direct implementation of Cantor's intuition that sets can be "... everything that forms a unity ...". The usual set-theoretic operators \cup , \cap , ... can be defined by suitable axioms.

This formalization will now allow to understand the problems of set theory: with great power comes great responsibility!



The culprit for the paradox is the comprehension axiom that guarantees the existence of the "set of all sets" from which we can then separate out Russell's set. Multiple ways have been proposed to get around the paradoxes induced by the "set of all sets". We have already seen one: (typed) higher-order logic simply does not allow to write down MM which is higher-order (sets-as-predicates) way of representing set theory.

The way we are going to exploren now is to remove the general set comprehension axiom we had introduced above and replace it by more selective ones that only introduce sets that are known to be safe.

Chapter 19

ZFC Axioms

We will now introduce the set theory axioms due to Zermelo and Fraenkel.

We write down a first-order theory of sets by declaring axioms in first-order logic (with equality). The basic idea is that all individuals are sets, and we can therefore get by with a single binary predicate: \in for elementhood.



Note that we do not have a general comprehension axiom, which allows the construction of sets from expressions, but the separation axiom **Sep**, which – given a set – allows to "separate out" a subset. As this axiom is insufficient to providing any sets at all, we guarantee that there is one in **Ex** to make the theory less boring.

Before we want to develop the theory further, let us fix the success criteria we have for our foundation.

Quality Control
Participation: Is ZFC good? (make this more precise under various views)
foundational: Is ZFC sufficient for mathematics?

adequate: is th	e ZFC notion of sets adequate	2?	
formal: is ZFC	consistent?		
ambitious: ls Z	FC complete?		
pragmatic: Is the formalization convenient?			
${f computational:}$ does the formalization yield computation-guiding structure?			
▷ Questions like these help us determine the quality of a foundational system or theory.			
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The question about consistency is the most important, so we will address it first. Note that the absence of paradoxes is a big question, which we cannot really answer now. But we *can* convince ourselves that the "set of all sets" cannot exist.

low about Russel's Antinomy?			
▷ Theorem 19.0.4 There is no universal set			
⊳ Proof:			
P.1 For each set M , there is a set $M_R := \{X \in M \mid X \notin X\}$ by Sep. P.2 show $\forall M \cdot M_R \notin M$			
P.3 If $M_R \in M$, then $M_R \notin M_R$, (also if $M_R \notin M$)			
P.4 thus $M_R \notin M$ or $M_R \in M_R$.			
$Dash$ to get the paradox we would have to separate from the universal set \mathcal{A} , to get $\mathcal{A}_R.$			
ightarrow Great, then we can continue developing our set theory!			
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Somewhat surprisingly, we can just use Russell's construction to our advantage here. So back to the other questions.



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So we have identified at least interesting set, the empty set. Unfortunately, the existence of the intersection operator is no big help, if we can only intersect with the empty set. In general, this is a consequence of the fact that \mathbf{Sep} – in contrast to the comprehension axiom we have abolished – only allows to make sets "smaller". If we want to make sets "larger", we will need more axioms that guarantee these larger sets. The design contribution of axiomatic set theories is to find a balance between "too large" – and therefore paradoxical – and "not large enough" – and therefore inadequate.

Before we have a look at the remaining axioms of ZFC, we digress to a very influential experiment in developing mathematics based on set theory.

"Nicolas Bourbaki" is the collective pseudonym under which a group of (mainly French) 20thcentury mathematicians, with the aim of reformulating mathematics on an extremely abstract and formal but self-contained basis, wrote a series of books beginning in 1935. With the goal of grounding all of mathematics on set theory, the group strove for rigour and generality.

Is Set theory enoug	gh? → Nicolas Bourbak	i	
 ▷ Is it possible to develop all of Mathematics from set theory? → N. Bourbaki: Éléments de Mathématiques (there is only one mathematics) 			
⊳ Original Goal: A mod	ern textbook on calculus.		
ightarrow Result: 40 volumes in nine books from 1939 to 1968			
Set Theory [Bou68] Algebra [Bou74] Topology [Bou89]	Functions of one real variable Integration Topological Vector Spaces	Commutative Algeb Lie Theory Spectral Theory	ra
⊳ Contents:			
 starting from set theory all of the fields above are developed. All proofs are carried out, no references to other books. 			
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Even though Bourbaki has dropped in favor in modern mathematics, the universality of axiomatic set theory is generally acknowledged in mathematics and their rigorous style of exposition has influenced modern branches of mathematics.

The first two axioms we add guarantee the unions of sets, either of finitely many $- \bigcup A \mathbf{x}$ only guarantees the union of two sets – but can be iterated. And an axiom for unions of arbitrary families of sets, which gives us the infinite case. Note that once we have the ability to make finite sets, $\bigcup A \mathbf{x}$ makes $\cup A \mathbf{x}$ redundant, but minimality of the axiom system is not a concern for us currently.

The Axioms for Set Union

▷ Axiom 19.0.6 (Small Union Axiom (\cup Ax)) For any sets M and N there is a set W, that contains all elements of M and N. $\forall M, N . \exists W . \forall X . (X \in M \lor X \in N) \Rightarrow X \in W$



In Definition 19.0.10 we note that $\bigcup \mathbf{Ax}$ also guarantees us intersection over families. Note that we could not have defined that in analogy to Definition 19.0.5 since we have no set to separate out of. Intuitively we could just choose one element N from M and define

$$\bigcap(M) := \{ Z \in N \mid \forall X \cdot X \in M \Rightarrow Z \in X \}$$

But for choice from an infinite set we need another axiom still.

The power set axiom is one of the most useful axioms in ZFC. It allows to construct finite sets.

The Power Set Axiom

▷ Axiom 19.0.11 (Power Set Axiom) For each set *M* there is a set *W* that contains all subsets of *M*: \wp Ax := $(\forall M.\exists W.\forall X.(X\subseteq M) \Rightarrow X \in W)$ ▷ Definition 19.0.12 Power Set: $\mathcal{P}(M) := \{X \mid X\subseteq M\}$ (Exists by Sep.)
▷ Definition 19.0.13 singleton set: $\{X\} := \{Y \in \mathcal{P}(X) \mid X = Y\}$ ▷ Axiom 19.0.14 (Pair Set (Axiom)) (is often assumed instead of \cup Ax)
Given sets *M* and *N* there is a set *W* that contains exactly the elements *M* and *N*: $\forall M, N.\exists W.\forall X.X \in W \Leftrightarrow (X = N) \lor (X = M)$ ▷ Is derivable from \wp Ax: $\{M, N\} := \{M\} \cup \{N\}$.
▷ Definition 19.0.15 (Finite Sets) $\{X, Y, Z\} := \{X, Y\} \cup \{Z\}...$ ▷ Theorem 19.0.16 $\forall Z, X_1, ..., X_n.Z \in \{X_1, ..., X_n\} \Leftrightarrow Z = X_1 \lor ... \lor Z = X_n$ ©: Michael Kohlhase

The Foundation Axiom

▷ Axiom 19.0.17 (The foundation Axiom (Fund)) Every non-empty set has a \in -minimal element,. $\forall X \cdot X \neq \emptyset \Rightarrow (\exists Y \cdot Y \in X \land \neg (\exists Z \cdot Z \in X \land Z \in Y))$



Zermelo Fraenkel Set Theory

Definition 19.0.26 (Zermelo Fraenkel Set Theory) We call the firstorder theory given by the axioms below Zermelo/Fraenkel set theory and denote it by ZF.

F w	$\exists V \ V = V$		
Ex	$ \exists A , A \equiv A $	(\mathcal{N})	
Ext	$\forall M, N, M = N \Leftrightarrow (\forall X, X \in M \Leftrightarrow X)$	$i \in N$)	
Sep	$\forall N \exists M \forall Z Z \in M \Leftrightarrow Z \in N \land \mathbf{E}$		
$\cup \mathbf{Ax}$	$\forall M, N . \exists W . \forall X . (X \in M \lor X \in N)$	$\Rightarrow X \in W$	
$\bigcup \mathbf{Ax}$	$\forall M. \exists W. \forall X, Y. Y \in M \Rightarrow X \in Y \Rightarrow$	$r X \in W$	
℘Ax	$\forall M . \exists W . \forall X . (X \subseteq M) \Rightarrow X \in W$		
$\infty \mathbf{A} \mathbf{x}$	$\exists M . \emptyset \in M \land (\forall Z . Z \in M \Rightarrow (Z \cup \{Z \}))$	$Z\}) \in M)$	
Rep	$(\forall X . \exists^1 Y . \mathbf{P}(X, Y)) \Rightarrow (\forall U . \exists V . \forall X$	$, Y \cdot X \in U \land \mathbf{P}(X, Y)$	$Y \to Y \in V$
Fund	$\forall X \cdot X \neq \emptyset \Rightarrow (\exists Y \cdot Y \in X \land \neg (\exists Z \cdot Z))$	$Z \in X \land Z \in Y))$	
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The Axiom of Choice

- \triangleright Axiom 19.0.27 (The axiom of Choice :AC) For each set X of nonempty, pairwise disjoint subsets there is a set that contains exactly one element of each element of X.
- $\forall X, Y, Z \cdot Y \in X \land Z \in X \Rightarrow Y \neq \emptyset \land (Y = Z \lor Y \cap Z = \emptyset) \Rightarrow \exists U \cdot \forall V \cdot V \in X \Rightarrow (\exists W \cdot U \cap V = \{W\})$
- \triangleright This axiom assumes the existence of a set of representatives, even if we cannot give a construction for it. \rightsquigarrow we can "pick out" an arbitrary element.

 \triangleright Reasons for **AC**:

- \triangleright Neither $\mathbf{ZF} \vdash \mathbf{AC}$, nor $\mathbf{ZF} \vdash \neg \mathbf{AC}$
- \triangleright So it does not harm?
- ▷ Definition 19.0.28 (Zermelo Fraenkel Set Theory with Choice) The theory ZF together with AC is called ZFC with choice and denoted as ZFC.

