Artificial Intelligence 1 Winter Semester 2024/25

Lecture Notes –Conclusion of AI-1

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This document contains the conclusions of the course "Artificial Intelligence 1" held at FAU Erlangen-Nürnberg in the Winter Semesters 2016/17 ff. Other parts of the lecture notes can be found at http://kwarc.info/teaching/AI/notes-*.pdf.

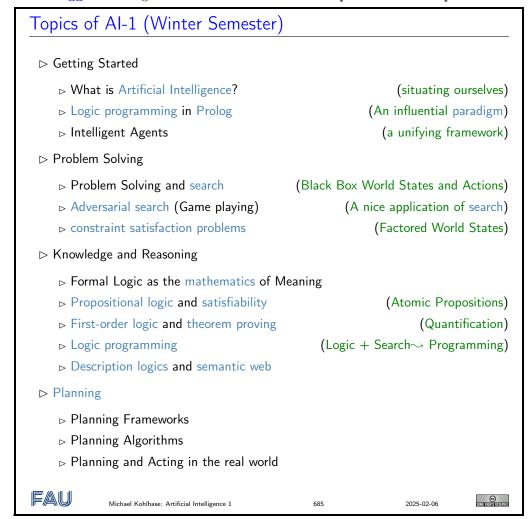
Contents

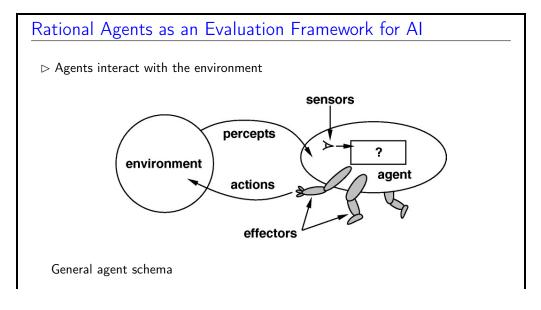
21.1	What die	d we	learn i	n A	I 1?																													4
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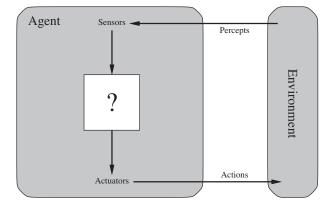
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21.1 What did we learn in AI 1?

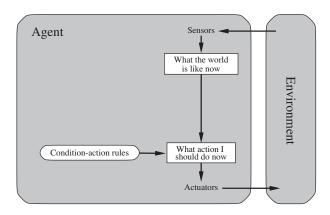
A Video Nugget covering this section can be found at https://fau.tv/clip/id/26916.



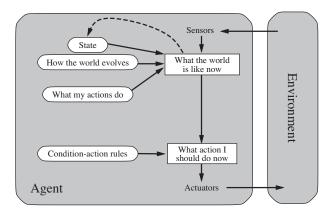




Simple Reflex Agents

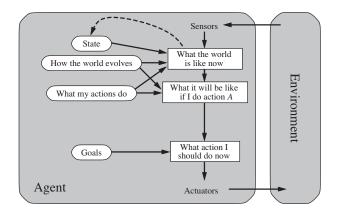


Reflex Agents with State

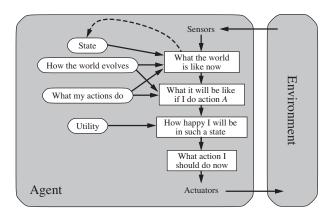


Goal-Based Agents

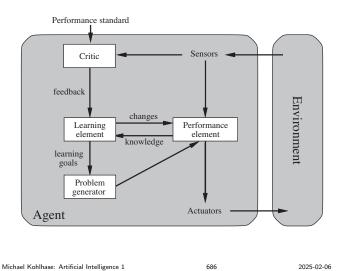
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Utility-Based Agent



Learning Agents



Rational Agent

FAU

ightharpoonup Idea: Try to design agents that are successful

(do the right thing)

- ▶ Definition 21.1.1. An agent is called rational, if it chooses whichever action maximizes the expected value of the performance measure given the percept sequence to date. This is called the MEU principle.
- Note: A rational agent need not be perfect
 - \triangleright only needs to maximize expected value (rational \neq omniscient)
 - ⊳ need not predict e.g. very unlikely but catastrophic events in the future
 - □ percepts may not supply all relevant information (Rational ≠ clairvoyant)
 - ⊳ if we cannot perceive things we do not need to react to them.
 - but we may need to try to find out about hidden dangers (exploration)
 - \triangleright action outcomes may not be as expected (rational \neq successful)
 - but we may need to take action to ensure that they do (more often) (learning)
- ▷ Rational ~→ exploration, learning, autonomy



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Symbolic AI: Adding Knowledge to Algorithms

▷ Problem Solving

(Black Box States, Transitions, Heuristics)

▶ Framework: Problem Solving and Search

(basic tree/graph walking)

(minimax + $\alpha\beta$ -Pruning)

> Constraint Satisfaction Problems

(heuristic search over partial assignments)

- > States as partial variable assignments, transitions as assignment
- ⊳ Inference as constraint propagation (transferring possible values across arcs)
- Describing world states by formal language

(and drawing inferences)

▶ Propositional logic and DPLL

(deciding entailment efficiently)

⊳ First-order logic and ATP

(reasoning about infinite domains)

▶ Digression: Logic programming

(logic + search)

- Description logics as moderately expressive, but decidable logics
- ▶ Planning: Problem Solving using white-box world/action descriptions
 - ▶ Framework: describing world states in logic as sets of propositions and actions by preconditions and add/delete lists
 - ⊳ Algorithms: e.g heuristic search by problem relaxations



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Topics of Al-2 (Summer Semester)

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- - ▶ Uncertainty
 - ▶ Probabilistic reasoning

 - ⊳ Problem Solving in Sequential Environments
- - $\, \, \triangleright \, \, \mathsf{Knowledge} \, \, \mathsf{in} \, \, \mathsf{Learning} \, \,$
- ightharpoonup Communication

(If there is time)

- ▶ Natural Language Processing
- Natural Language for Communication



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