Artificial Intelligence 1 Winter Semester 2024/25 – Lecture Notes – Conclusion of Al-1

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21.1 What did we learn in AI 1?



Michael Kohlhase: Artificial Intelligence 1



Topics of AI-1 (Winter Semester)

- Getting Started
 - What is Artificial Intelligence?
 - Logic programming in Prolog
 - Intelligent Agents
- Problem Solving
 - Problem Solving and search
 - Adversarial search (Game playing)
 - constraint satisfaction problems
- Knowledge and Reasoning
 - Formal Logic as the mathematics of Meaning
 - Propositional logic and satisfiability
 - First-order logic and theorem proving
 - Logic programming
 - Description logics and semantic web
- Planning
 - Planning Frameworks
 - Planning Algorithms
 - Planning and Acting in the real world

(situating ourselves) (An influential paradigm) (a unifying framework)

(Black Box World States and Actions) (A nice application of search) (Factored World States)

> (Atomic Propositions) (Quantification) (Logic + Search~ Programming)





Agents interact with the environment





General agent schema





Simple Reflex Agents



Reflex Agents with State



► Goal-Based Agents



Utility-Based Agent



Learning Agents





Idea: Try to design agents that are successful (do the right thing)

Definition 1.1. An agent is called rational, if it chooses whichever action maximizes the expected value of the performance measure given the percept sequence to date. This is called the MEU principle.

Note: A rational agent need not be perfect

- only needs to maximize expected value (rational ≠ omniscient)
 need not predict e.g. very unlikely but catastrophic events in the future
 percepts may not supply all relevant information (Rational ≠ clairvoyant)
 if we cannot perceive things we do not need to react to them.
 but we may need to try to find out about hidden dangers (exploration)
 action outcomes may not be as expected (rational ≠ successful)
 but we may need to take action to ensure that they do (more often) (learning)
- ▶ Rational ~→ exploration, learning, autonomy

Problem Solving

(Black Box States, Transitions, Heuristics)

- Framework: Problem Solving and Search
- Variant: Game playing (Adversarial search)

(basic tree/graph walking) (minimax + $\alpha\beta$ -Pruning)



Problem Solving (Black Box States, Transitions, Heuristics)
 Framework: Problem Solving and Search (basic tree/graph walking)
 Variant: Game playing (Adversarial search) (minimax + αβ-Pruning)
 Constraint Satisfaction Problems (heuristic search over partial assignments)
 States as partial variable assignments, transitions as assignment
 Heuristics informed by current restrictions, constraint graph
 Inference as constraint propagation (transferring possible values across arcs)

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 Describing world states by formal la 	nguage (and drawing inferences)
 Propositional logic and DPLL First-order logic and ATP Digression: Logic programming Description logics as moderately exp 	(deciding entailment efficiently) (reasoning about infinite domains) (logic + search) ressive, but decidable logics



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Planning: Problem Solving using white-box world/action descriptions		
Framework: describing world states in logic as sets of propositions and actions by preconditions and add/delete lists		

Algorithms: e.g heuristic search by problem relaxations

Topics of AI-2 (Summer Semester)

Uncertain Knowledge and Reasoning

- Uncertainty
- Probabilistic reasoning
- Making Decisions in Episodic Environments
- Problem Solving in Sequential Environments
- Foundations of machine learning
 - Learning from Observations
 - Knowledge in Learning
 - Statistical Learning Methods

Communication

- Natural Language Processing
- Natural Language for Communication

(If there is time)



References I