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Chapter 20

ZFC Applications

Limits of ZFC

- Conjecture 20.0.1 (Cantor's Continuum Hypothesis (CH)) There is no set whose cardinality is strictly between that of integers and real numbers.
- ▷ Theorem 20.0.2 If ZFC is consistent, then neither CH nor ¬ CH can be derived.
 (CH is independent of ZFC)
- \rhd The axiomatzation of ${\bf ZFC}$ does not suffice
- \triangleright There are other examples like this.

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Ordered Pairs

 \triangleright Empirically: In ZFC we can define all mathematical concepts.

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 \triangleright For Instance: We would like a set that behaves like an odererd pair

- \triangleright Definition 20.0.3 Define $\langle X, Y \rangle := \{ \{X\}, \{X, Y\} \}$
- $\rhd \textbf{Lemma 20.0.4} \langle X,Y\rangle = \langle U,V\rangle \Rightarrow X = U \land Y = V$
- $\triangleright \text{ Lemma 20.0.5 } U \in X \land V \in Y \Rightarrow \langle U, V \rangle \in \mathcal{P}(\mathcal{P}(X \cup Y))$
- $\triangleright \text{ Definition 20.0.6 left projection: } \pi_l(X) = \begin{cases} U & \text{if } \exists V.X = \langle U, V \rangle \\ \emptyset & \text{if } X \text{ is no pair} \end{cases}$

 \triangleright **Definition 20.0.7 right projection** π_r analogous.

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Relations

 \rhd All mathematical objects are represented by sets in ${\bf ZFC}$, in particular relations

- \triangleright **Definition 20.0.8** The Cartesian produkt of X and Y $X \times Y := \{ Z \in \mathcal{P}(\mathcal{P}(X \cup Y)) \mid Z \text{ is ordered pair with } \pi_l(Z) \in X \land \pi_r(Z) \in Y \}$ A relation is a subset of a Cartesian product.
- \triangleright Definition 20.0.9 The domain and codomain of a function are defined as usual

but they (as first-order functions) must be total, so we (arbitrarily) extend them by the empty set for non-relations





Functions

 \triangleright Definition 20.0.10 A function f from X to Y is a right-unique relation with Dom(f) = X and coDom(f) = Y; write $f: X \to Y$.

 $\triangleright \text{ Definition 20.0.11 function application: } f(X) = \begin{cases} Y & \text{if } f \text{ function and } \langle X, Y \rangle \\ \emptyset & \text{else} \end{cases}$

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Part V

Knowledge Representation

In the third and final part of the course, we will look into logic-based formalisms for knowledge representation and their application in the "Semantic Web".

The field of "Knowledge Representation" is usually taken to be an area in Artificial Intelligence that studies the representation of knowledge in formal system and how to leverage inferencing techniques to generate new knowledge items from existing ones.

Note that this definition coincides with what we know as "logical systems" in this course. This is the view taken by the subfield of "description logics", but restricted to the case, where the logical systems have a entailment relation to ensure applicability.

This Part is organized as follows. We will first give a general introduction to the concepts of knowledge representation using semantic networks – an early and very intuitive approach to knowledge representation – as an object-to-think-with. In Chapter 21 we introduce the principles and services of logic-based knowledge-representation using a non-standard interpretation of propositional logic as the basis, this gives us a formal account of the taxonomic part of semantic networks. In Chapter 22 we introduce the logic \mathcal{ACC} that adds relations (called "roles") and restricted quantification and thus gives us the full expressive power of semantic networks. Thus \mathcal{ACC} can be seen as a prototype description logic. In Chapter 23 we show how description logics are applied as the basis of the "semantic web", and finally in Chapter 24 we show various extensions of \mathcal{ACC} an their inference procedures.

Chapter 21

Introduction to Knowledge Representation

Before we start into the development of description logics, we set the stage by looking into alternatives for knowledge representation.

21.1 Knowledge & Representation

To approach the question of knowledge representation, we first have to ask ourselves, what knowledge might be. This is a difficult question that has kept philosophers occupied for millennia. We will not answer this question in this course, but only allude to and discuss some aspects that are relevant to our cause of knowledge representation.



According to an influential view of [PRR97], knowledge is appears in layers. Staring with a character set that defines a set of glyphs, we can add syntax that turns mere strings into data.

Adding context information gives information, and finally, by relating the information to other information allows to draw conclusions, turning information into knowledge.

Note that we already have aspects of representation and function in the diagram at the top of the slide. In this, the additional functions added in <th successive layers give the representations more and more function, until we reach the knowledge level, where the function is given by inferencing. In the second example, we can see that representations determine possible functions.

Let us now strengthen our intuition about knowledge by contrasting knowledge representations from "regular" data structures in computation.



As knowledge is such a central notion in artificial intelligence, it is not surprising that there are multiple approaches to dealing with it. We will only deal with the first one and leave the others to self-study.



When assessing the relative strengths of the respective approaches, we should evaluate them with respect to a pre-determined set of criteria.



21.2 Semantic Networks

To get a feeling for early knowledge representation approaches from which description logics developed, we take a look at "semantic networks" and contrast them to logical approaches. Semantic networks are a very simple way of arranging concepts and their relations in a graph.



Even though the network in Example 21.2.2 is very intuitive (we immediately understand the

concepts depicted), it is unclear how we (and more importantly a machine that does not associate meaning with the labels of the nodes and edges) can draw inferences from the "knowledge" represented.

Another problem is that the semantic net in Example 21.2.2 confuses two kinds of concepts: individuals (represented by proper names like *John* and *Jack*) and concepts (nouns like *robin* and *bird*). Even though the "isa" and "inst" links already acknowledge this distinction, the "has_part" and "loves" relations are at different levels entirely, but not distinguished in the networks.



But there are sever shortcomings of semantic networks: the suggestive shape and node names give (humans) a false sense of meaning, and the inference rules are only given in the process model (the implementation of the semantic network processing system).

This makes it very difficult to assess the strength of the inference system and make assertions e.g. about completeness.





To alleviate the perceived drawbacks of semantic networks, we can contemplate another notation that is more linear and thus more easily implemented: function/argument notation.



Indeed the function/argument notation is the immediate idea how one would naturally represent semantic networks for implementation.

This notation has been also characterized as subject/predicate/object triples, alluding to simple (English) sentences. This will play a role in the "semantic web" later.

Building on the function/argument notation from above, we can now give a formal semantics for semantic networks: we translate into first-order logic and use the semantics of that.

A Denotational Semantics for Semantic Networks

 \triangleright Extension: take isa/inst concept/individual distinction into account



Indeed, the semantics induced by the translation to first-order logic, gives the intuitive meaning to the semantic networks. Note that this only holds only for the features of semantic networks that are representable in this way, e.g. the cancel links shown above are not (and that is a feature, not a bug).

But even more importantly, the translation to first-order logic gives a first process model: we can use first-order inference to compute the set of inferences that can be drawn from a semantic network.

Before we go on, let us have a look at an important application of knowledge representation technologies: the Semantic Web.

21.3 The Semantic Web



 Query: Who was US president in 1961?

 Google: President: Dwight D. Eisenhower [...] John F. Kennedy (starting January 20)

 Humans can read (and understand) the text and combine the information to get the answer.

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The term "Semantic Web" was coined by Tim Berners Lee in analogy to semantic networks, only applied to the world wide web. And as for semantic networks, where we have inference processes that allow us the recover information that is not explicitly represented from the network (here the world-wide-web).

To see that problems have to be solved, to arrive at the "Semantic Web", we will now look at a concrete example about the "semantics" in web pages. Here is one that looks typical enough.

What is the Information a User sees?	
WWW2002 The eleventh International World Wide Web Conference Sheraton Waikiki Hotel Honolulu, Hawaii, USA 7-11 May 2002	
Registered participants coming from Australia, Canada, Chile Denmark, France, Germany, Ghana, Hong Kong, India, Ireland, Italy, Japan, Malta, New Zealand, The Netherlands, Nor-	
way, Singapore, Switzerland, the United Kingdom, the United States, Vietnam, Zaire	
On the 7th May Honolulu will provide the backdrop of the eleventh International World Wide Web Conference.	
Speakers confirmed Tim Berners-Lee: Tim is the well known inventor of the Web, Ian Foster: Ian is the pioneer of the Grid, the next generation internet.	
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But as for semantic networks, what you as a human can see ("understand" really) is deceptive, so let us obfuscate the document to confuse your "semantic processor". This gives an impression of what the computer "sees".

What the machine sees $\mathcal{WWWe}''\in \mathcal{T}_{1}=\u(\mathcal{I}_{1})\nabla_{1}U(\mathcal{I}_{1})\nabla_{1}U(\mathcal{I}_{1})$



Obviously, there is not much the computer understands, and as a consequence, there is not a lot the computer can support the reader with. So we have to "help" the computer by providing some meaning. Conventional wisdom is that we add some semantic/functional markup. Here we pick XML without loss of generality, and characterize some fragments of text e.g. as dates.



What can we do with this?



We have to obfuscate the markup as well, since it does not carry any meaning to the machine intrinsically either.



So we have not really gained much either with the markup, we really have to give meaning to the markup as well, this is where techniques from knowledge representation come into play

To understand how we can make the web more semantic, let us first take stock of the current status of (markup on) the web. It is well-known that world-wide-web is a hypertext, where multimedia documents (text, images, videos, etc. and their fragments) are connected by hyperlinks. As we have seen, all of these are largely opaque (non-understandable), so we end up with the following situation (from the viewpoint of a machine).



Let us now contrast this with the envisioned semantic web.



Essentially, to make the web more machine-processable, we need to classify the resources by the concepts they represent and give the links a meaning in a way, that we can do inference with that.

The ideas presented here gave rise to a set of technologies jointly called the "semantic web", which we will now summarize before we return to our logical investigations of knowledge representation techniques.

Need to add "Semantics"
External agreement on meaning of annotations E.g., Dublin Core
Agree on the meaning of a set of annotation tags
Problems with this approach: Inflexible, Limited number of things can be



21.4 Other Knowledge Representation Approaches

Now that we know what semantic networks mean, let us look at a couple of other approaches that were influential for the development of knowledge representation. We will just mention them for reference here, but not cover them in any depth.



KR involving Time (Scripts [Shank '77])




Chapter 22

Logic-Based Knowledge Representation

We now turn to knowledge representation approaches that are based on some kind of logical system. These have the advantage that we know exactly what we are doing: as they are based on symbolic representations and declaratively given inference calculi as process models, we can inspect them thoroughly and even prove facts about them.

Logic-Based Knowledge Representation				
ho Logic (and related formalisms) have a well-defined semantics				
▷ explicitly	(gives more understanding than	statistical/neural met	hods)	
▷ transparently	(symbo	lic methods are mono [.]	tonic)	
▷ systematically	(we can prove th	eorems about our sys	tems)	
\triangleright Problems with logic-based approaches				
⊳ Where does t	he world knowledge come from?	(Ontology pro	blem)	
▷ How to guide search induced by log. calculi (combinatorial explosion)		osion)		
One possible answ	wer: Description Logics.	(next couple of t	times)	
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But of course logic-based approaches have big drawbacks as well. The first is that we have to obtain the symbolic representations of knowledge to do anything – a non-trivial challenge, since most knowledge does not exist in this form in the wild, to obtain it, some agent has to experience the word, pass it through its cognitive apparatus, conceptualize the phenomena involved, systematize them sufficiently to form symbols, and then represent those in the respective formalism at hand.

The second drawback is that the process models induced by logic-based approaches (inference with calculi) are quite intractable. We will see that all inferences can be played back to satisfiability tests in the underlying logical system, which are exponential at best, and undecidable or even incomplete at worst.

Therefore a major thrust in logic-based knowledge representation is to investigate logical systems that are expressive enough to be able to represent most knowledge, but still have a decidable – and maybe even tractable in practice – satisfiability problem. Such logics are called "description logics". We will study the basics of such logical systems and their inference procedures in the following.

22.1 Propositional Logic as a Set Description Language

Before we look at "real" description logics in Chapter 22, we will make a "dry run" with a logic we already understand: propositional logic, which we will re-interpret the system as a set description language by giving a new, non-standard semantics. This allows us to already preview most of the inference procedures and knowledge services of knowledge representation systems in the next Section.

To establish propositional logic as a set description language, we use a different interpretation than usual. We interpret propositional variables as names of sets and the logical connectives as set operations, which is why we give them a different – more suggestive – syntax.



We elaborate the idea of PL^0 as a set description language by giving a variant – set theoretic – semantics as well.

Set-Theoretic Semantics of Axioms $\triangleright \text{ Definition 22.1.2 (Formal Semantics)} \\ \text{Let } \mathcal{D} \text{ be a given set (called the domain) and } \varphi \colon \mathcal{V}_o \to \mathcal{P}(\mathcal{D}), \text{ then} \\ \triangleright \llbracket P \rrbracket := \varphi(P), (\text{remember } \varphi(P) \subseteq \mathcal{D}). \\ \triangleright \llbracket \mathbf{A} \sqcup \mathbf{B} \rrbracket = \llbracket \mathbf{A} \rrbracket \cup \llbracket \mathbf{B} \rrbracket \text{ and } \llbracket [\overline{\mathbf{A}} \rrbracket = \mathcal{D} \setminus \llbracket \mathbf{A} \rrbracket ... \\ \text{Let } \mathcal{L} \text{ be given by } \mathcal{L} :== C \mid \top \mid \bot \mid \overline{\mathcal{L}} \mid \mathcal{L} \sqcap \mathcal{L} \mid \mathcal{L} \sqcup \mathcal{L} \mid \mathcal{L} \sqsubseteq \mathcal{L} \mid \mathcal{L} \equiv \mathcal{L}, \text{ then} \\ \text{we denote the logical system } \mathcal{L}, \mathcal{D}, \llbracket \cdot \rrbracket \text{ with } \operatorname{PL}_{\mathrm{DL}}^0. \\ \triangleright \text{ Set-Theoretic Semantics of 'true' and 'false'} \qquad (\top = \varphi \sqcup \overline{\varphi} \quad \bot = \varphi \sqcap \overline{\varphi}) \\ \llbracket \bot \rrbracket = \llbracket p \rrbracket \cup \llbracket \overline{p} \rrbracket = \llbracket p \rrbracket \cup \varlimsup \overline{p} \rrbracket = \mathcal{D} \qquad \text{Analogously: } \llbracket \bot \rrbracket = \emptyset \\ \end{cases}$

Idea: Use logical a admissible domain	exioms to describe the world structures)	(Axioms restrict the	e class of
\gg Definition 22. domain \mathcal{D} iff $\llbracket \mathbf{A} rbracket$	1.3 (Set-Theoretic Seman = D	tics of Axioms) A	is true in
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The main use of the set-theoretic semantics for PL^0 is that we can use it to give meaning to "concept axioms", which we use to describe the "world".

Concept axioms are used to restrict the set of admissible domains to the intended ones. In our situation, we require them to be true – as usual – which here means that they denote the whole domain \mathcal{D} .

The set-theoretic semantics introduced above is compatible with the regular semantics of propositional logic, therefore we have the same propositional identities. Their validity can be established directly from the settings in Definition 22.1.2.

Prop	ositiona	l Identities		
	Name	for □	for ⊔	
	Idenpot.	$\varphi \sqcap \varphi = \varphi$	$\varphi \sqcup \varphi = \varphi$	
	Identity	$\varphi \sqcap \top = \varphi$	$\varphi \sqcup \bot = \varphi$	
	Absorpt.	$\varphi \sqcup \top = \top$	$\varphi \sqcap \bot = \bot$	
	Commut.	$\varphi \sqcap \psi = \psi \sqcap \varphi$	$\varphi \sqcup \psi = \psi \sqcup \varphi$	
	Assoc.	$\varphi \sqcap (\psi \sqcap \theta) = (\varphi \sqcap \psi) \sqcap \theta$	$\varphi \sqcup (\psi \sqcup \theta) = (\varphi \sqcup \psi) \sqcup \theta$	
	Distrib.	$\varphi \sqcap (\psi \sqcup \theta) = \varphi \sqcap \psi \sqcup \varphi \sqcap \theta$	$\varphi \sqcup \psi \sqcap \theta = (\varphi \sqcup \psi) \sqcap (\varphi \sqcup \theta)$	
	Absorpt.	$\varphi \sqcap (\varphi \sqcup \theta) = \varphi$	$\varphi \sqcup \varphi \sqcap \theta = \varphi \sqcap \theta$	
	Morgan	$\overline{\varphi \sqcap \psi} = \overline{\varphi} \sqcup \overline{\psi}$	$\overline{\varphi \sqcup \psi} = \overline{\varphi} \sqcap \overline{\psi}$	
	dneg	$\overline{\overline{\varphi}}$	$= \varphi$	
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Let us fortify our intuition about concept axions with a simple example about the sibling relation. We tive four concept axions and study their effect on the admissible models by looking at the respective Venn diagrams. In the end we see that in all admissible models, the denotations of the concepts son and daughter are disjoint, and child is the union of the two - just as intended.

Effe	cts of Axioms to Siblings	5	
	Axioms	Semantics	
	$\begin{array}{ c c c c c c c c c c c c c c c c c c c$	sons daughters children	daughters
	$son \sqcap daughter$ child \sqsubseteq (son \sqcup daughter)	sons daughters	children



There is another way we can approach the set description interpretation of propositional logic: by translation into a logic that can express knowledge about sets – first-order logic.



Normally, we embed PL^0 into PL^1 by mapping propositional variables to atomic predicates and the connectives to themselves. The purpose of this embedding is to "talk about truth/falsity of assertions". For "talking about sets" we use a non-standard embedding: propositional variables in PL^0 are mapped to first-order predicates, and the propositional connectives to corresponding set operations. This uses the convention that a set S is represented by a unary predicate p_S (its characteristic predicate), and set membership $a \in S$ as $p_S(a)$.





22.2 Ontologies and Description Logics

We have seen how sets of concept axioms can be used to describe the "world" by restricting the set of admissible models. We want to call such concept descriptions "ontologies" – formal descriptions of (classes of) objects and their relations.

Ontologies aka. "World Descriptions"
Definition 22.2.1 (Classical) An ontology is a representation of the types, properties, and interrelationships of the entities that really or fundamentally exist for a particular domain of discourse.
Remark: Definition 22.2.1 is very general, and depends on what we mean by "representation", "entities", "types", and "interrelationships".
This may be a feature, and not a bug, since we can use the same intuitions across a variety of representations.
\triangleright Definition 22.2.2 An ontology consists of a representation format ${\cal L}$ and statements (expressed in ${\cal L}$)about
▷ Individuals: concrete instances of objects in the domain.
\sim concepts: classes of individuals that share properties and aspects, and
relations: ways in which classes and individuals can be related to one an- other
▷ Example 22.2.3 Semantic networks are ontologies (relatively informal)
$ ho {f Example ~ 22.2.4 ~ PL_{DL}^0}$ is an ontology format (formal, but relatively weak)
$ ightarrow \mathbf{Example} \ 22.2.5 \ \mathrm{PL}^1$ is an ontology format as well. (formal, expressive)
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As we will see, the situation for PL_{DL}^{0} is typical for formal ontologies (even though it only offers concepts), so we state the general description logic paradigm for ontologies. The important idea is that having a formal system as an ontology format allows us to capture, study, and implement ontological inference.





For convenience we add concept definitions as a mechanism for defining new concepts from old ones. The so-defined concepts inherit the properties from the concepts they are defined from.



As PL_{DL}^{0} does not offer any guidance on this, we will leave the discussion of ABoxes to Section 23.2 when we have introduced our first proper description logic ACC.

22.3 Description Logics and Inference

Now that we have established the description logic paradigm, we will have a look at the inference services that can be offered on this basis.

Before we go into details of particular description logics, we must ask ourselves what kind of inference support we would want for building systems that support knowledge workers in building, maintaining and using ontologies. An example of such a system is the Protégé system [Pro], which can serve for guiding our intuition.

Kinds of Inference in Description Logics			
⊳ Consistency te	est	(is a concept definition sat	isfiable?)
\triangleright Subsumption 1	test	(does a concept subsume a	nother?)
\triangleright Instance test	▷ Instance test (is an individual an example of a concept?)		
⊳			
Problem: decidability, complexity, algorithm			
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We will now through these inference-based tests separately.

The consistency test checks for concepts that do not/cannot have instances. We want to avoid such concepts in our ontologies, since they clutter the namespace and do not contribute any meaningful contribution.



Even though consistency in our example seems trivial, large ontologies can make machine support necessary. This is even more true for ontologies that change over time. Say that an ontology initially has the concept definitions woman = person \sqcap long_hair and man = person \sqcap bearded, and then is modernized to a more biologically correct state. In the initial version the concept hermaphrodite is consistent, but becomes inconsistent after the renovation; the authors of the renovation should be made aware of this by the system.

The subsumption test determines whether the sets denoted by two concepts are in a subset relation. The main justification for this is that humans tend to be aware of concept subsumption, and tend to think in taxonomic hierarchies. To cater to this, the subsumption test is useful.



The good news is that we can reduce the subsumption test to the consistency test, so we can re-use our existing implementation.

The main user-visible service of the subsumption test is to compute the actual taxonimy induced by an ontology.



If we take stock of what we have developed so far, then we can see PL_{DL}^{0} as a rational reconstruction of semantic networks restricted to the "isa" relation. We relegate the "instance" relation to Section 23.2.

This reconstruction can now be used as a basis on which we can extend the expressivity and inference procedures without running into problems.

Chapter 23

A simple Description Logic: \mathcal{AC}

In this Chapter, we instantiate the description-logic paradigm further with the prototypical logic \mathcal{AC} , which we will introduce now.

23.1 Basic AC: Concepts, Roles, and Quantification

In this Section, we instantiate the description-logic paradigm with prototypical logic \mathcal{AC} , which we will devleop now.



More ALC Examples

```
    ▷ car □∃ has_part.(∃made_in.ĒU) (cars that have at least one part that has not been made in the EU)
    ▷ student □∀ audits_course.graduatelevelcourse (students, that only audit
```

graduate level	courses)		
\triangleright house $\sqcap \forall$ has	_parking.off_street	(houses with off-street	parking)
\triangleright Note: $p \sqsubseteq q$ can still be used as an abbreviation for $\overline{\overline{p} \sqcup q}$.			
<pre>▷ student □∀audits_course.(∃hastutorial. T ⊑ ∀has_TA.woman) (students that only audit courses that either have no tutorial or tutorials that are TAed by women)</pre>			
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As before we allow concept definitions so that we can express new concepts from old ones, and obtain more concise descriptions.

ACC Concept Definitions	
\triangleright Define new concepts from known ones: $(KD_{AC} := C$	$C = F_{ACC}$)
Definition	rec?
$man = person \sqcap \exists has_chrom.Y_chrom$	-
woman = person $\sqcap \forall$ has _ chrom . Y _ chrom	-
$mother = woman \sqcap \exists has child.person$	-
$father = man \sqcap \exists has child.person$	-
$grandparent = person \sqcap \exists has_child.(mother \sqcup father)$	-
$german = person \sqcap \exists has _ parents . german$	+
$number_list = empty_list \sqcup \exists is_first.number \sqcap \exists is_rest.number_list$	+
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As before, we can be normalize a TBox by definition exapansion – if it is acyclic. With the introduction of roles and quantification, concept definitions in \mathcal{AC} have a more "interesting" way to be cyclic as Observation 23.1.4 shows.

TBox Normalization in $\mathcal{A\!C\!C}$				
$\triangleright \mathbf{Example}$	23.1.2 (Normalizing grandparent)			
grandparent ← person □ ∃ has_child.(mother ⊔ father) ← person □ ∃ has_child.(woman □ ∃ has_child.person), man, (∃ has_child.person) ← person □ ∃ has_child.(person □ ∃ has_chrom ·Y_chrom □ ∃ has_child.person □ person □ ∃ has_chrom ·Y_chrom □ ∃ has_child.person)				
Observat redundancie	Observation 23.1.3 Normalization result can be exponential (contain redundancies)			
\triangleright Observat	tion 23.1.4 Normalization need not terminate on	n cyclic TBoxes.		
german	\mapsto person $\Box \exists$ has_parents.german			
	\mapsto person $\sqcap \exists$ has_parents.(person $\sqcap \exists$ has_parents.	arents.german)		
	\mapsto			
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Now that we have motivated and fixed the syntax of \mathcal{AC} , we will give it a formal semantics. The semantics of \mathcal{AC} is an extension of the set-theoretic semantics for PL^0 , thus the interpretation $\llbracket \cdot \rrbracket$ assigns subsets of the domain to concepts and binary relations over the domain to roles.

Semantics of ACC \triangleright All semantics is an extension of the set-semantics of propositional logic. \triangleright Definition 23.1.7 A model for \mathcal{ACC} is a pair $\langle \mathcal{D}, \llbracket \cdot \rrbracket \rangle$, where \mathcal{D} is a non-empty set called the domain and $\left[\!\left[\cdot\right]\!\right]$ a mapping called the interpretation, such that formula semantics Op. $\llbracket \bot \rrbracket = \emptyset$ $[c] \subseteq \mathcal{D} = \llbracket \top \rrbracket$ $\llbracket r \rrbracket \subset \mathcal{D} \times \mathcal{D}$ $[\![\overline{\varphi}]\!] = [\![\overline{\varphi}]\!] = \mathcal{D} \backslash [\![\overline{\varphi}]\!]$ ÷ $\llbracket \varphi \sqcap \psi \rrbracket = \llbracket \varphi \rrbracket \cap \llbracket \psi \rrbracket$ Π $\llbracket \varphi \sqcup \psi \rrbracket = \llbracket \varphi \rrbracket \cup \llbracket \psi \rrbracket$ \square ∃R. $\llbracket \exists \mathsf{R}.\varphi \rrbracket = \{ x \in \mathcal{D} \mid \exists y.\langle x, y \rangle \in \llbracket \mathsf{R} \rrbracket \text{ and } y \in \llbracket \varphi \rrbracket \}$ $\llbracket \forall \mathsf{R} \, \varphi \rrbracket = \{ x \in \mathcal{D} \, | \, \forall y \, \text{if} \, \langle x, y \rangle \in \llbracket \mathsf{R} \rrbracket \text{ then } y \in \llbracket \varphi \rrbracket \}$ ∀R. \triangleright Alternatively we can define the semantics of \mathcal{AL} by translation into PL^1 . \triangleright Definition 23.1.8 The translation of \mathcal{AC} into PL^1 extends the one from Definition 22.1.4 by the following quantifier rules: $\overline{\forall \mathsf{R}.\varphi}^{fo(x)} := (\forall y.\mathsf{R}(x,y) \Rightarrow \overline{\varphi}^{fo(y)}) \quad \overline{\exists \mathsf{R}.\varphi}^{fo(x)} := (\exists y.\mathsf{R}(x,y) \land \overline{\varphi}^{fo(y)})$ > Observation 23.1.9 The set-theoretic semantics from Definition 23.1.7 and the "sematnics-by-translation" from Definition 23.1.8 induce the same notion of satisfiability. JACOBS UNIVERSI (c): Michael Kohlhase 223

The following equivalences will be useful later on. They can be proven directly with the settings from Definition 23.1.7; we carry this out for one of them below.

$$\mathcal{A\!C\!C}$$
 Identities

$\triangleright \boxed{\begin{array}{c c}1 & \exists \mathbf{R}.\varphi = \forall \mathbf{R}.\varphi \\ 2 & \forall \mathbf{R}.(\varphi \sqcap \psi) = \end{array}}$ $\triangleright \text{ Proof of 1}$	$\overline{\varphi}$ $\forall R.(\varphi \sqcap \forall R.\psi)$	$\begin{vmatrix} 3 \\ 4 \end{vmatrix} = \exists \mathbf{R}. \overline{\varphi} = \exists \mathbf{R}. \overline{\varphi} \\ \exists \mathbf{R}. (\varphi \sqcup \psi) = \exists $	∃ R. ψ)
$\left[\left[\exists R.\varphi \right] \right] = \mathcal{D} \setminus \left[\exists R.\right]$	$\varphi] = \mathcal{D} \setminus \{ x \in \mathbb{D} \\ = \{ x \in \mathcal{D} \\ = \ \forall R. \overline{\varphi} \ $	$\mathcal{D} \mid \exists y \cdot (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ and } (y \in \llbracket R \rrbracket) \text{ and } (y \in \llbracket R \rrbracket) \text{ and } (y \in \llbracket Y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \notin \forall y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \forall y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \forall y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \forall y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in \exists y \cdot if (\langle x, y \rangle \in \llbracket R \rrbracket) \text{ then } (y \in I \cap I) then$	$\llbracket \varphi \rrbracket) \}$ $\exists \llbracket \varphi \rrbracket) \}$ $\llbracket \varphi \rrbracket) \}$ $(\mathcal{D} \setminus \llbracket \varphi \rrbracket)) \}$ $\llbracket \varphi \rrbracket) \}$
CO Some filights reserved	©: Michael Kohlhas	e 224	

The form of the identities (interchanging quantification with propositional connectives) is reminiscient of identities in PL^1 ; this is no coincidence as the "semantics by translation" of Definition 23.1.8 shows.

We can now use the \mathcal{AC} identities above to establish a useful normal form for \mathcal{AC} . This will play a role in the inference procedures we study next.



Finally, we extend \mathcal{AC} with an ABox component. This mainly means that we define two new assertions in \mathcal{AC} and specify their semantics and PL^1 translation.

$\mathcal{A\!L\!C}$ with Assertions about Indivi	duals
$ hightarrow { m Definition} \ { m 23.1.11} \ { m (ABox \ Formula)} \ { m All}$	e) We define the ABox formulae for
$\triangleright (a \colon \varphi)$	$(a ext{ is a } arphi)$
ightarrow aRb	(a stands in relation R to b)
$ ho$ Definition 23.1.12 Let $\langle \mathcal{D}, \llbracket \cdot rbracket angle$ be a m	odel for $\mathcal{A\!L\!C}$, then we define



If we take stock of what we have developed so far, then we see that $\mathcal{A\!C\!C}$ as a rational reconstruction of semantic networks restricted to the "isa" and "instance" relations – which are the only ones that can really be given a denotational and operational semantics.

23.2 Inference for \mathcal{AC}

In this Section we make good on the motivation from Section 22.1 that description logics enjoy tractable inference procedures: We present a tableau calculus for \mathcal{AC} , show that is a decision procedures, and study its complexity.



In contrast to the tableau calculi for theorem proving we have studied earlier, \mathcal{T}_{AC} is run in "model generation mode". Instead of initializing the tableau with the axioms and the negated conjecture and hope that all branches will close, we initialize the \mathcal{T}_{AC} tableau with axioms and the "conjecture" that a given concept φ is satisfiable – i.e. φ has a member x, and hope for branches that are open, i.e. that make the conjecture true (and at the same time give a model). Let us now work through two very simple examples; one unsatisfiable, and a satisfiable one.



Another example: this one is more complex, but the concept is satisfiable.



After we got an intution about \mathcal{T}_{AC} , we can now study the properties of the calculus to determine that it is a decision procedure for AC.



The correctness result for \mathcal{T}_{AC} is as usual: we start with a model of $(x: \varphi)$ and show that an \mathcal{T}_{AC} tableau must have an open branch.

Correctness				
$ hightarrow {f Lemma 23.2.4}$ lf $arphi$ satisfiable branch.	e, then $\mathcal{T}_{\mathcal{ACC}}$	terminates on	$(x \colon arphi)$ with open	
$ ho$ Proof: Let $\mathcal{M}:=\langle \mathcal{D},\mathcal{I} angle$ be a m	odel for $arphi$ a	nd $w \in \llbracket \varphi \rrbracket$.		
$ \begin{array}{c} \mathcal{I} \models \\ \mathbf{P.1} \text{ we define } \llbracket x \rrbracket := w \text{ and } \begin{array}{c} \mathcal{I} \models \\ \mathcal{I} \models \\ \end{array} \end{array} $	$\begin{array}{ll} (x \colon \psi) & \text{iff} \\ x R y & \text{iff} \\ S & \text{iff} \end{array}$	$ \begin{split} \llbracket x \rrbracket \in \llbracket \psi \rrbracket \\ \langle x, y \rangle \in \llbracket R \rrbracket \\ \mathcal{I} \models c \text{ for all } c \in \end{split} $	$\in S$	
P.2 This gives us $\mathcal{I} \models (x \colon \varphi)$			(base case)	
$\mathbf{P.3}$ case analysis: if branch satis	fiable, then	either		
ho no rule applicable to lea	af		(open branch)	
\triangleright or rule applicable and o	ne new bran	ch satisfiable	(inductive case)	
P.4 consequence: there must be	an open bra	anch	(by termination)	
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We complete the proof by looking at all the \mathcal{T}_{AC} inference rules in turn.

Case analysis on the rules $\mathcal{T}_{\sqcap} \text{ applies then } \mathcal{I} \models (x: \varphi \sqcap \psi), \text{ i.e. } [\![x]\!] \in [\![(\varphi \sqcap \psi)]\!]$ so $[\![x]\!] \in [\![\varphi]\!] \text{ and } [\![x]\!] \in [\![\psi]\!], \text{ thus } \mathcal{I} \models (x: \varphi) \text{ and } \mathcal{I} \models (x: \psi).$ $\mathcal{T}_{\sqcup} \text{ applies then } \mathcal{I} \models (x: \varphi \sqcup \psi), \text{ i.e. } [\![x]\!] \in [\![(\varphi \sqcup \psi)]\!]$ so $[\![x]\!] \in [\![\varphi]\!] \text{ or } [\![x]\!] \in [\![\psi]\!], \text{ thus } \mathcal{I} \models (x: \varphi) \text{ or } \mathcal{I} \models (x: \psi),$ wlog. $\mathcal{I} \models (x: \varphi).$ $\mathcal{T}_{\forall} \text{ applies then } \mathcal{I} \models (x: \forall \mathbb{R}.\varphi) \text{ and } \mathcal{I} \models x\mathbb{R}y, \text{ i.e. } [\![x]\!] \in [\![\forall \mathbb{R}.\varphi]\!] \text{ and } \langle x, y \rangle \in$ $[\![\mathbb{R}]\!], \text{ so } [\![y]\!] \in [\![\varphi]\!]$

$ \begin{array}{l} \mathcal{T}_{\exists} \ \mathbf{applies} \ \text{then} \ \mathcal{I} \models (x \colon \exists \mathbf{R}.\varphi), \ \text{i.e} \ \llbracket x \rrbracket \in \llbracket \exists \mathbf{R}.\varphi \rrbracket, \\ \text{so there is a} \ v \in D \ \text{with} \ \langle \llbracket x \rrbracket, v \rangle \in \llbracket R \rrbracket \ \text{and} \ v \in \llbracket \varphi \rrbracket. \\ \text{We define} \ \llbracket y \rrbracket := v, \ \text{then} \ \mathcal{I} \models x Ry \ \text{and} \ \mathcal{I} \models (y \colon \varphi) \end{array} $			
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For the completeness result for \mathcal{T}_{AC} we have to start with an open tableau branch and construct at model that satisfies all judgements in the branch. We proceed by building a Herbrand model, whose domain consists of all the individuals mentioned in the branch and which interprets all concepts and roles as specified in the branch. Not surprisingly, the model thus constructed satisfies the branch.



We complete the proof by looking at all the \mathcal{T}_{AC} inference rules in turn.

Case Analysis for Induction case $(y: \psi) = (y: \psi_1 \sqcap \psi_2)$ Then $\{y: \psi_1, y: \psi_2\} \subseteq \mathcal{B}$ (\mathcal{T}_{\sqcap} -rule, saturation) so $\mathcal{I} \models (y: \psi_1)$ and $\mathcal{I} \models (y: \psi_2)$ and $\mathcal{I} \models (y: \psi_1 \sqcap \psi_2)$ (IH, Definition) case $(y: \psi) = (y: \psi_1 \sqcup \psi_2)$ Then $(y: \psi_1) \in \mathbf{B}$ or $(y: \psi_2) \in \mathbf{B}$ (\mathcal{T}_{\sqcup} , saturation) so $\mathcal{I} \models (y: \psi_1)$ or $\mathcal{I} \models (y: \psi_2)$ and $\mathcal{I} \models (y: \psi_1 \sqcup \psi_2)$ (IH, Definition) **case** $(y: \psi) = (y: \exists R, \theta)$ then $\{yRz, z: \theta\} \subseteq \mathbf{B}$ (*z* new variable) (\mathcal{T}_{\exists} -rules, saturation) so $\mathcal{I} \models (z: \theta)$ and $\mathcal{I} \models y Rz$, thus $\mathcal{I} \models (y: \exists R.\theta)$. (IH, Definition) $\mathbf{case} \ (y \colon \psi) = (y \colon \forall \mathsf{R}.\theta) \ \text{Let} \ \langle \llbracket y \rrbracket, v \rangle \in \llbracket \mathsf{R} \rrbracket \text{ for some } r \in \mathcal{D}$ then v = z for some variable z with $y R z \in \mathbf{B}$ (construction of [R]) So $(z: \theta) \in \mathcal{B}$ and $\mathcal{I} \models (z: \theta)$. $(\mathcal{T}_{\forall}\text{-rule, saturation, Def})$ Since v was arbitrary we have $\mathcal{I} \models (y: \forall \mathsf{R}.\theta)$.



We can turn the termination result into a worst-case complexity result by examining the sizes of branches.





In summary, the theoretical complexity of \mathcal{AC} is the same as that for PL^0 , but in practice \mathcal{AC} is much more expressive. So this is a clear win.

But the description of the tableau algorithm \mathcal{T}_{AC} is still quite abstract, so we look at an exemplary implementation in a functional programming language



Note that we have (so far) only considered an empty TBox: we have initialized the tableau with a normalized concept; so we did not need to include the concept definitions. To cover "real" ontologies, we need to consider the case of concept axioms as well.

We now extend $\mathcal{T}_{\mathcal{A}\mathcal{L}}$ with concept axioms. The key idea here is to realize that the concept axioms apply to all individuals. As the individuals are generated by the \mathcal{T}_{\exists} rule, we can simply extend that rule to apply all the concepts axioms to the newly introduced individual.

Extending the Tableau Algorithm by Concept Axioms \triangleright Concept axioms, e.g. child \sqsubseteq (son \sqcup daughter) cannot be handled in \mathcal{T}_{AC} yet. \triangleright Idea: Whenever a new variable y is introduced (by \mathcal{T}_{\exists} -rule) add the information that axioms hold for y. \triangleright initialize tableau with $\{x: \varphi\} \cup CA$ (CA: = set of concept axioms)



The problem of this approach is that it spoils termination, since we cannot control the number of rule applications by (fixed) properties of the input formulae. The example shows this very nicely. We only sketch a path towards a solution.



23.3 ABoxes, Instance Testing, and \mathcal{AC}





ABox Inference in $\mathcal{A\!C\!C}$: Phenomena

 \rhd There are different kinds of interactions between TBox and ABox in description logics

	property	example		
	internally inconsistent	(tony: student), (tony: student)		
	inconsistant with a TRoy	TBox: stud	dent ⊓ prof	
	Inconsistent with a TBox	ABox: (tor	ny: student), (tony: pr	of)
		Abox: (ton	ıy:∀has_grad_genius)
	implicit info that is not ex-	tony	/has_gradmary	
	plicit	⊨(mary: genius)	
		TBox: con	$t_prof = prof \sqcap \forall has$	_grad.genius
	info that can be combined	ABox: (tor	ny: cont_prof), tonyha	as_gradmary
	with TBox info \models (mary: genius)			
·				
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⊳ necessary changes:		(no big deal)		
⊳ Normalize ABox wrt. TBox		(definition expansion)		
$_{\vartriangleright}$ initialize the tableau with ABox in NNF		(so it can be used)		
	Example: add (mary: genius) to determine $ABox, TBox \models$ (mary: genius)			
TBox	<pre>cont_prof = prof □ ∀ has_grad.genius</pre>	(tony: prof □∀has_grad.genius) tonyhas_gradmary (mary: genius) (tony: prof) (tony: ∀has_grad_genius)	TBox ABox Query \mathcal{T}_{\Box}	
ABox	(tony: cont_prof) tonyhas_gradmary	(mary: genius) *	$\mathcal{T}_{\forall} \\ \mathcal{T}_{*}$	
▷ Note: The instance test is the base for the realization (remember?)				
\triangleright extend to more complex ABox queries: (give me all instances of φ)				
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EDitorial need to unity abox and toox judgments.				

Chapter 24

Description Logics and the Semantic Web

In this Chapter we discuss how we can apply description logics in the real world, in particular, as a conceptual and algorithmic basis of the "Semantic Web". That tries to transform the "World Wide Web" from a human-understandable web of multimedia documents into a "web of machine-understandable data". In this context, "machine-understandable" means that machines can draw inferences from data they have access to.

Note that the discussion in this digression is not a full-blown introduction to RDF and OWL, we leave that to [SR14, HASB13a, HKP⁺12] and the respective W3C recommendations. Instead we introduce the ideas behind the mappings from a perspective of the description logics we have discussed above.

The most important component of the "Semantic Web" is a standardized language that can represent "data" about information on the Web in a machine-oriented way.



Note that all these examples have in common that they are about "objects on the Web", which is an aspect we will come to now. "Objects on the Web" are traditionally called "resources", rather than defining them by their intrinsic properties – which would be ambitious and prone to change – we take an external property to define them: everything that has a URI is a web resource. This has repercussions on the design or RDF.



The crucial observation here is that if we map "subjects" and "objects" to "individuals", and "predicates" to "relations", the RDF statements are just relational ABox statements of description logics. As a consequence, the techniques we developed apply.

We now come to the concrete syntax of RDF. This is a relatively conventional XML syntax that combines RDF statements with a common subject into a single "description" of that resource.

XML Syntax for RDF

 \triangleright RDF is a concrete XML vocabulary for writing statements

 \rhd $\mathbf{Example}$ 24.0.7 The following RDF document could describe the slides as a resource

This RDF document makes two statements:

- ${\scriptstyle \vartriangleright}$ The subject of both is given in the about attribute of the rdf:Description element
- $_{\vartriangleright}$ The predicates are given by the element names of its children

 ▷ The objects are given in the elements as URIs or literal content.

 Intuitively: RDF is a web-scalable way to write down ABox information.

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Note that XML namespaces play a crucial role in using element to encode the predicate URIs. Recall that an element name is a qualified name that consists of a namespace URI and a proper element name (without a colon character). Concatenating them gives a URI in our example the predicate URI induced by the dc:creator element is http://purl.org/dc/elements/1.1/creator. Note that as URIs go RDF URIs do not have to be URLs, but this one is and it references (is redirected to) the relevant part of the Dublin Core elements specification [DCM12].

RDF was deliberately designed as a standoff markup format, where URIs are used to annotate web resources by pointing to them, so that it can be used to give information about web resources without having to change them. But this also creates maintenance problems, since web resources may change or be deleted without warning.

RDFa gives authors a way to embed RDF triples into web resources and make keeping RDF statements about them more in sync.



In the example above, the **about** and **property** attribute are reserved by RDFa and specify the subject and predicate of the RDF statement. The object consists of the body of the element, unless otherwise specified e.g. by the **resource** attribute.

Let us now come back to the fact that RDF is just an XML syntax for ABox statements.



▷ Example 24.0.9 h is the resource for Ian Horrocks, s is the resource for Ulrike Sattler, R is the the relation "hasColleague", and φ is the class foaf :Person <rdf:Description about="some.uri/person/ian_horrocks"> <rdf:type rdf:resource="http://xmlns.com/foaf/0.1/Person"/> <hasColleague resource="some.uri/person/uli_sattler"/> </rdf:Description> Idea: Now, we need an similar language for TBoxes (based on ACC)

In this situation, we want a standardized representation language for TBox information; OWL does just that: it standardizes a set of knowledge representation primitives and specifies a variety of concrete syntaxes for them. OWL is designed to be compatible with RDF, so that the two together can form an ontology language for the web.



We have introduced the ideas behind using description logics as the basis of a "machine-oriented web of data". While the first OWL specification (2004) nhad three sublanguages "OWL Lite", "OWL DL" and "OWL Full", of which only the middle was based on description logics, with the OWL2 Recommendation from 2009, the foundation in description logics was nearly universally accepted.

The Semantic Web hype is by now nearly over, the technology has reached the "plateau of productivity" with many applications being pursued in academia and industry. We will not go into these, but briefly instroduce one of the tools that make this work.

SPARQL a RDF Query language

 \rhd Definition~24.0.12 A database that stores ${\rm RDF}$ data is called a triple store

Definition 24.0.13 SPARQL, the "SPARQL Protocol and RDF Query Language" is an RDF query language, able to retrieve and manipulate data stored in RDF. The SPARQL language was standardize by the World Wide Web Consortium in 2008 [PS08].	
$ hightarrow { m SPARQL}$ is pronounced like the word "sparkle".	
\triangleright Definition 24.0.14 A triple store is called a <u>SPARQL endpoint</u> , iff it answers SPARQL queries.	
\triangleright Example 24.0.15	
Query for person names and their e-mails from a triple store with FOAF data.	
PREFIX foaf: <http: 0.1="" foaf="" xmlns.com=""></http:> SELECT ?name ?email	
WHERE { ?person a foaf:Person. ?person foaf:name ?name. ?person foaf:mbox ?email.	
}	
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SPARQL end-points can be used to build interesting applications, if fed with the appropriate data. An interesting – and by now paradigmatic – example is the DBPedia project.

SPARQL Applications: DBPedia
Typical Application: DBPedia screen-scrapes Wikipedia fact boxes for RDF triples and uses SPARQL for querying the induced triple store.
Europealo 24.0.16 (DBDodio Ouropea)
▷ Example 24.0.16 (DBPedia Query)
People who were born in Berlin before 1900 (http://dbpedia.org/sparq1)
PREFIX dbo: <http: dbpedia.org="" ontology=""></http:>
<pre>SELECT ?name ?birth ?death ?person WHERE { ?person dbo:birthPlace :Berlin . ?person dbo:birthDate ?birth . ?person foaf:name ?name . ?person dbo:deathDate ?death .</pre>
$FILTER$ (?birth < "1900-01-01"^^xsd:date) .
} ORDER BY ?name
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Chapter 25

ALC Extensions



Description Logic Naming Scheme

- ▷ Idea: Use the name of a description logic to show its expressive power(letters express constructors)
- - \triangleright The letter \mathcal{H} represents subroles (role Hierarchies),
 - $\triangleright \mathcal{O}$ represents nominals (nOminals),
 - $\triangleright \mathcal{I}$ represents inverse roles (linverse),
 - $\triangleright \mathcal{N}$ represent number restrictions (Number), and
 - $\triangleright \mathcal{Q}$ represent qualified number restrictions (Qualified).

The integration of a concrete domain/datatype is indicated by appending its name in parenthesis, but sometimes a âĂIJgenericâĂİ D is used to express that some concrete domain/datatype has been integrated.

\triangleright Example 25.0.2 The DL corresponding to the OWL DL ontology language includes all of these constructors and is therefore called $SHOIN(D)$.			
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25.1 Functional Roles and Number Restrictions

Functional Roles			
$ ho \ {f Example \ 25.1.1 \ CSR} \hat{=} \ {f Car}$ with glass sun roof			
▷ In AC : CSR = car $\Box \exists$ has_sun_roof.glass ▷ potential unwanted interpretation: more than c	one sun roof.		
\triangleright Problem : has_sun_roof is a relation in AC	(no partial functi	ion)	
$ ho \ \mathbf{Example} \ 25.1.2$ Humans have exactly one father and mother.			
$ ho$ in $\mathcal{A\!C\!C}$: human $\sqsubseteq \exists$ has father human $\sqcap \exists$ has mother human			
▷ Problem: has_father should be a total function	n (on the set of huma	ans)	
Solution: Number Restrictions	(see next slid	e)	
\gg Example 25.1.3 Teenager = human between 13 and 19			
$_{\vartriangleright} teenager = human \sqcap (age < 20) age > 12$	(not covered by $\mathcal A$	VCC)	
▷ Solution: concrete domains (outside)	de the scope of this cou	rse)	
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Number Restrictions



(Unqualified) Number Restrictions \triangleright Definition 25.1.5 ACCN is ACC plus operators $\exists_{\geq}^{n} R$ and $\forall_{\leq}^{n} R$ (R role, $n \in \mathbb{N}$) \triangleright Example 25.1.6

 $car = vehicle \sqcap \exists_{>}^{4} has_wheel \qquad (25.1)$

$$\mathsf{city} = \mathsf{town} \sqcap \exists_{>}^{1,000,000} \mathsf{has_inhabitants} \qquad (25.2)$$

$$\mathsf{small_family} = \mathsf{family} \sqcap \forall^2_{\leq} \mathsf{has_child} \tag{25.3}$$

 \triangleright

$$\left[\exists_{\geq}^{n}\mathsf{R}\right] = \{x \in \mathcal{D} \mid \#(\{y \mid \langle x, y \rangle \in \llbracket\mathsf{R}\rrbracket\}) \ge n\}$$
(25.4)

$$\left[\forall_{<}^{n}\mathsf{R}\right] = \{x \in \mathcal{D} \mid \#(\{y \mid \langle x, y \rangle \in [\![\mathsf{R}]\!]\}) \le n\}$$
(25.5)

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 \triangleright Intuitively: $\exists_{>}^{n}\mathsf{R}$ is the set of objects that have at least n R-successors.

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 \triangleright Example 25.1.7 $\exists_{\geq}^{1,000,000}$ has_inhabitants is the set of objects that have at least 1,000,000 inhabitants.

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Translation into Predicate Logic \triangleright Two extra rules for number restrictions: (very cumbersome) $\overline{\forall_{<}^{n}\mathsf{R}}^{fo(x)}$ $\overline{\exists \mathbb{R}^n \mathsf{R}}^{\overline{fo(x)}}$ $\neg \exists y R(x, y) \lor$ $\exists y_1 \, \mathbf{R}(x, y_1) \land$ $\wedge \exists y_n \, \mathbf{R}(x, y_n)$ $(\exists y_1 \, \mathsf{R}(x, y_1) \land \ldots \land \exists y_n \, \mathsf{R}(x, y_n))$ $\wedge y_1 \neq y_2 \wedge$ $\wedge y_1 \neq y_n$. . . $y_2 \neq y_3 \land$ $\forall y \, \mathbf{R}(x, y) \Rightarrow (y = y_1 \lor \ldots \lor y = y_n))$ $\ldots \wedge y_2 \neq y_n \wedge$ Λ $y_{n-1} \neq y_n$ \triangleright Definable Operator: $\stackrel{n}{=} \mathsf{R} := \exists_{>}^{n} \mathsf{R} \sqcap \forall_{<}^{n} \mathsf{R}$ defines the set of objects that have exactly n R-successors. \triangleright Example 25.1.8 car = vehicle $\sqcap \stackrel{n}{=}$ has wheel (vehicles with exactly 4 wheels) 6 ©: Michael Kohlhase 257

Functional Roles

- ▷ Example 25.1.9 CSR = car $\sqcap \stackrel{1}{=}$ has_sun_roof (CSR = car with sun roof) has sun roof is a relation, but restricted to CSR it is a total function.
- \triangleright Partial functions: Chd = computer $\sqcap \forall_{\leq}^1$ has _hd (computer with at most one hard drive) has hd is a partial function on the set Chd
- \triangleright Intuition: number restrictions can be used to encode partial and total functions, but not to specify the range type.





25.2 Unique Names









25.3 Qualified Number Restrictions



 $\begin{array}{l} \textbf{Optimizied Tableau Rules [Tob00]} \\ \vartriangleright \textbf{Definition 25.3.6 } \mathcal{T}_{\mathcal{AC}} \text{ rules plus:} \\ & \underline{\mathcal{B}} \\ & \underline{(x: \exists_{\geq}^{n} r. \varphi)} \quad \#(\{y \,|\, x \mathbb{R} y, y: \varphi \in \mathcal{B}\}) < n \ y \ \text{new}} \\ & \underline{(x: \exists_{\geq}^{n} r. \varphi)} \\ & \underline{(y: \varphi)} \\ & (y: \varphi) \\ & (y: \xi_{1}) \\ & \vdots \\ & (y: \xi_{k}) \\ \end{array} \\ \textbf{where } \{\psi_{1}, \ldots, \psi_{k}\} = \{\psi \,|\, (x: \exists_{\geq}^{m} \mathbb{R}. \psi) \in \mathcal{B} \text{ or } (x: \forall_{\leq}^{m} \mathbb{R}. \psi) \in \mathcal{B}\} \text{ and } \xi_{i} = \psi \end{array}$

Example Tableau \triangleright Example 25.3.7 $\begin{array}{c} (x \colon (\exists_{\geq}^{3}\mathsf{R}.\varphi) \sqcap (\forall_{\leq}^{1}\mathsf{R}.\psi) \sqcap (\forall_{\leq}^{1}\mathsf{R}.\overline{\psi})) \\ (x \colon \exists_{\geq}^{3}\mathsf{R}.\varphi) \\ (x \colon \forall_{\leq}^{\Gamma}\mathsf{R}.\psi) \\ (x \colon \forall_{\leq}^{\Gamma}\mathsf{R}.\overline{\psi}) \end{array}$ $x \mathsf{R} y_1$ $(y_1:\varphi)$ $(y_1:\psi)$ $(y_1:\overline{\psi})$ $x Ry_2$ $x Ry_2$ $(y_2:\varphi)$ $(y_2:\varphi)$ $\begin{array}{c} (y_2 \colon \overline{\psi}) \\ (y_2 \colon \overline{\psi}) \\ x R y_3 \\ (y_3 \colon \varphi) \\ (y_3 \colon \psi) \mid (y_3 \colon \overline{\psi}) \end{array}$ $(y_2 \colon \psi)$ $(y_2 \colon \psi)$ $(y_2:\overline{\psi})$ $x Ry_3$ * $(y_2:\varphi)$ $(y_3:\psi) \mid (y_3:\overline{\psi})$ * * ▷ Problem: Naive Implementation: exponential path lengths © JACOBS UNIVERSITY ©: Michael Kohlhase 267

Implementation by "Traces"

 \triangleright Algorithm SAT(φ) = sat($x_0, \{x_0 : \varphi\}$)

sat(x, S):

allocate counter $\#r^S(x,\psi):=0$ for all roles R and positive or negative subformulae ψ in S.

apply rules \mathcal{T}_{\sqcap} and \mathcal{T}_{\sqcup} as long as possible

If S contains an inconsistency, RETURN $\ast.$

 $while(\mapsto_{\geq} is appliccable to x) do:$

$$\begin{split} S_{neu} &:= \{\mathcal{T}_{\mathcal{A}\mathcal{L}} \mathsf{R} xy, y \colon \varphi, y \colon \xi_1, \dots y \colon \xi_k\} \\ \text{where} \\ y \text{ is a new variable,} \\ &(x \colon \exists_{\geq}^n \mathsf{R} \boldsymbol{.} \varphi) \text{ triggers rule} \mapsto_{\geq} \text{,} \\ &\{\psi_1, \dots, \psi_k\} = \{\psi \mid (x \colon \exists_{\geq}^m \mathsf{R} \boldsymbol{.} \psi) \in \mathcal{B} \text{ or } (x \colon \forall_{\leq}^m \mathsf{R} \boldsymbol{.} \psi) \in \mathcal{B}\} \text{ and} \\ &\xi_i = \psi \text{ oder } \xi = \neg \psi. \end{split}$$



Analysis

- \triangleright Idea: Each R-successor of x triggers a recursive call of sat.
- > There may be exponentially many R-successor, but they are treated one-byone, so their space can be re-used.
- > The chains of R-successors are at most as long as the nesting depth of operators (linear)
- ▷ Lemma 25.3.8 Space consumption is polynomial.
- ▷ Lemma 25.3.9 This algorithm is complete.
- \triangleright Proof Sketch: The global counters $\#r^S(x,\psi)$ count the R-successors and trigger rule $\mapsto_{<}$.
- > Theorem 25.3.10 The algorithm is correct, complete and terminating, and PSPACE (no worse than ACC) © JACOBS

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25.4**Role Operators**





 \triangleright Definition 25.4.2 $\mathcal{T}_{\!\mathcal{A\!C\!C}}$ + complex roles instead of role names

 $\frac{(x: \exists \mathsf{R}_{\boldsymbol{\cdot}}\varphi)}{x\mathsf{R}y}\mathcal{T}_{\exists} \qquad \quad \frac{x\mathsf{S}y}{(x: \forall \mathsf{R}_{\boldsymbol{\cdot}}\varphi)} \mathsf{S} \sqsubseteq \mathsf{R} \in \mathcal{R} \\ \frac{(x: \forall \mathsf{R}_{\boldsymbol{\cdot}}\varphi)}{(y: \varphi)} \forall_{\sqsubseteq}$

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The \mathcal{T}_\exists rule is the same as before



- ▷ Example 25.4.3 person □∃(has_teacher □ has_friend).swiss (persons that have a Swiss teacher that is also their friend)
- \triangleright Example 25.4.4 com $\sqcap \exists (has_employee \sqcap has_attorney).lawyer (companies that have an employed attorney that is a lawyer)$
- $\rhd \llbracket \mathsf{R} \sqcap \mathsf{S} \rrbracket = \llbracket \mathsf{R} \rrbracket \cap \llbracket \mathsf{S} \rrbracket = \{ \langle x, y \rangle \in \mathcal{D} \, | \, \langle x, y \rangle \in \llbracket \mathsf{R} \rrbracket \text{ and } \langle x, y \rangle \in \llbracket \mathsf{S} \rrbracket \}$



Role Disjunction \sqcup





Role composition \circ

 \triangleright Example 25.4.10 person $\sqcap \exists$ has_child \circ has_child.prof (persons that have grandchild that is a professor)


Converse Roles (\cdot^{-1}) \triangleright Example 25.4.12 (set of objects whose parents are teachers) $[\![\forall \mathsf{has_child}^{-1}.\mathsf{teacher}]\!] = \{x \mid \forall y.\langle x, y \rangle \in [\![\mathsf{has_child}^{-1}]\!] \Rightarrow y \in [\![\mathsf{teacher}]\!]\}$ $= \{x \mid \forall y \, \langle y, x \rangle \in \llbracket \mathsf{has child} \rrbracket \Rightarrow y \in \llbracket \mathsf{teacher} \rrbracket \}$ $= \{x \mid \forall y \, (x, y) \in [[has parents]] \Rightarrow y \in [[teacher]]\}$ $\triangleright \text{ Definition 25.4.13 } \left[\!\left[\mathsf{R}^{-1}\right]\!\right] = \left[\!\left[\mathsf{R}\right]\!\right]^{-1} = \left\{\langle y, x\rangle \in \mathcal{D}^2 \,|\, \langle x, y\rangle \in \left[\!\left[\mathsf{R}\right]\!\right]\!\right\}$ \triangleright Example 25.4.14 has child^{-1} = has parents $\mathsf{is}_\mathsf{part}_\mathsf{of}^{-1} = \mathsf{contains}_\mathsf{as}_\mathsf{part}$ owns^{-1} = belongs to . . . V JACOBS CC Some filterist filts from the ©: Michael Kohlhase 278

Translation of Role Terms

 \triangleright Definition 25.4.15 Translation Rules:

tr(R) := R(x, y)	
$tr(R\sqcapS):=tr(R)\wedgetr(S)$	$tr(R \sqcup S) := tr(R) \lor tr(S)$
$tr(R \sqsubseteq S) := tr(R) \Rightarrow tr(S)$	$tr(R \circ S) := \exists z tr(R), tr(S)$
$tr(R^{-1}):=tr(R)$	$tr(\overline{R}) := \neg tr(R)$
$\overline{\forall R.\varphi}^{fo(x)} := \forall y.tr(R) \! \Rightarrow \! \overline{\varphi}^{fo(y)}$	$\overline{\exists R_{\bullet}\varphi}^{fo(x)} := \exists y_{\bullet}tr(R), \overline{\varphi}^{fo(y)}$

 \triangleright Example 25.4.16





Tableaux Calculus: \mathcal{ACC} + Role Terms> Definition 25.4.17 complex roles instead of role names $\frac{(x: \exists R.\varphi)}{xRy}$ $\frac{xRz}{xRy}$ \mathcal{T}_{\exists} $\frac{\mathcal{B}}{(x: \forall R.\varphi)}$ $\mathcal{B} \models xRy$ $(y: \varphi)$ > Problem: What is $\mathcal{B} \models xRy$ (\mathcal{B} is the current branch)> Simple case: no role composition \circ and no converse roles \cdot^{-1} .> then $\mathcal{B} \models xRy$, iff $\{S \mid xSy \in \mathcal{B}\} \cup \{\overline{R}\}$ inconsistent in PL^0 (decidable)> General case: $\mathcal{B} \models xRy$, iff $\{tr(S) \mid uSv \in \mathcal{B}\} \cup \{tr(\overline{R})\}$ inconsistent in PL^1 (undecidable in general)



25.5 Role Axioms



$\mathcal{AC} + \text{Role Terms} + \text{Role Axioms } \rho$ $\triangleright \text{ Idea: Tableau like for } \mathcal{AC} + \text{ role terms} \qquad (\mathcal{B}, \rho \models x Ry \text{ instead of } \mathcal{B} \models x Ry)$ $\triangleright \text{ Simple case: no role composition } \circ \text{ and no converse roles } \cdot^{-1}. \qquad (\text{decidable})$ $\triangleright \text{ then } \mathcal{B}, \rho \models x Ry \text{ iff } \{S \mid x Sy \in \mathcal{B}\} \cup \rho \cup \{\overline{R}\} \text{ inconsistent in } \text{PL}^{0}$ $\triangleright \text{ General case: } \mathcal{B}, \rho \models x Ry, \text{ iff } \{\text{tr}(S) \mid u Sv \in (\mathcal{B} \cup \text{trr}(\rho) \cup \{\text{tr}(\overline{R})\})\} \text{ inconsistent in } \text{PL}^{1}$



25.6 Features



Examples

- \triangleright Example 25.6.3 persons, whose father is a teacher: person \sqcap had_father.teacher
- \triangleright Example 25.6.4 persons that have no father: person \sqcap (had_father)
- \triangleright Example 25.6.5 companies, whose bosses have no company car: company \sqcap (has $_$ poss \circ has $_$ comp $_$ car) \uparrow
- ▷ Example 25.6.6 cars whose exterior color is the same as the interior color: car □ color_exterior = color_interior
- ▷ Example 25.6.7 cars whose exterior color is different from the interior color: car □ color_exterior ≠ color_interior

▷ Example 25.6.8 companies whose Bosses and Vice Presidents have the same company car: company □ has_boss ◦ has_comp_car = has_VP ◦ has_comp_car

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Normalization

 \triangleright Normalization rules

 $\begin{array}{rcl} \overline{f.\varphi} & \rightarrow & (f) \uparrow \sqcup f.\varphi \\ \overline{\pi = \omega} & \rightarrow & ((\pi) \uparrow)(\omega) \uparrow \sqcup \pi \neq \omega \\ \overline{\pi \neq \omega} & \rightarrow & ((\pi) \uparrow)(\omega) \uparrow \sqcup \pi = \omega \\ (f \circ \pi) \uparrow & \rightarrow & (f) \uparrow \sqcup f \circ (\pi) \uparrow \end{array}$

▷ Example 25.6.9 (for the last transformation)

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```
(has boss \circ has comp car \circ has sun roof) \uparrow = ...
```

i.e. the set of objects that do not have a boss, plus the set of objects whose boss does not have a company car plus the set of objects whose bosses have company cars without sun roofs





Example

▷ Example 25.6.13 (has_boss o has_comp_car)↑ □ has_boss.has_comp_car.has_sun_roof.⊤ is inconsistent.

25.7 Concrete Domains

$\mathcal{A\!C\!C}$ with "concrete Domains" (Examples)				
Formula	Concrete Domain			
person \sqcap age < 20	real numbers			
persons younger than 20				
$\begin{tabular}{lllllllllllllllllllllllllllllllllll$	natural numbers			
companies with CEOs with expensive car				
$\operatorname{car} \sqcap \operatorname{height} > \operatorname{width}$	natural numbers			
cars that are higher than wide				
$\verb person \sqcap first_name < last_name $	strings			
persons whose first name is lexicographically smaller than their last name				
$\begin{tabular}{lllllllllllllllllllllllllllllllllll$	temporal interval logic			
persons whose fathers have studied before their mothers				
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Concrete Domain

$ hightarrow {f Definition 25.7} {\cal P}$ a set of predica	7.1 A concrete domain is a pa ites.	air $\langle \mathcal{C}, \mathcal{P} angle$, where \mathcal{C} is	a set and
\triangleright Example 25.7.	$2_{} \mathrel{\scriptstyle{\triangleright}} \mathcal{C} = \mathbb{N} \text{ and } \mathcal{P} = \{=, <,$	$\leq, >, \geq \}$ (natural	numbers)
$ hitarrow \mathcal{C} = \mathbb{R}$ and \mathcal{P}	$=\{=,<,\leq,>,\geq\}$	(real	numbers)
$ hinstriangle \mathcal{C} = temporal \ logic)$	intervals, $\mathcal{P} = \{\text{before, after}, $	overlaps,} (Allen	ı's interval
$\triangleright \mathcal{C} = facts in a$	relational data base, $\mathcal{P}=SG$	QL relations	
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 $\mathsf{Example:}\mathsf{car} \sqcap \mathsf{height} = 2 \sqcap \mathsf{width} = 1 \sqsubseteq \mathsf{car} \sqcap \mathsf{height} > \mathsf{width}$ $(x: \operatorname{car} \sqcap \operatorname{height} = 2 \sqcap \operatorname{width} = 1)$ $(x: \overline{\operatorname{car}} \sqcap \operatorname{width} \leq \operatorname{height})$ (x: car)(x: height = 2)(x: width = 1) $(x:\overline{car}) \mid (x:width \leq height)$ * xheight y_1 $y_1 = 2$ $(x: width = y_2)$ $y_2 = 1$ $(x: width y_3)$ $(x: height = y_4)$ $y_3 \leq y_4$ $y_1 \leq y_2$ * (C): Michael Kohlhase 295

25.8 Nominals

Semantics

 \triangleright Definition 25.8.8 $[[\{a_1, \ldots, a_n\}]]$ is the set of objects with names $a_1, \ldots a_n$.

 \triangleright **Definition 25.8.9** [R: a] is the set of objects that have [a] as R-successor

 $\llbracket \{a_1, \dots, a_n\} \rrbracket = \{\llbracket a_1 \rrbracket, \dots, \llbracket a_n \rrbracket \}$ $\llbracket \mathsf{R} \colon a \rrbracket = \{x \in \mathcal{D} \mid \langle x, \llbracket a \rrbracket \rangle \in \llbracket \mathsf{R} \rrbracket \}$

▷ Definition 25.8.10 (Negation Rules)

 $\overline{\{a_1, \dots, a_n\}} = \text{invariant}$ $\overline{\mathsf{R} \colon a} = \forall \mathsf{R} \cdot \overline{\{a\}}$

 $\succ Example 25.8.11 \text{ had _friend: } Eva \quad (the complement of the set of friends of Eva)$

 $= \forall had_friend.{Eva}$ (the set of objects that do not have Eva as a friend)

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Example Language with Nominals

- \triangleright We consider the following language: \mathcal{AL} + unqualified number restrictions $(\exists_{>}^{n}\mathsf{R}, \forall_{<}^{n}\mathsf{R})$, some role operators $(\sqcap, \circ, \cdot^{-1})$, $\{a_{1}, \ldots, a_{n}\}$, R : a
- ▷ Example 25.8.12 persons that have at most two friends among their neighbors and whose neighbors are Bill, Bob, or the gardener person $\Box \forall^2_<$ (has_friend \Box has_neighbor) $\Box \forall$ has_neighbor).

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 $\succ \textbf{Example 25.8.13} companies with at least 100 employees that have a car and live in Bremen company <math>\sqcap \exists_{\geq}^{100} has_empl \circ has_comp_car \sqcap has_empl \circ lives_in : Bremen

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Tableaux Calculus (only T-Box)

 \rhd Definition~25.8.14 The calculus consists of the $\mathcal{T}_{\mathcal{A\!C}}$ rules together with:

$$\frac{(a:\overline{\{\ldots,a,\ldots\}})}{*} \qquad \frac{\mathcal{B}}{(x:\{a_1,\ldots,a_n\})} \qquad \frac{(x:\mathbb{R}:a)}{x\mathbb{R}a}$$
$$\frac{x\mathbb{R}^{-1}y}{y\mathbb{R}x} \qquad \frac{x\mathbb{R}\sqcap Sy}{x\mathbb{R}y} \qquad \frac{x\mathbb{R}\circ Sy}{x\mathbb{R}y}$$
$$\frac{x\mathbb{R}\circ Sy}{xSy} \qquad zSy$$

 \rhd Theorem 25.8.15 The calculus is correct, complete, and terminating

 \rhd Proof Sketch: very technical but not terribly difficult using the techniques developed so far. $\hfill\square$

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